



1. Invent Yourself

Martin Marek



Problem definition

“Truly random numbers are a very valuable and rare resource. Design, produce, and test a mechanical device for producing random numbers. Analyse to what extent the randomness produced is safe against **tampering.**”



MECHANICAL DEVICE DEFINITION

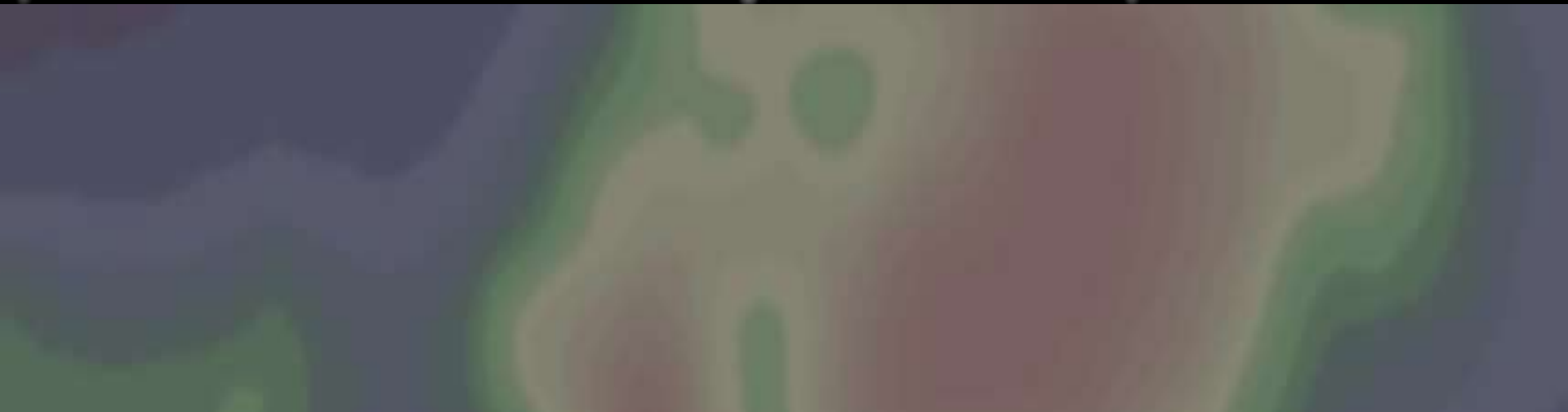
Atmospheric noise

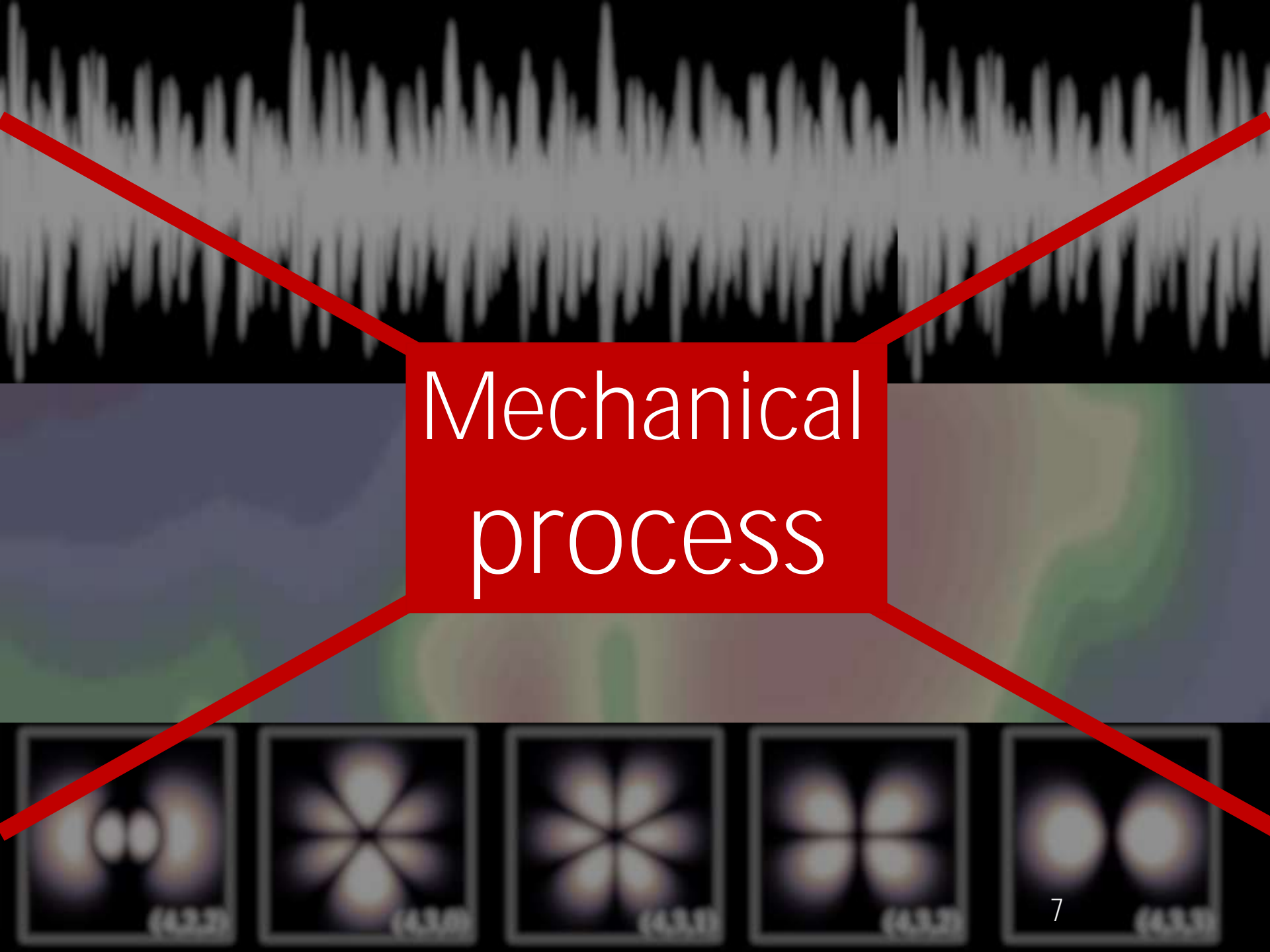




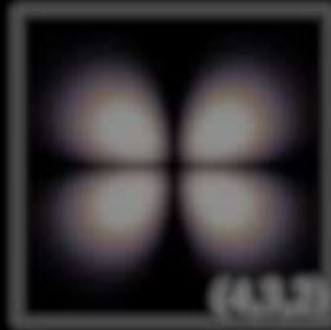
Thermal noise



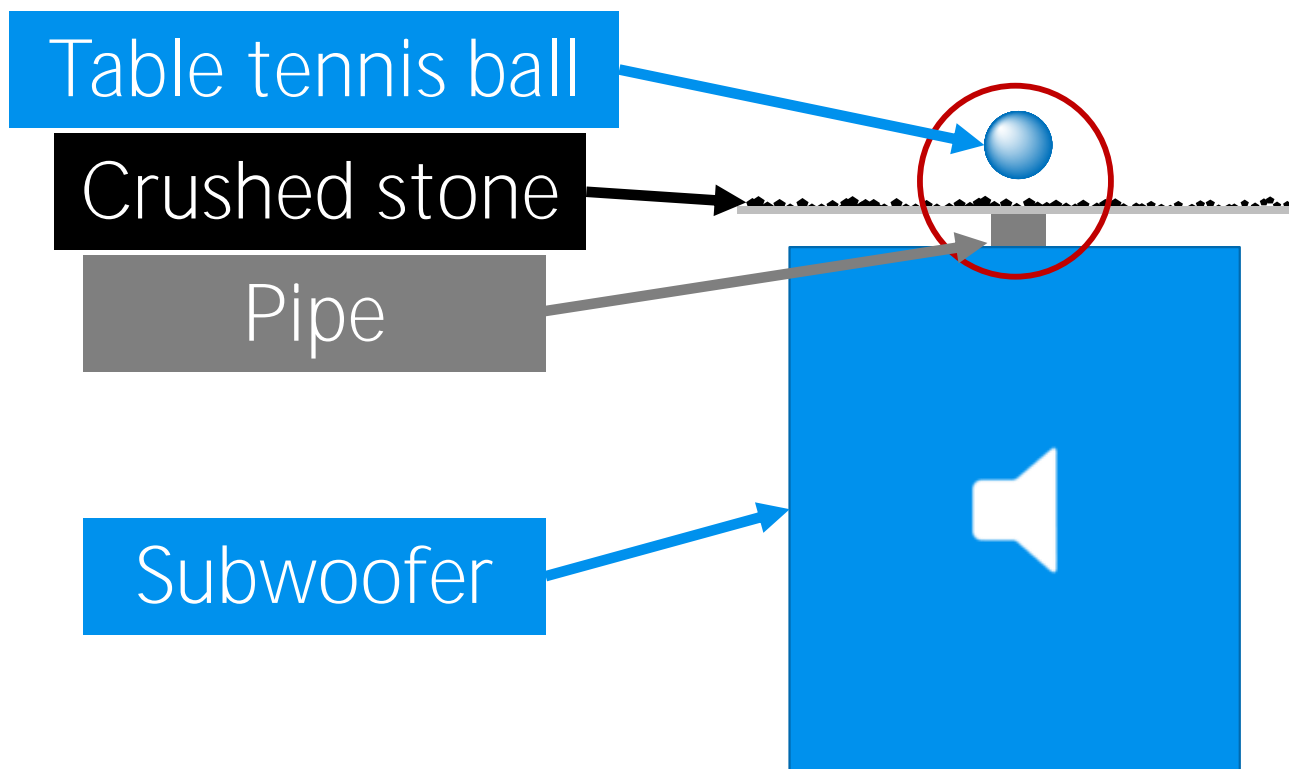


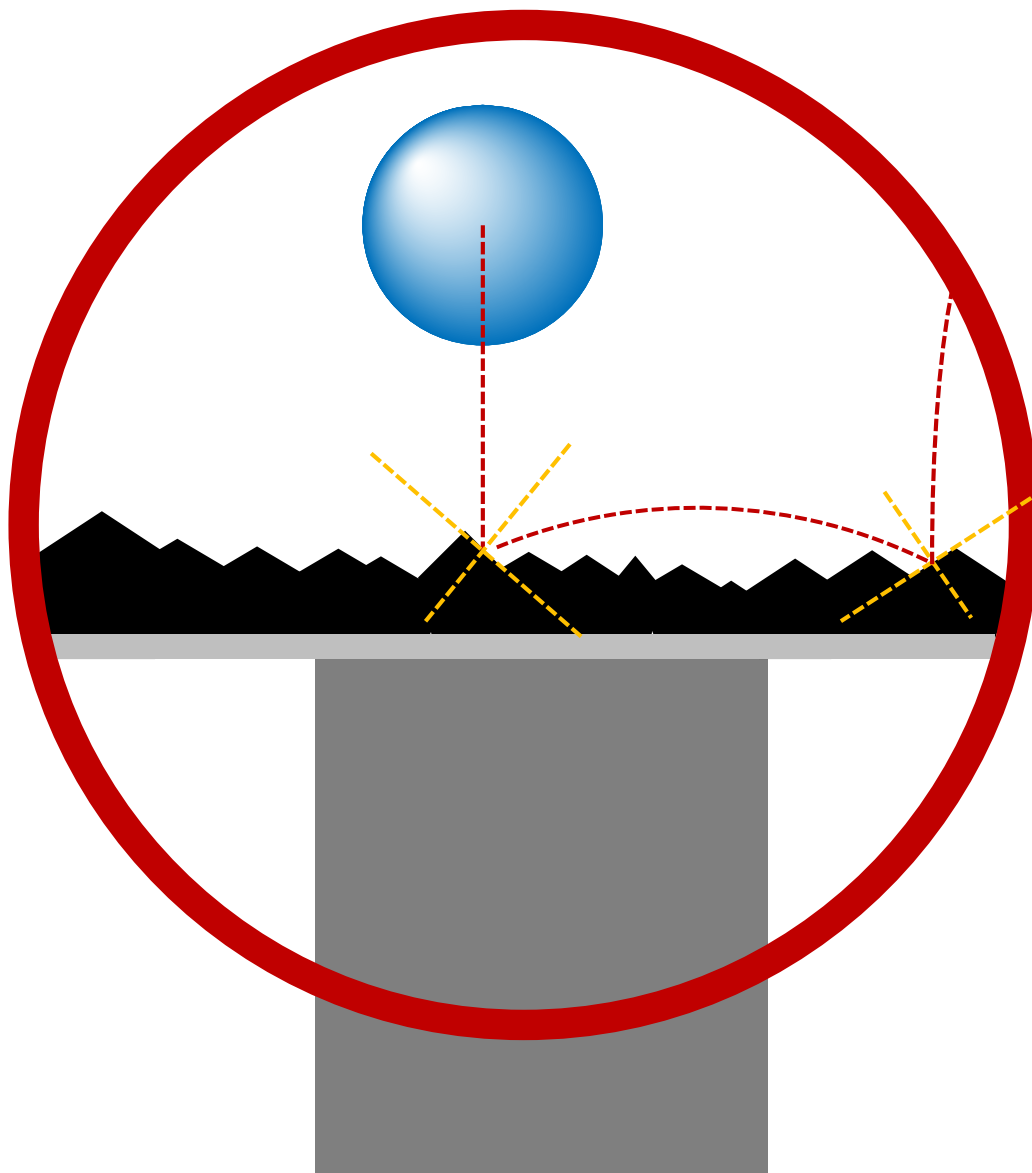


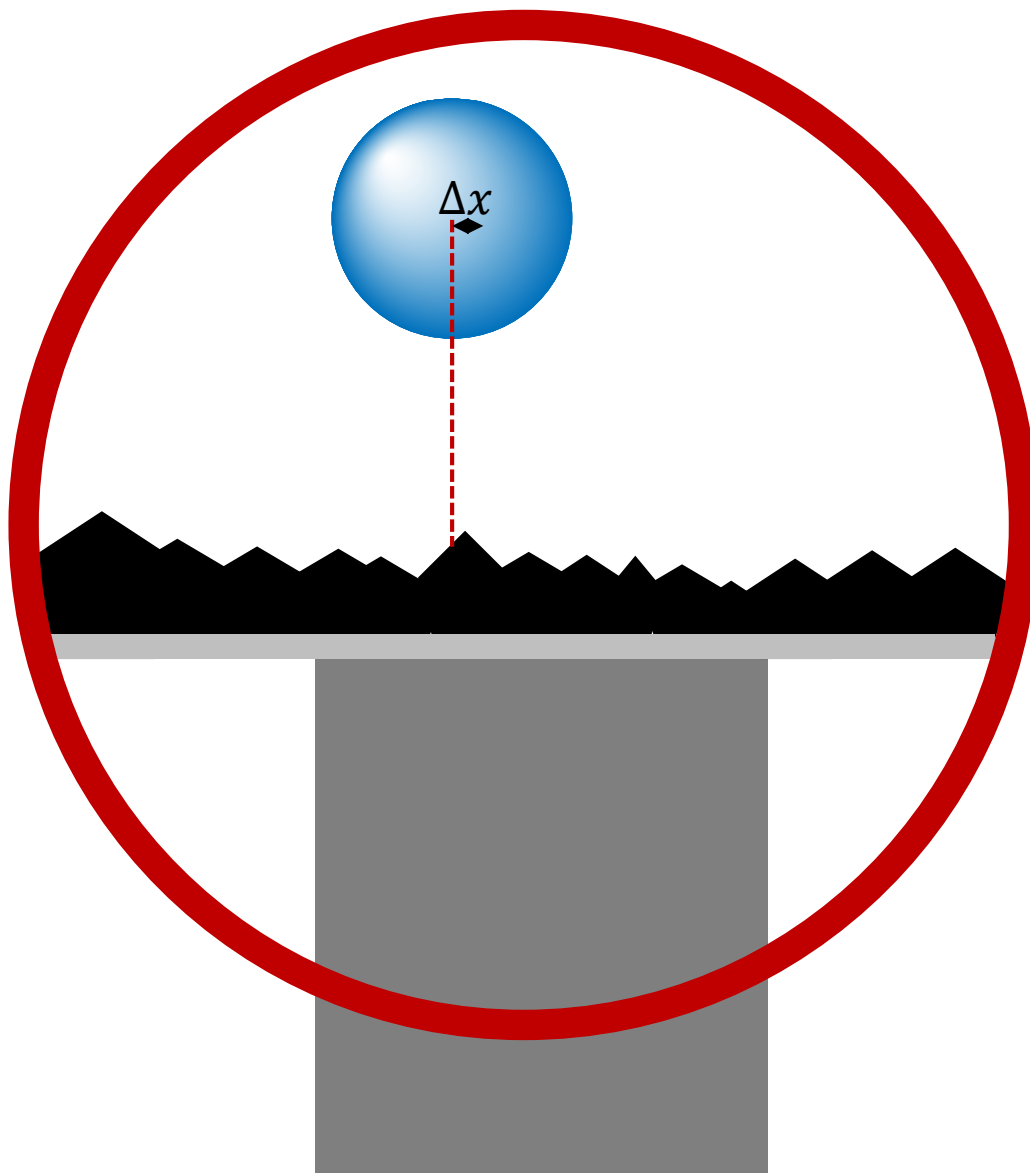
Mechanical process

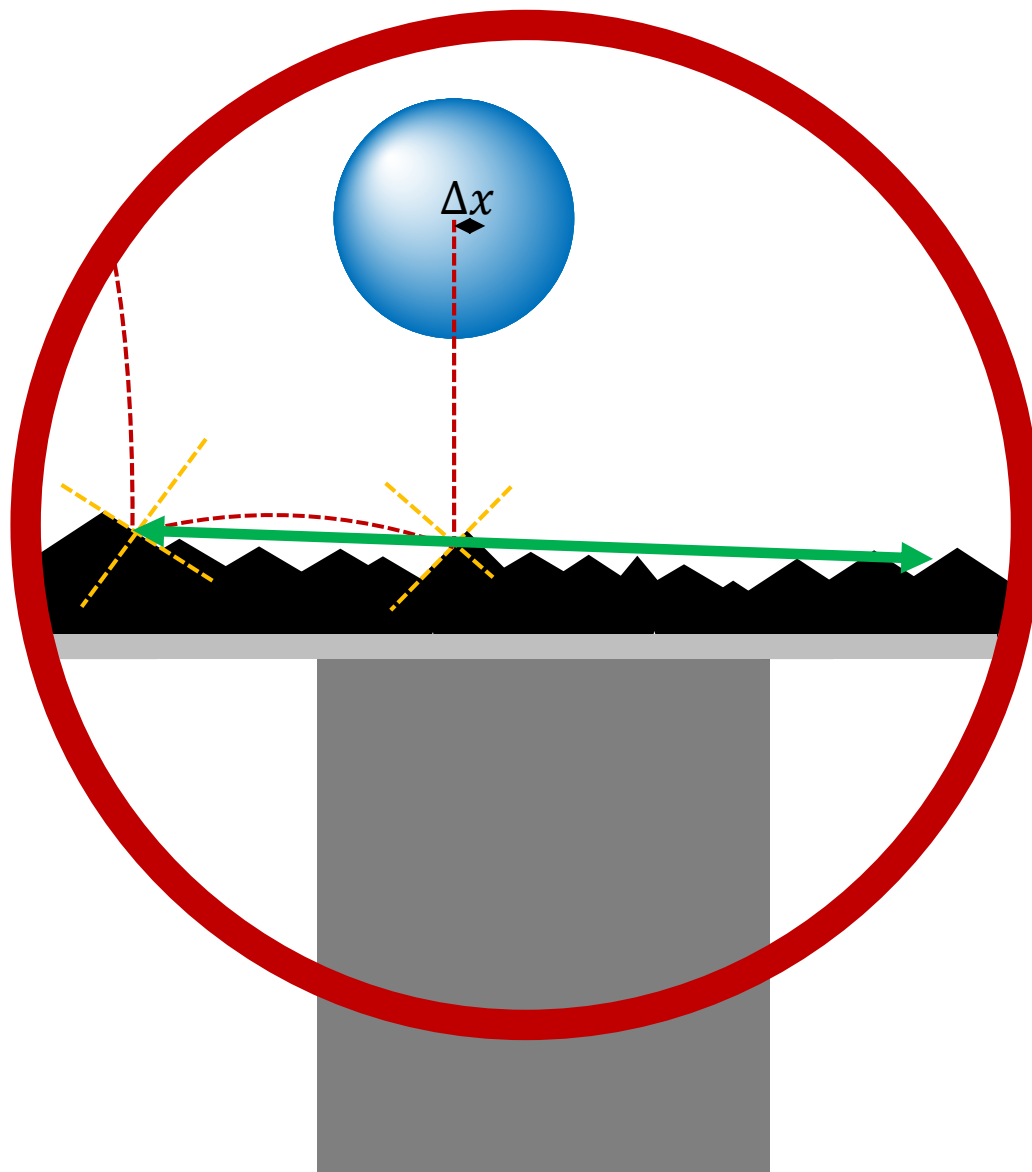


Chaotic Mechanical System





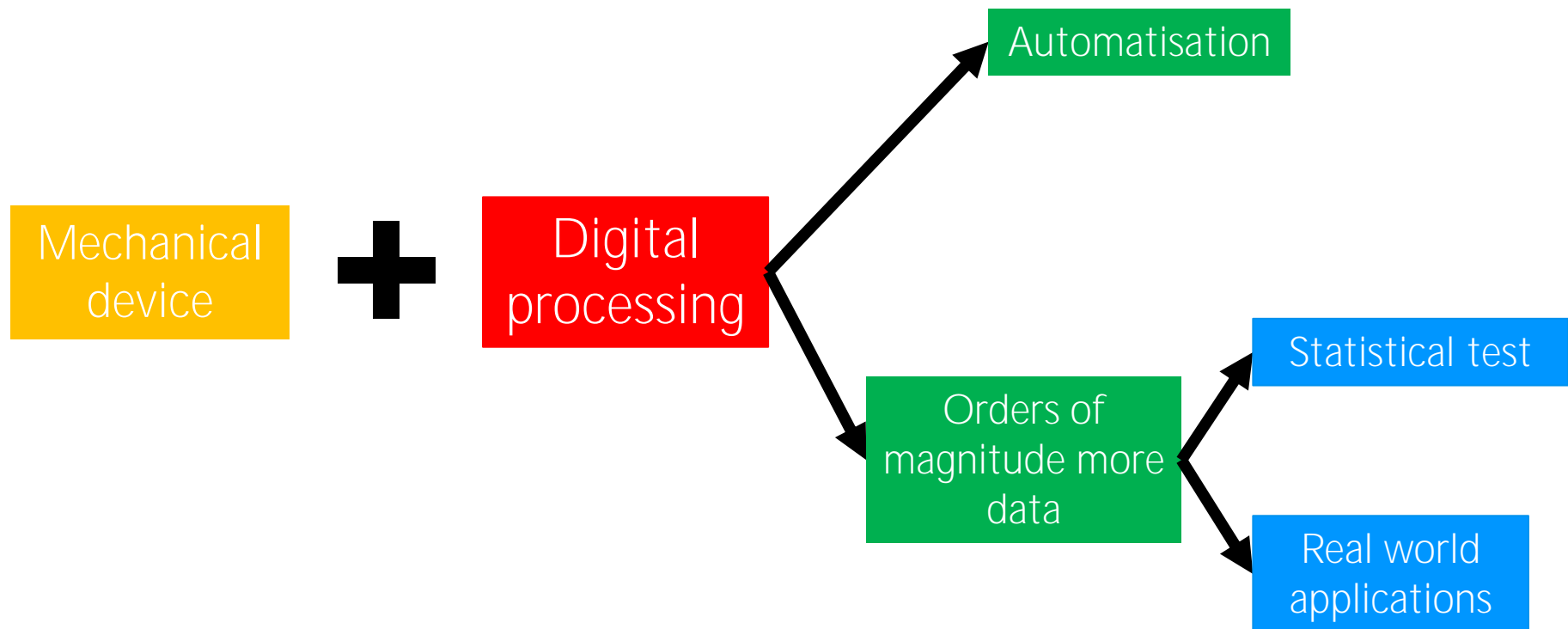




Chaotic
system



Digital processing





Camera

Subwoofer

Exemplary video





POSSIBLE WAYS OF GENERATING AN OUTPUT

Position

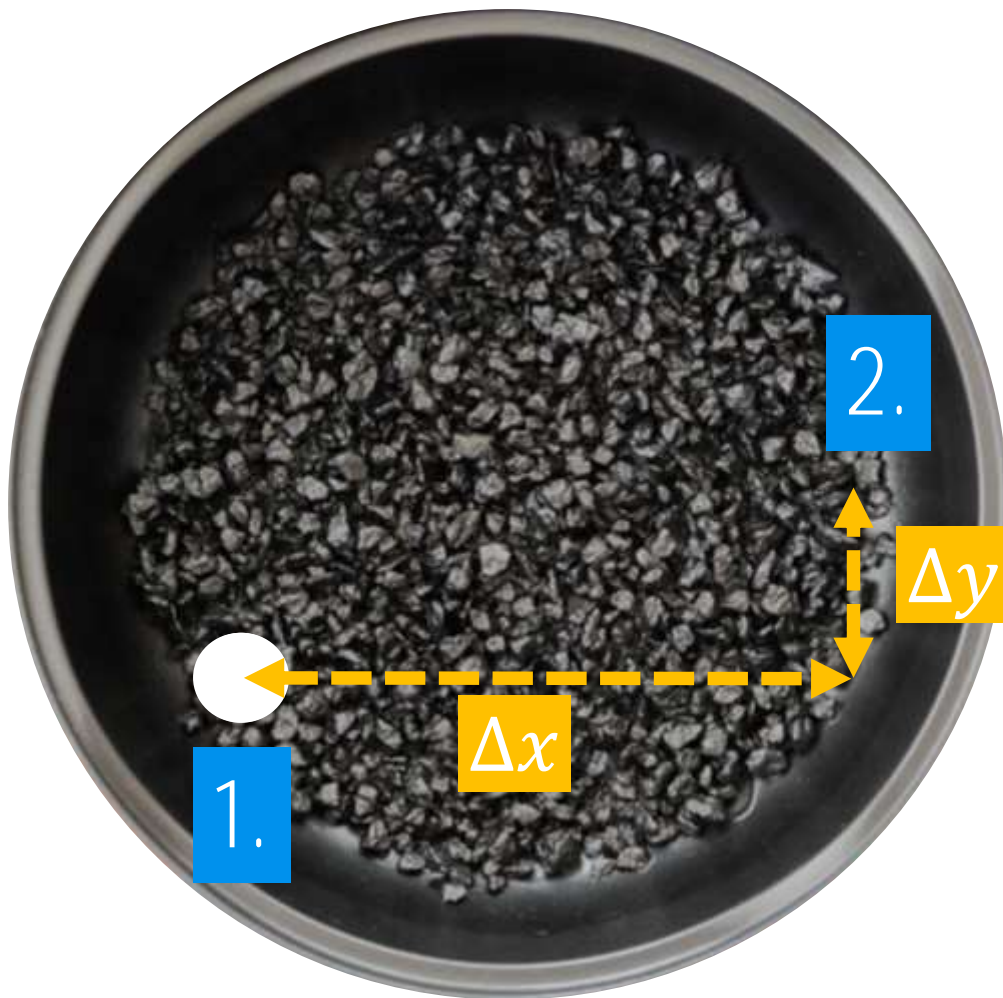


Position



~~x, y~~

Distance



$$\Delta x \Delta y \leq 2r^2$$

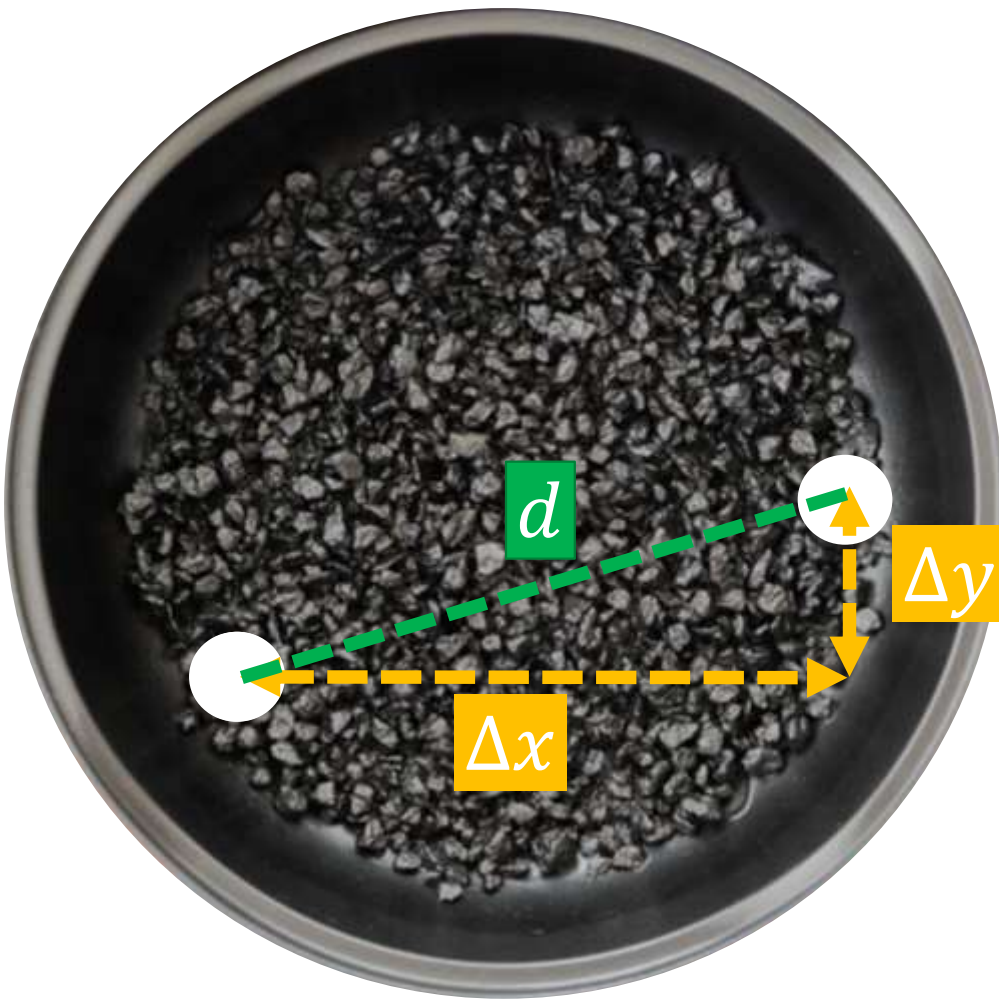


Correlated



Data needs
to be
combined

Distance

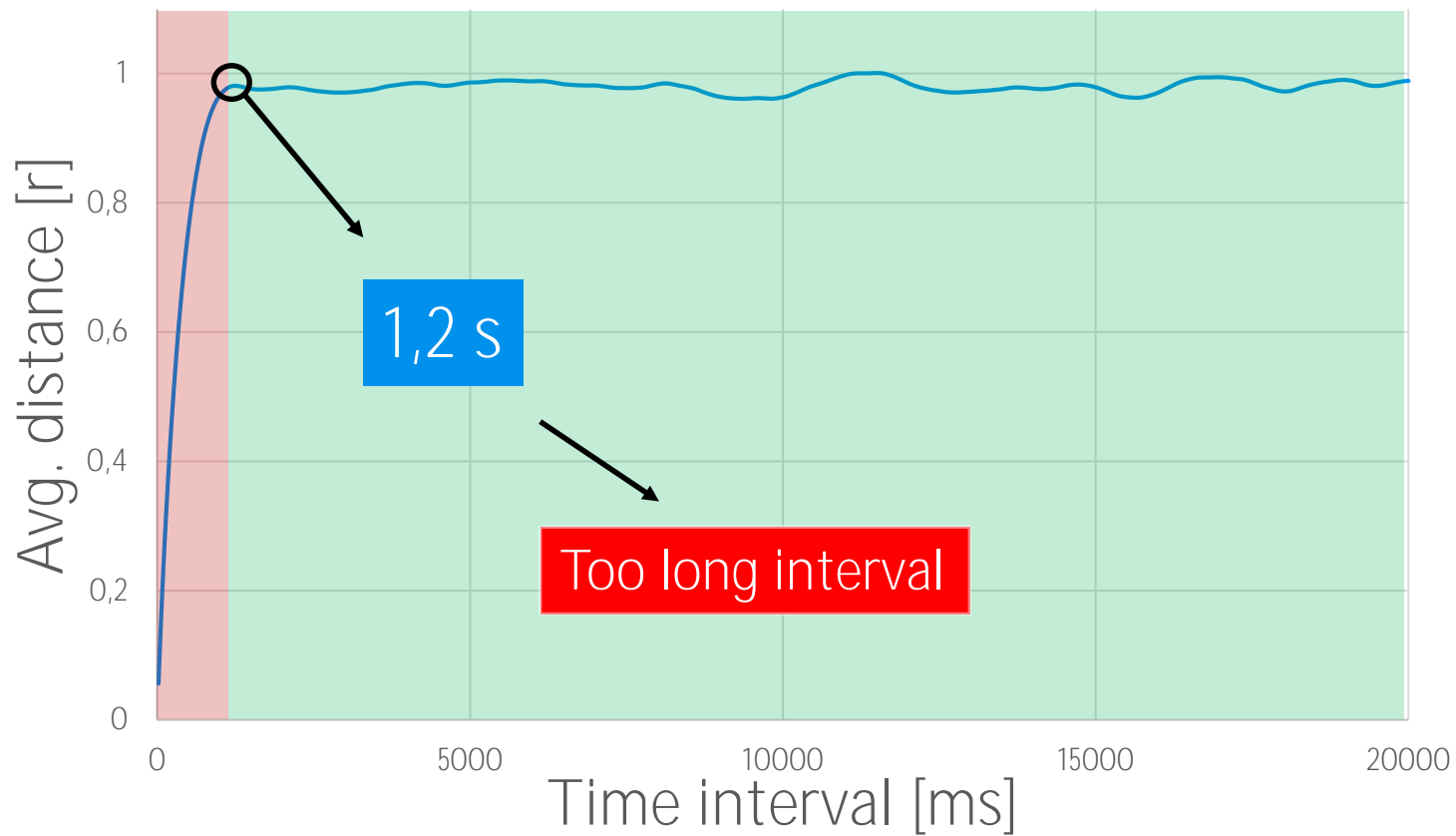


$$d = \sqrt{\Delta x^2 + \Delta y^2}$$



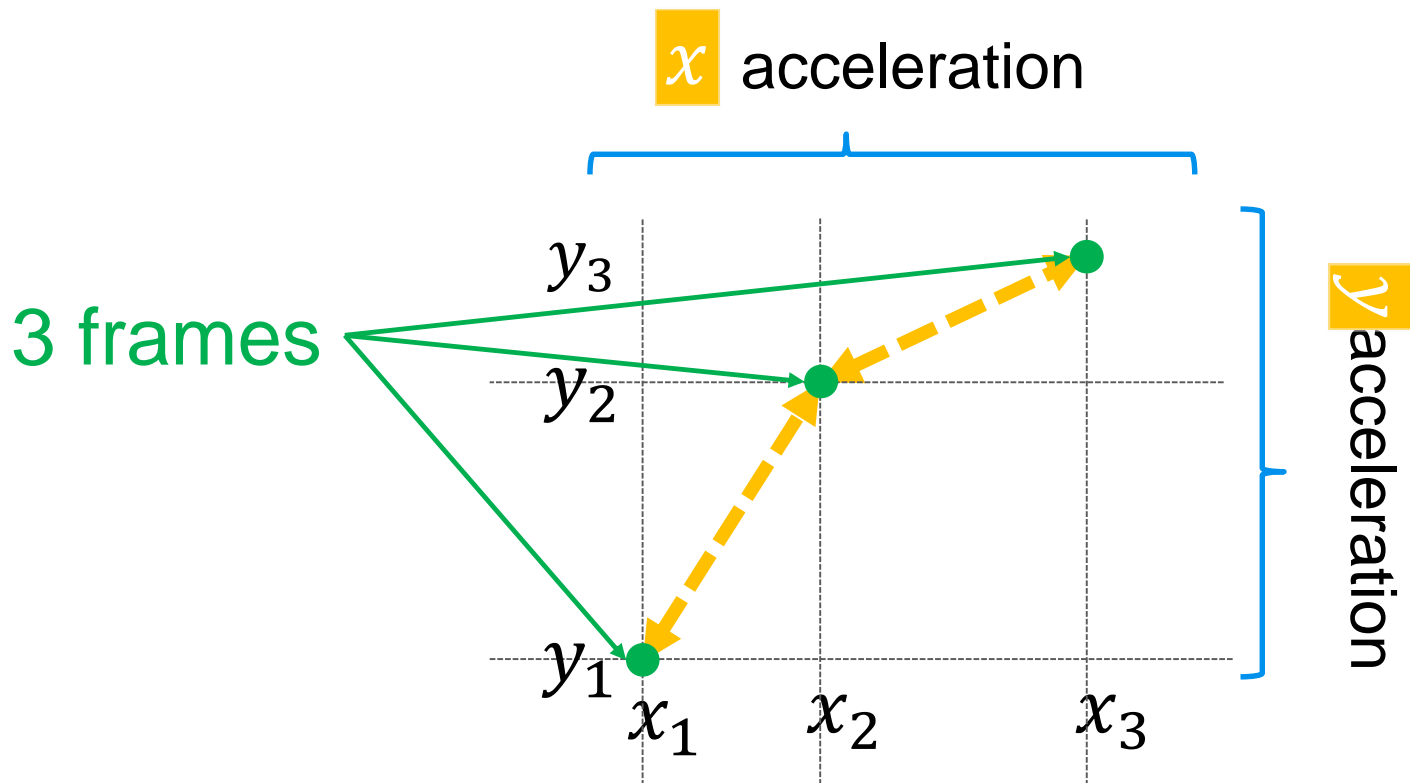
Correct time interval
is required

Distance Correlation time

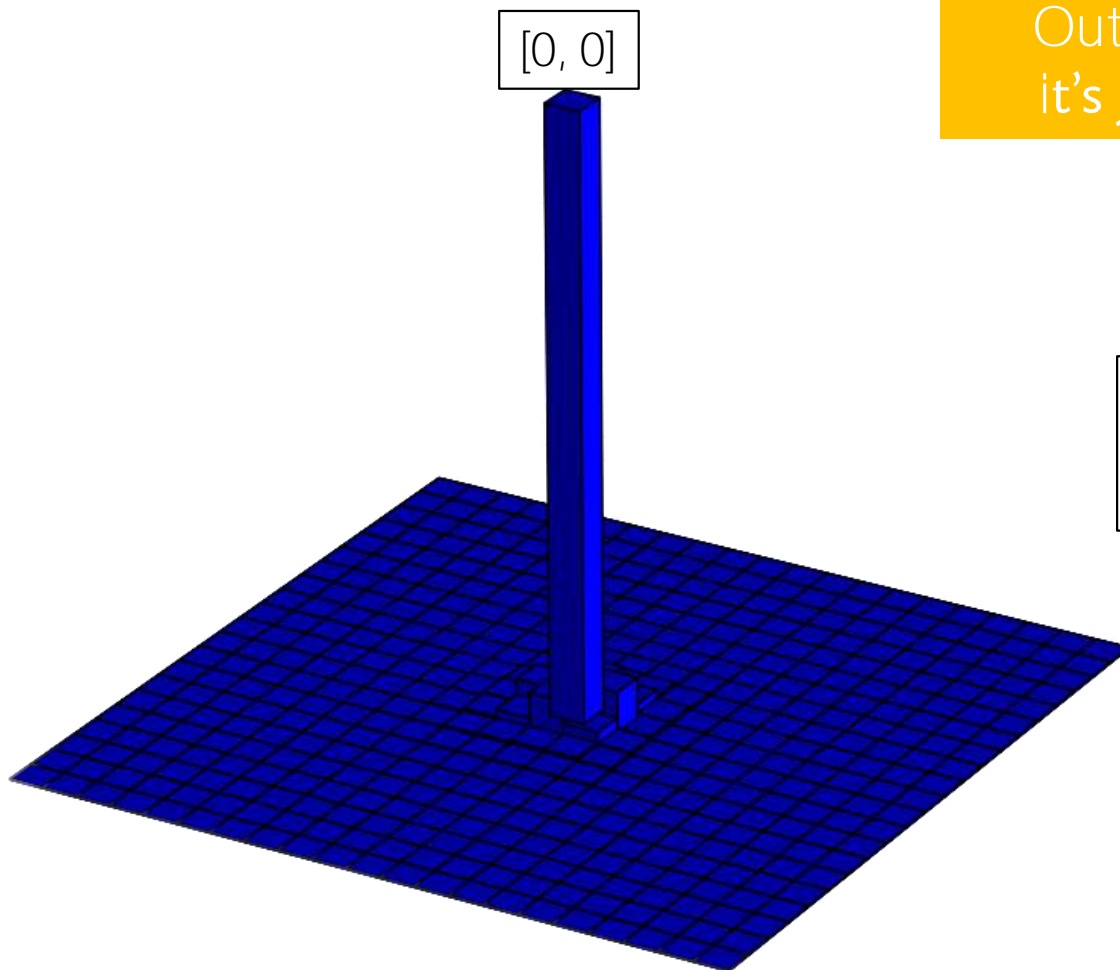


Generating Numbers from

Acceleration



Acceleration Histogram



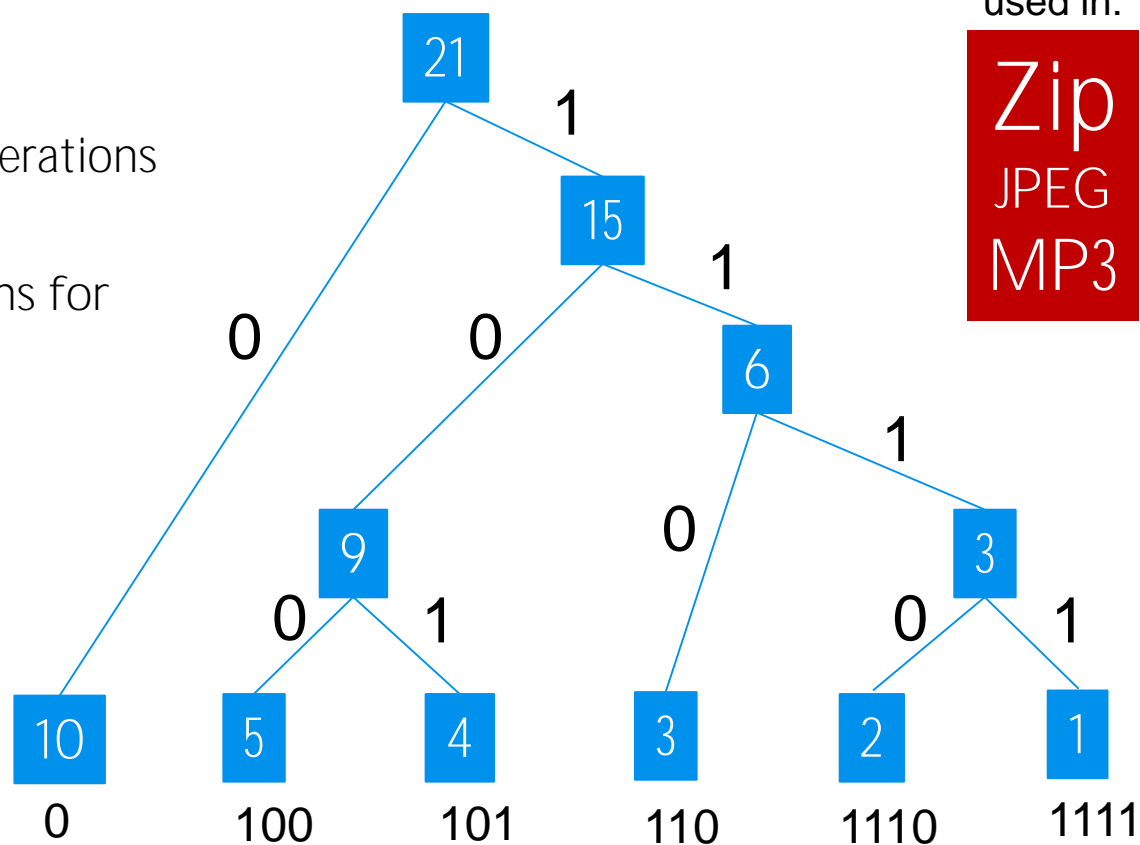
Output IS random...
it's just not uniform

We need
proper binary coding



Compression: Huffman coding

- Separate for x and y accelerations
- Codes pairs of accelerations for optimum efficiency





Compression: $L > H$

Entropy

$$H = 1.754$$

$$L = 1.762$$

Avg. length

99.55% efficiency

Imperfect coding

Problems:

Contains
patterns

Biased

Perfect coding: $H = L$



XOR: Extractor of randomness

How it works:

```
x data:  1 0 1 0 1 1 1 0 0 0 0 1 1 0 1 0 ...
y data:  1 0 0 1 1 1 1 1 1 0 0 1 0 0 1 1 ...
-----
output:  0 0 1 1 0 0 0 1 1 0 0 0 1 0 1 1 ...
```



Elimination
of any patterns



1/2 size reduction

Problems:

~~Contains
patterns~~

Biased



Neumann's Debiasing Algorithm

How it works:

1 1 1 0 1 1 1 0 0 1 0 1 1 1 1 1 0 0 0 0 1 1 1 0 1 0 1 0 ...
1 1 0 0 1 1 1 ...

Problems:

~~Contains
patterns~~

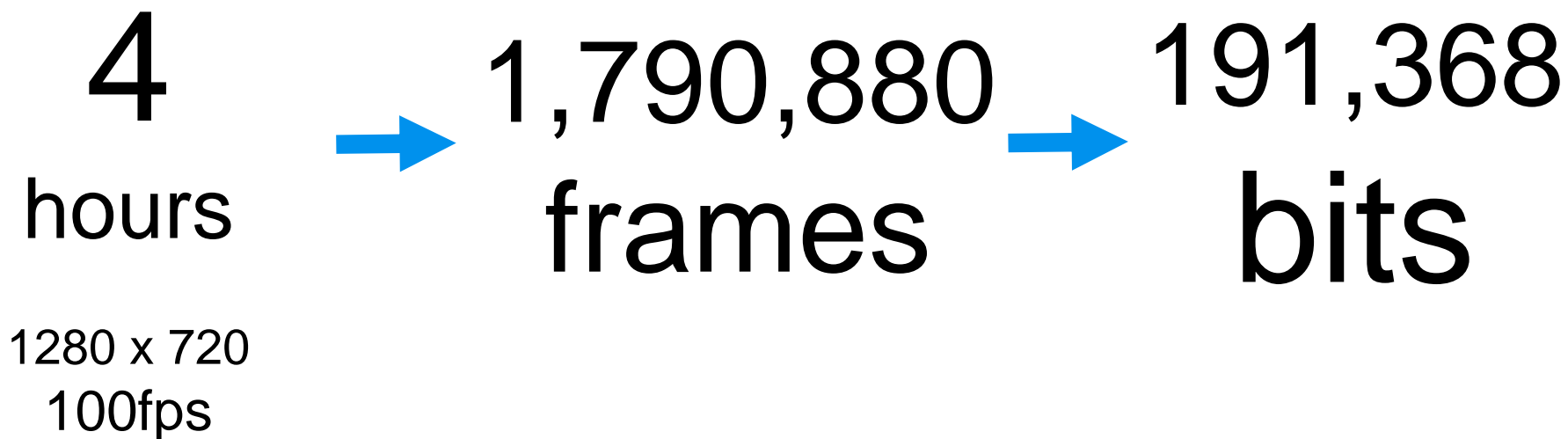
~~Biased~~

More balanced bits

$\frac{3}{4}$ size reduction



Produced Output





STATISTICAL TESTS

Our Generator vs. **RANDOM.ORG**



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RANDOM.ORG

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Google Custom Search

Search

True Random Number Service

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Random Integer Generator

This form allows you to generate random integers. The randomness comes from atmospheric noise, which for many purposes is better than the pseudo-random number algorithms typically used in computer programs.

Part 1: The Integers

Generate random integers (maximum 10,000).

Each integer should have a value between and (both inclusive; limits $\pm 1,000,000,000$).

Format in column(s).

Part 2: Go!

Be patient! It may take a little while to generate your numbers...

Note: The numbers generated with this form will be picked independently of each other (like rolls of a die) and may therefore contain duplicates. There is also the [Sequence Generator](#), which generates randomized sequences (like raffle tickets drawn from a hat) and where each number can only occur once.

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[Like](#) [Share](#) 405K

[G+](#) 19k

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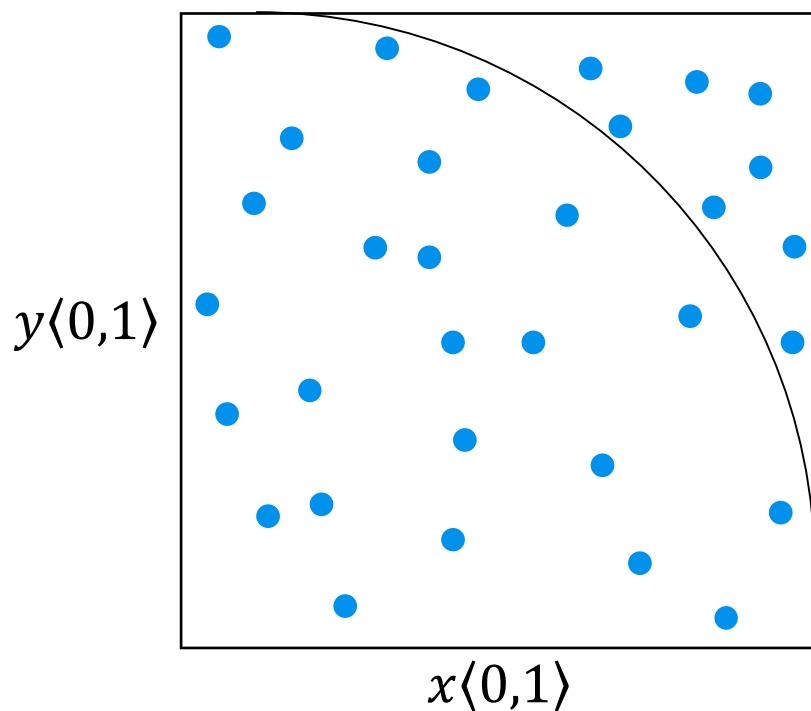
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Largest *TRNG*
on the internet

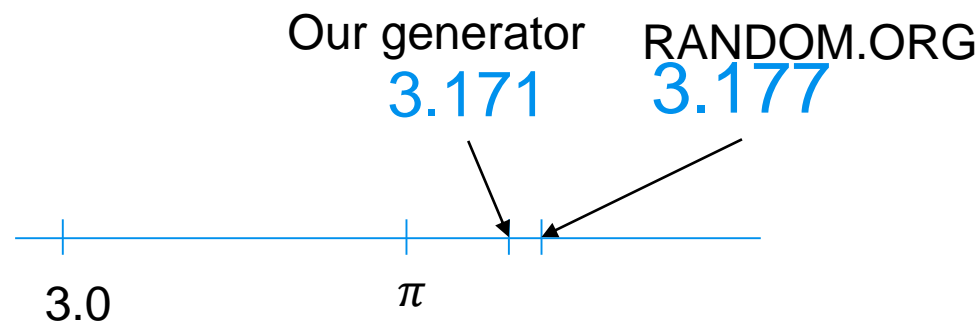


Atmospheric noise

Monte Carlo Computation: π



$$x^2 + y^2 \leq 1$$



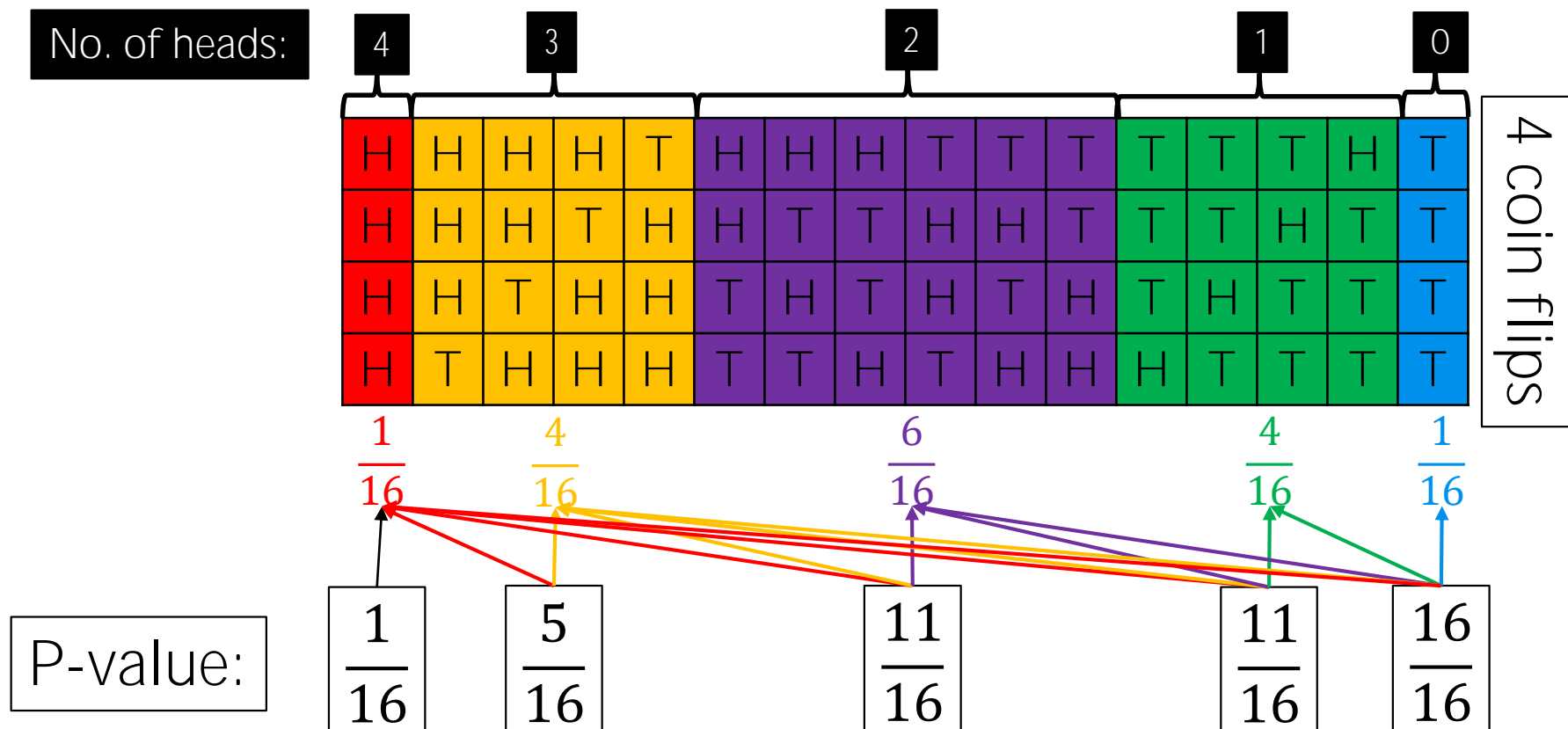


DIEHARDER

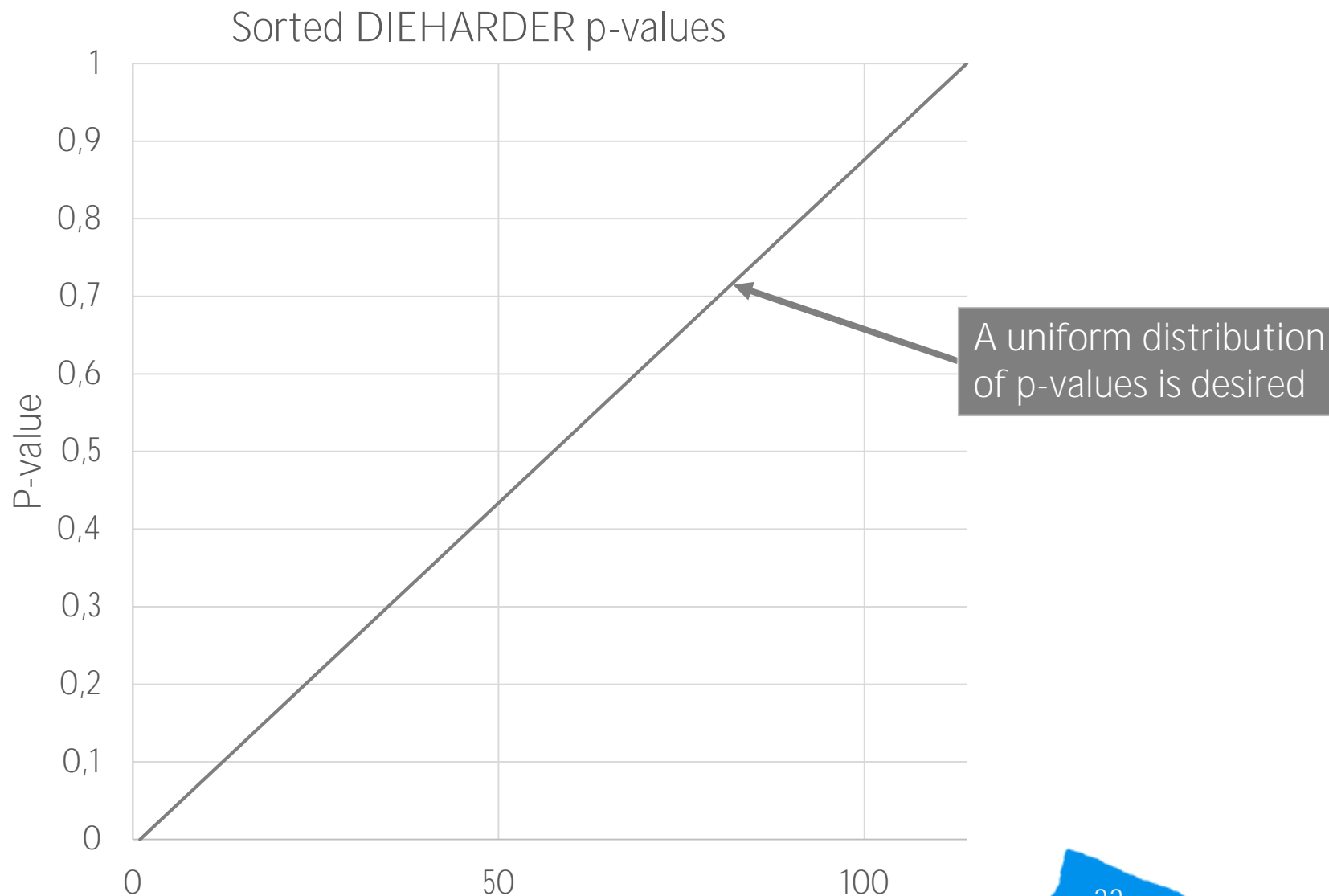
- Better parameterized (and expanded) DIEHARD tests
- Battery of 114 statistical test on RNG
- Output of each test: p-values based on the assumption of a perfect TRNG



What are p-values? – Example: No. of Heads

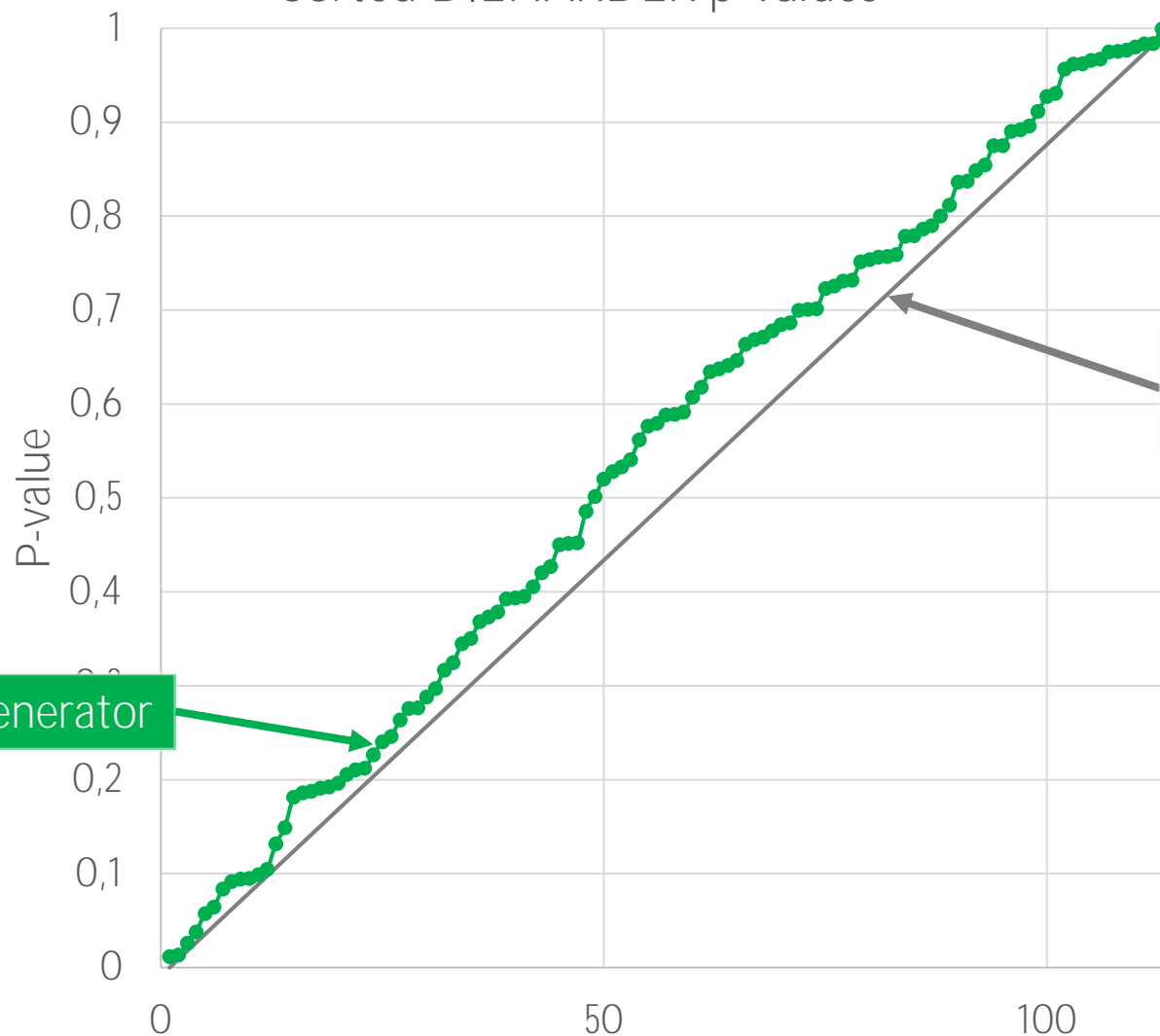


DIEHARDER: p-value Distribution



DIEHARDER: p-value Distribution

Sorted DIEHARDER p-values

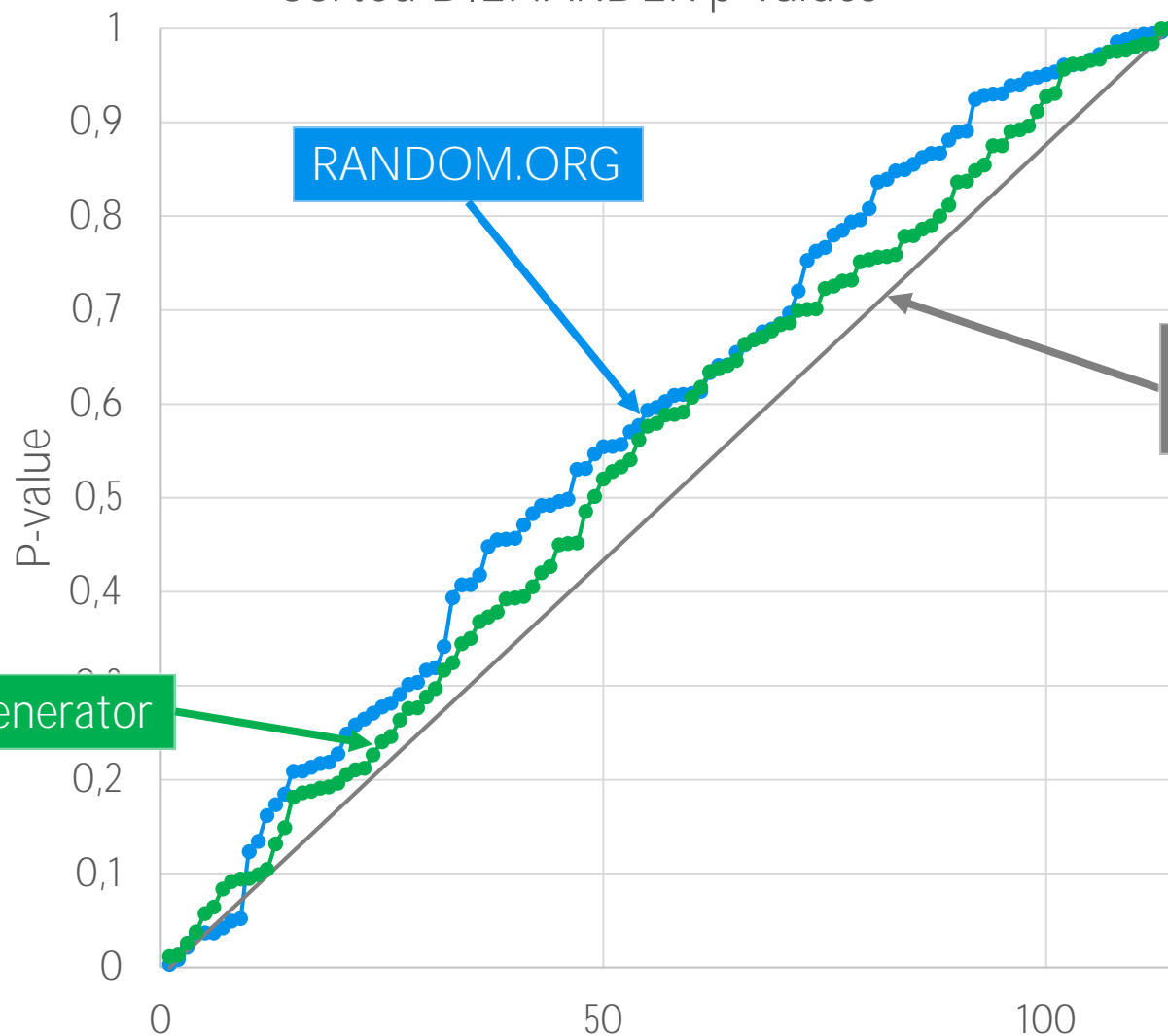


Our generator

A uniform distribution of p-values is desired

DIEHARDER: p -value Distribution

Sorted DIEHARDER p -values



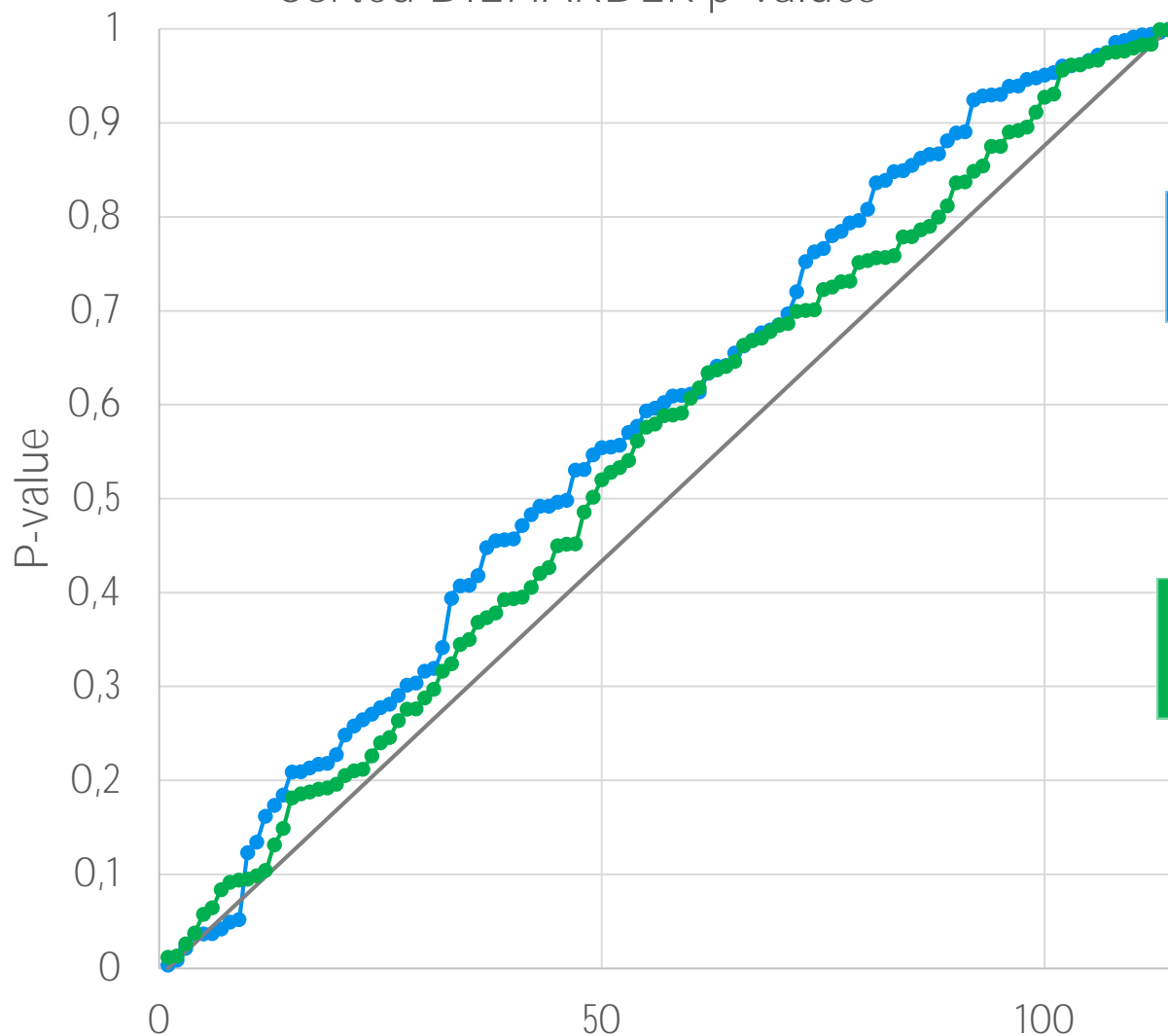
Our generator

RANDOM.ORG

A uniform distribution
of p -values is desired

DIEHARDER: p-value Distribution

Sorted DIEHARDER p-values



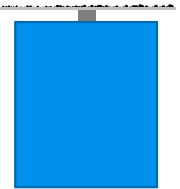
RANDOM.ORG's
mean difference: 0.0807

Our generator's
mean difference: 0.0474

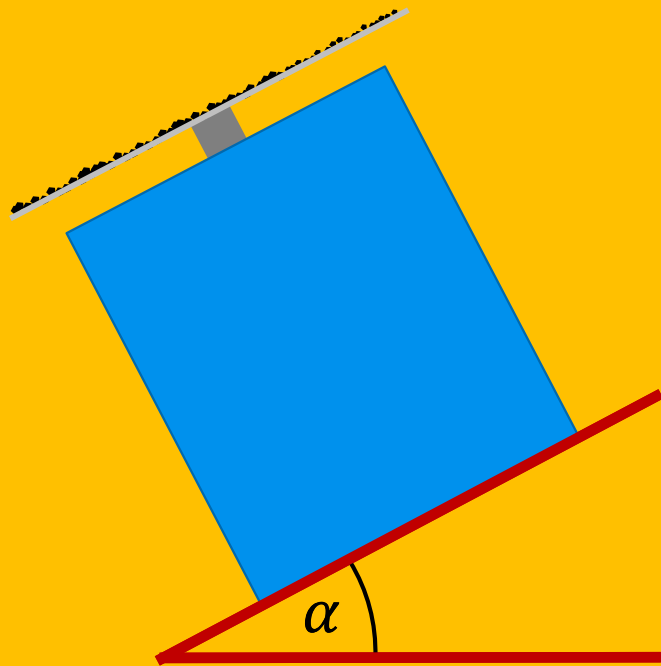


Problem definition

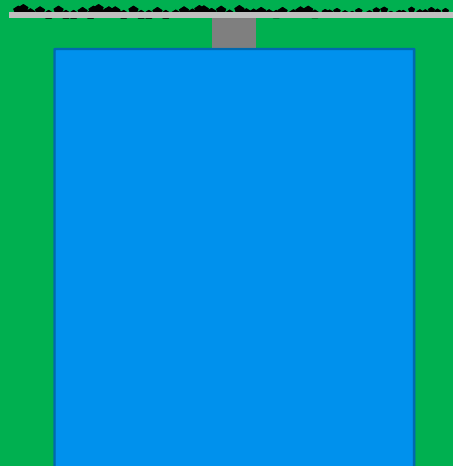
“Truly random numbers are a very valuable and rare resource. Design, produce, and test a mechanical device for producing random numbers. Analyse to what extent the randomness produced is safe against tampering.” ✓



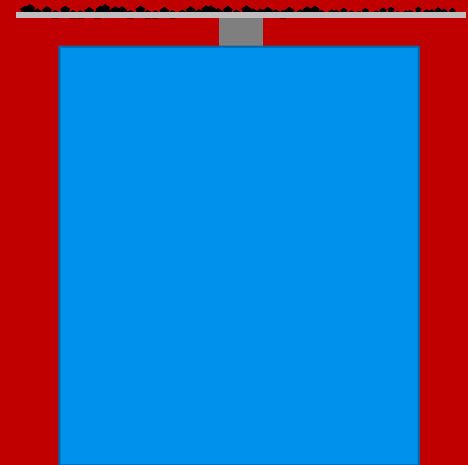
Angle



Amplitude



Frequency



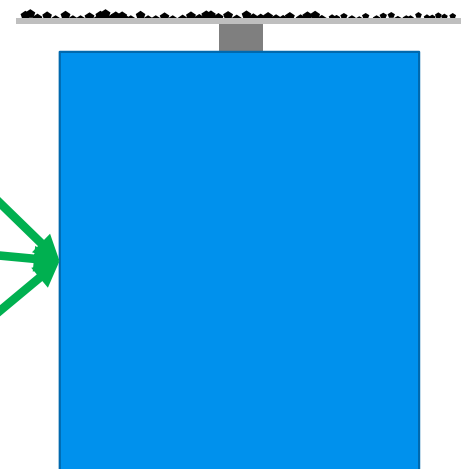
How we test against tampering

1. Created universal coding

$$f = 20\text{Hz}$$

$$\text{Amp.} = 0.12 \text{ (AU)}$$

$$\text{Tilt} = 0^\circ$$





How we test against tampering

1. Created universal coding

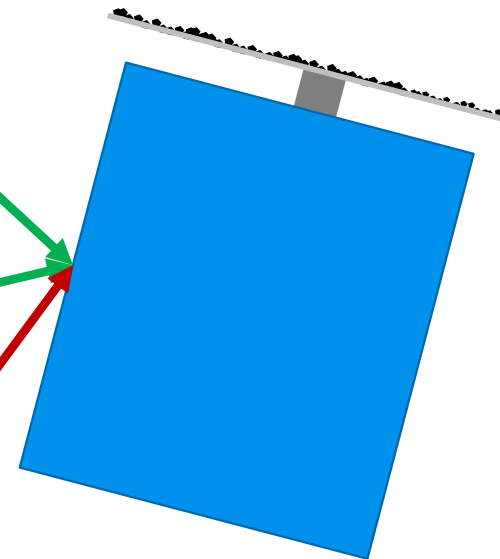
$f = 20\text{Hz}$

Amp. = 0.12 (AU)

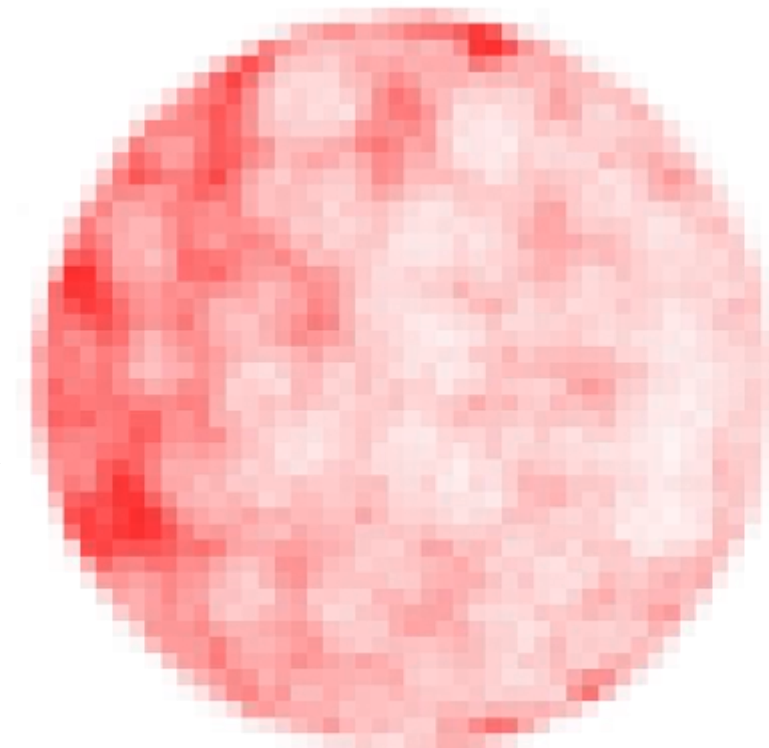
2. Changed parameters

Tilt = 15°

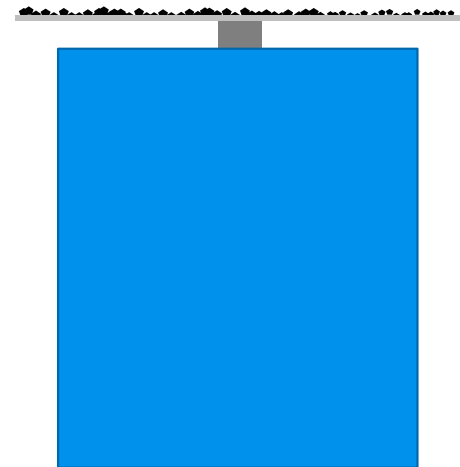
3. Test for randomness



Normal settings: heat map

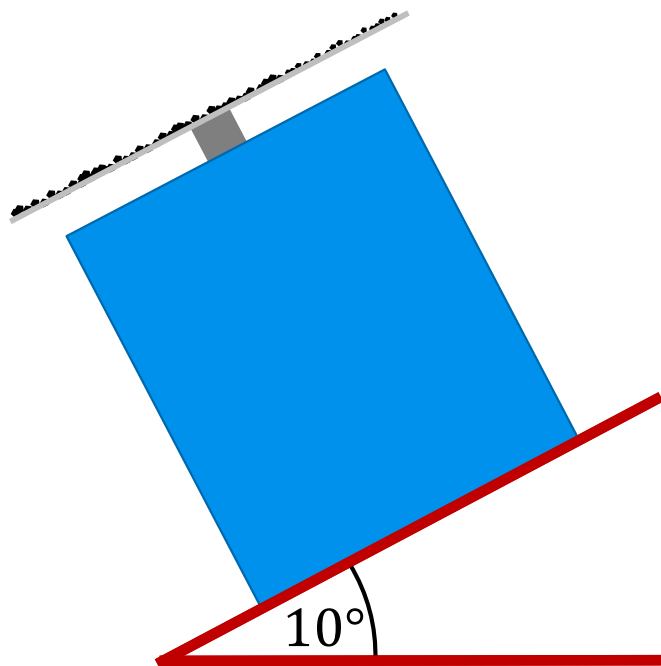


Near-uniform
distribution



15° tilt

Heat map:



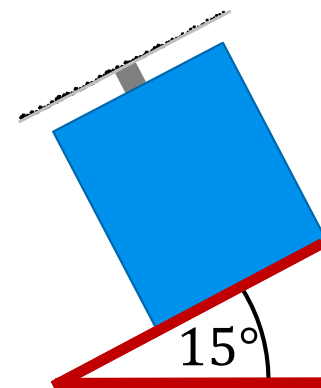
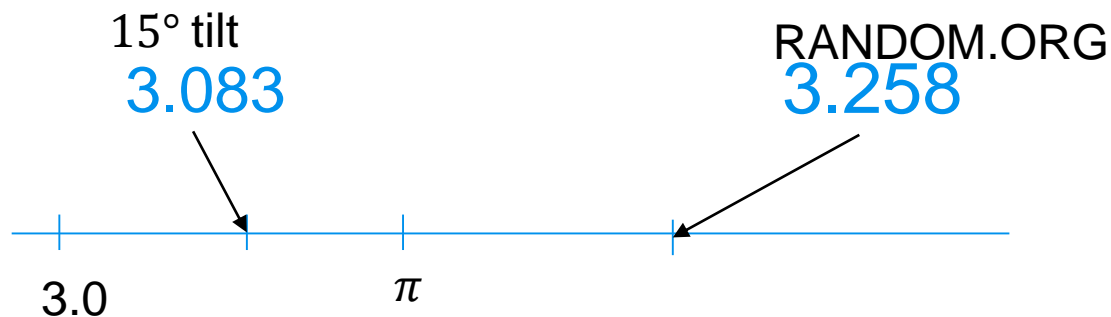


Tilt can easily be observed

Bud how good is the data anyway?

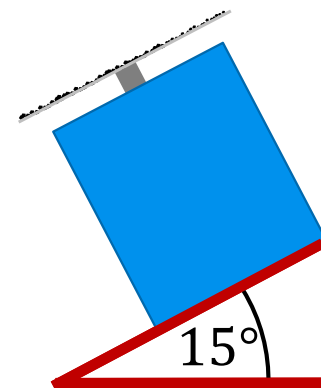
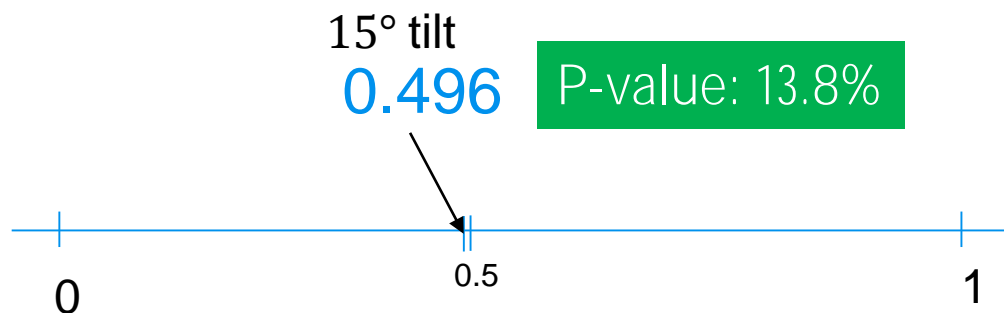
15° tilt: output quality

Monte Carlo: π



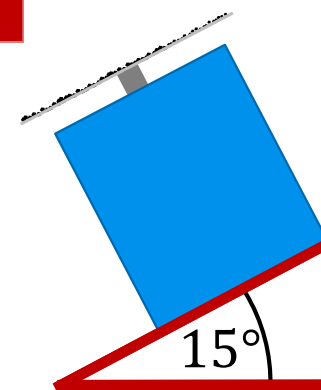
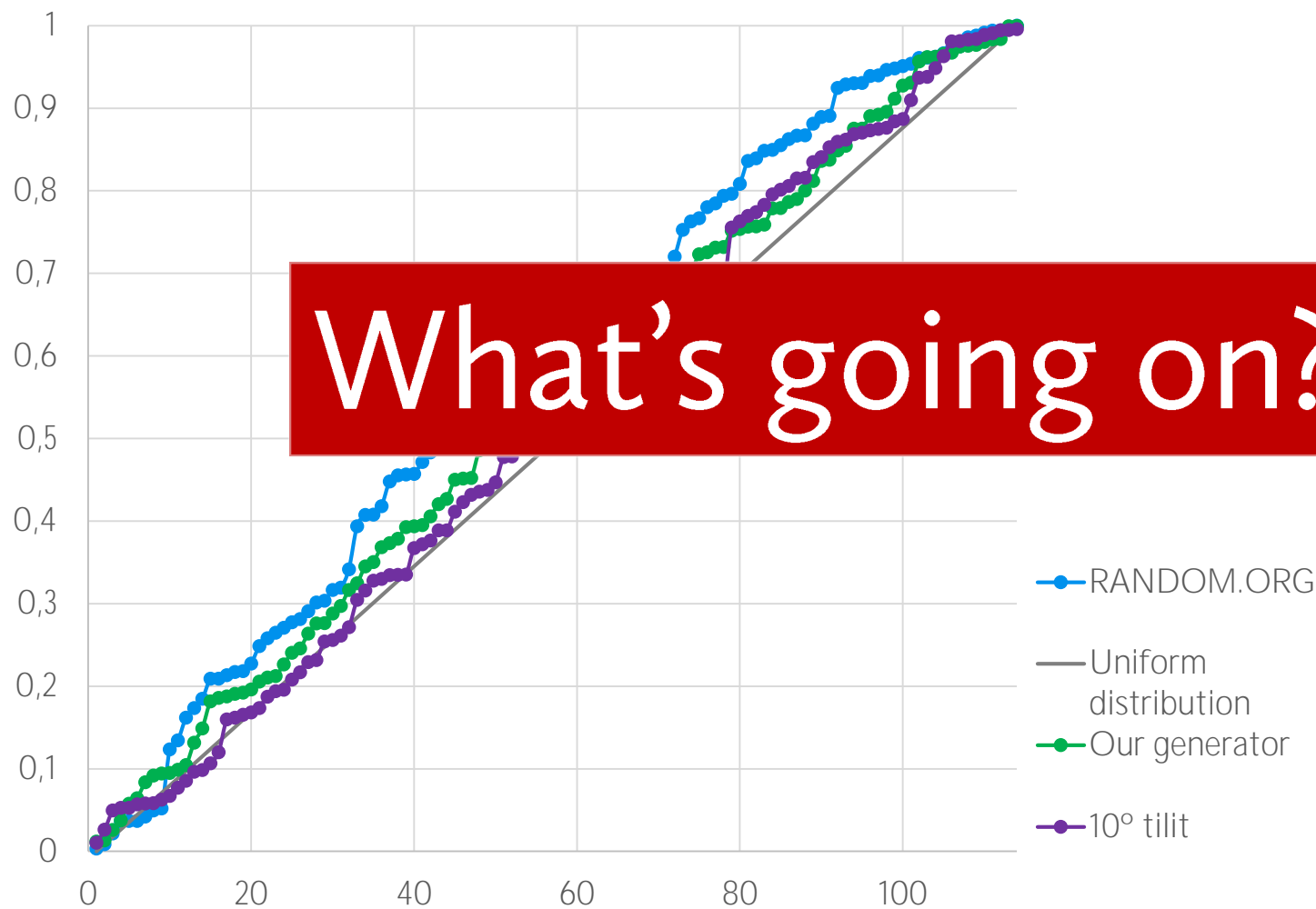
15° tilt: output quality

Avg. bit value



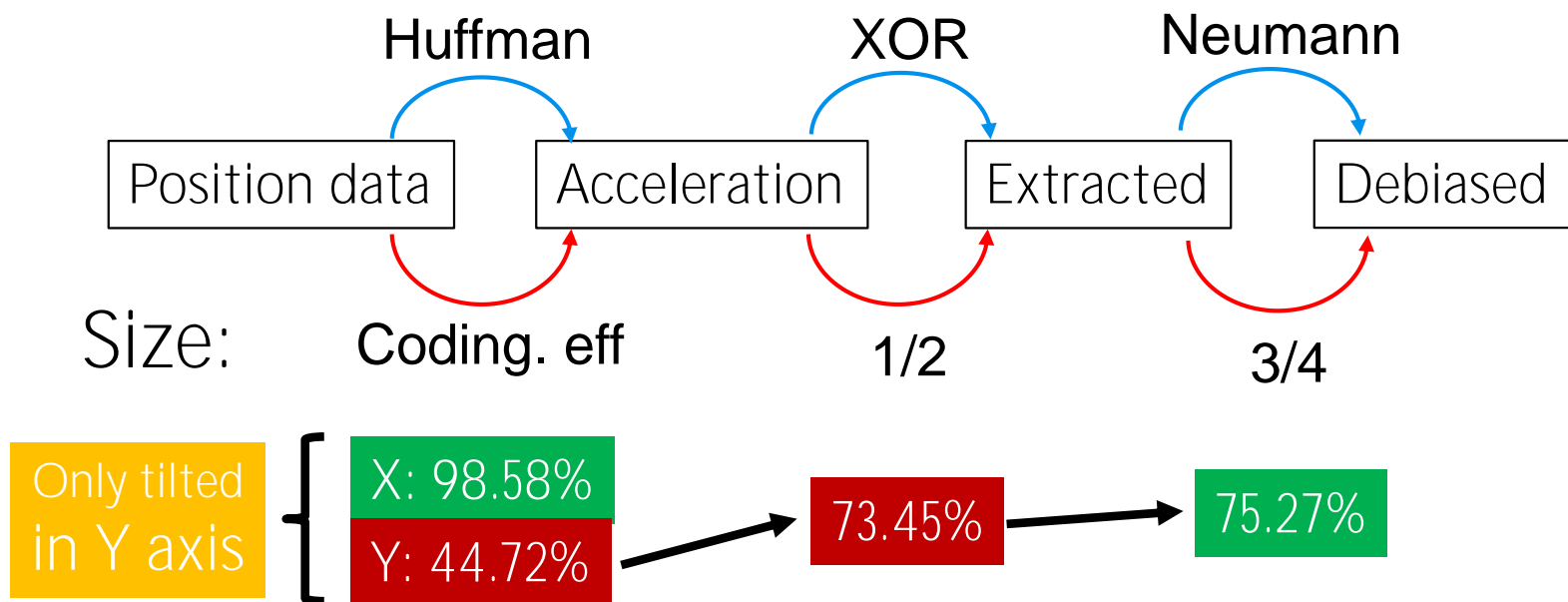
15° tilt: output quality

DIEHARDER





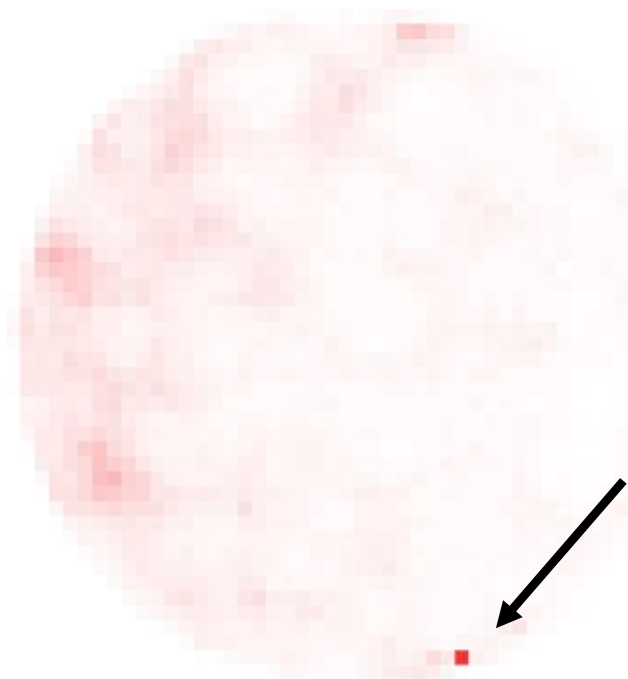
15° tilt: output size



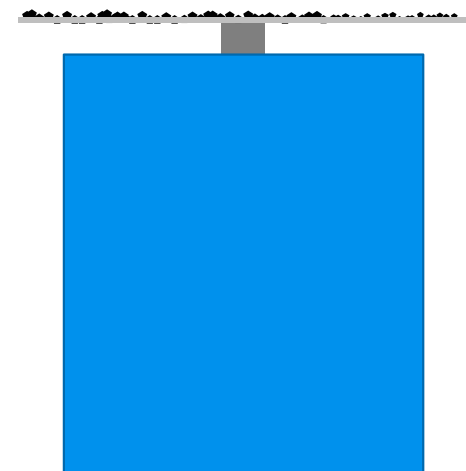
Difference between X and Y length
means throwing away excess data

10% lower Amp.

Heat map:

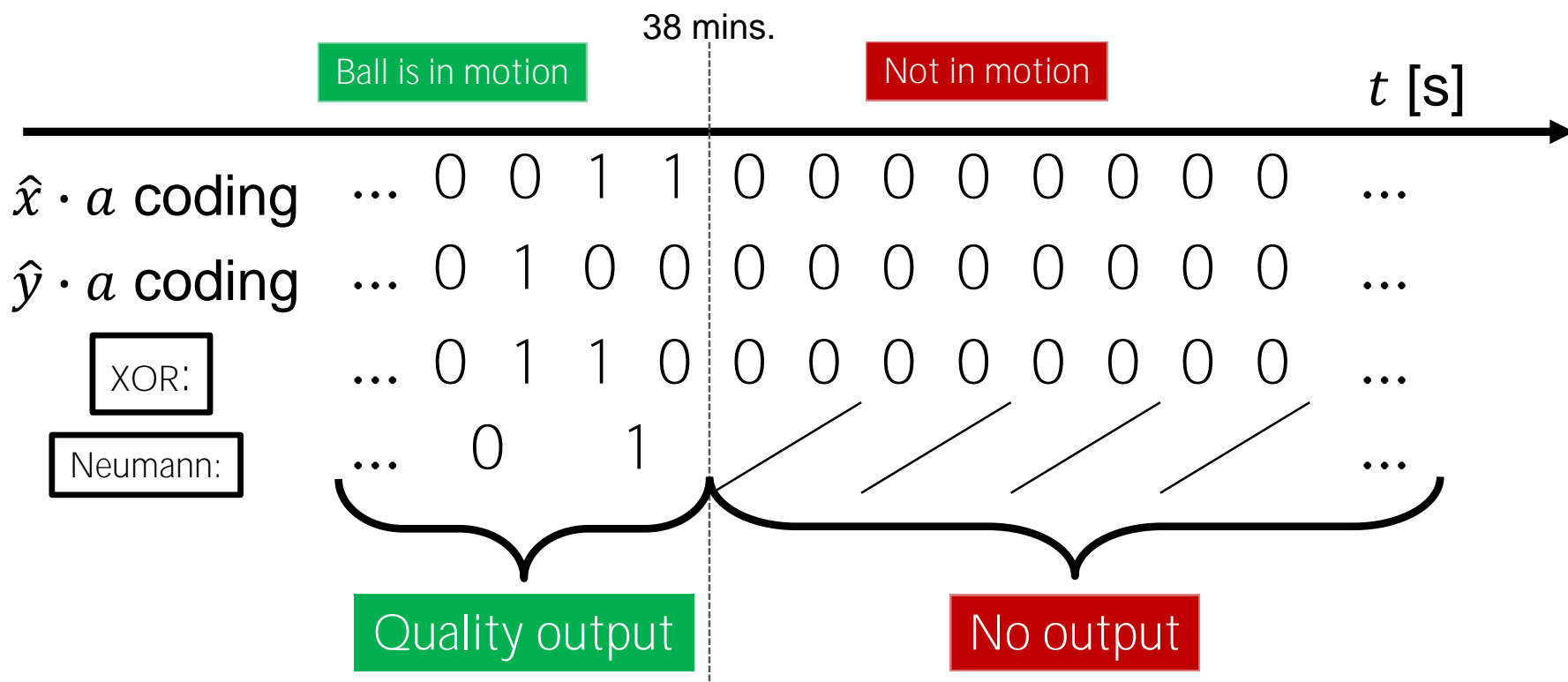


Stopped moving
Completely
after 38 mins.





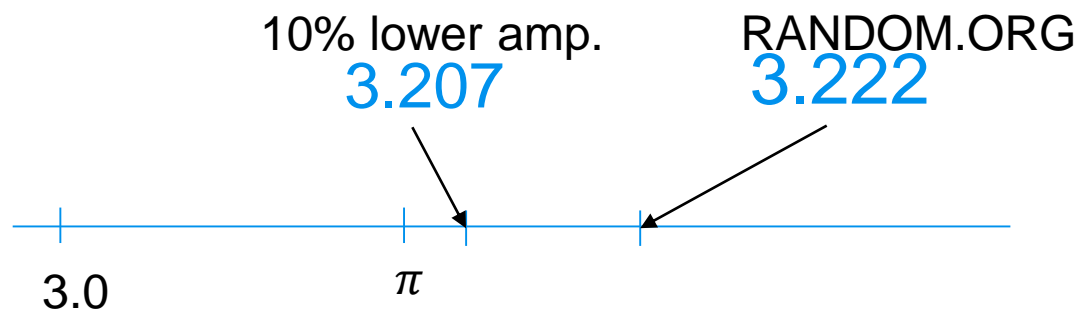
10% lower Amp.





10% lower Amp.: output quality

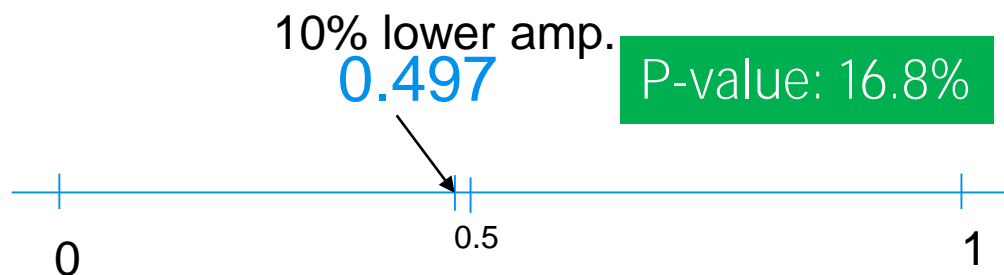
Mote Carlo: π





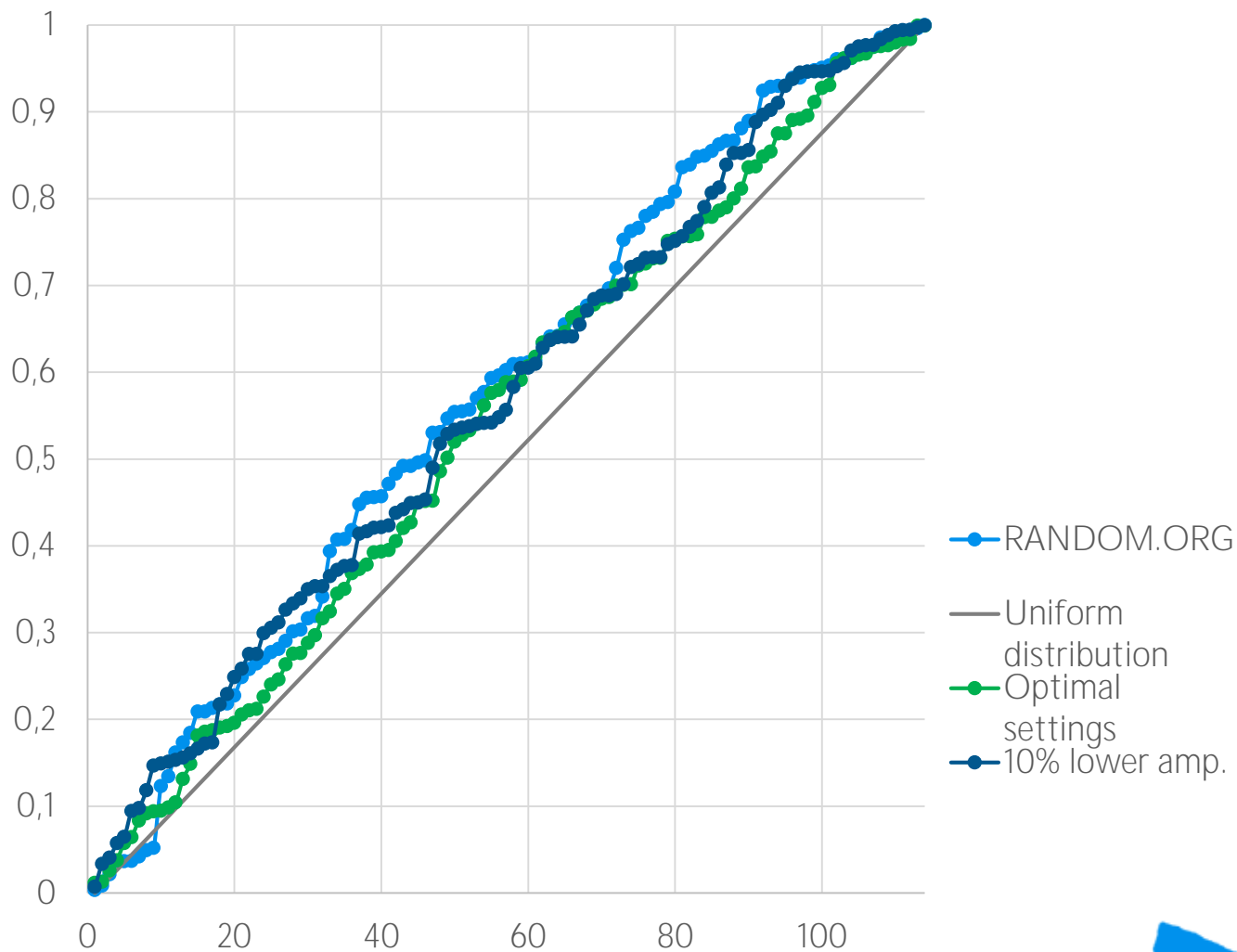
10% lower Amp.: output quality

Avg. bit value





10% lower Amp.: DIEHARDER





CHANGING FREQUENCY



f \longleftrightarrow analogous \longleftrightarrow Amp.

We are only interested
in the acceleration
of the crushed stone

$\longrightarrow a = f^2 A$

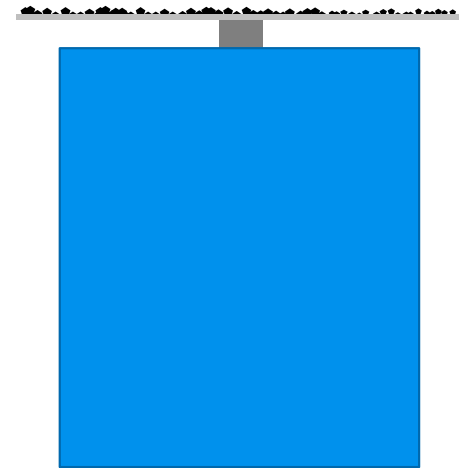
Heat map:

25% increase in f

Increase in f lowered the speaker's amplitude

Lower Af^2

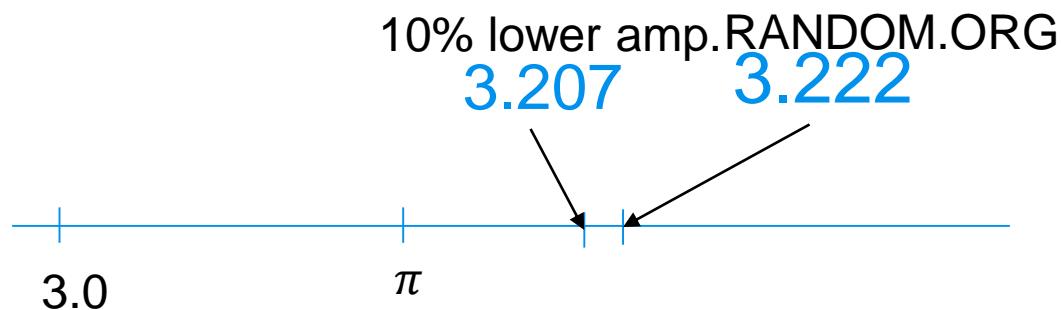
Couldn't easily escape from these holes





25% increase in f : output quality

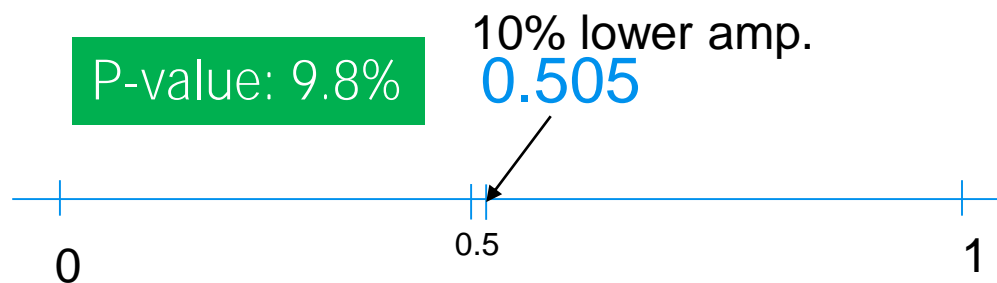
Mote Carlo: π





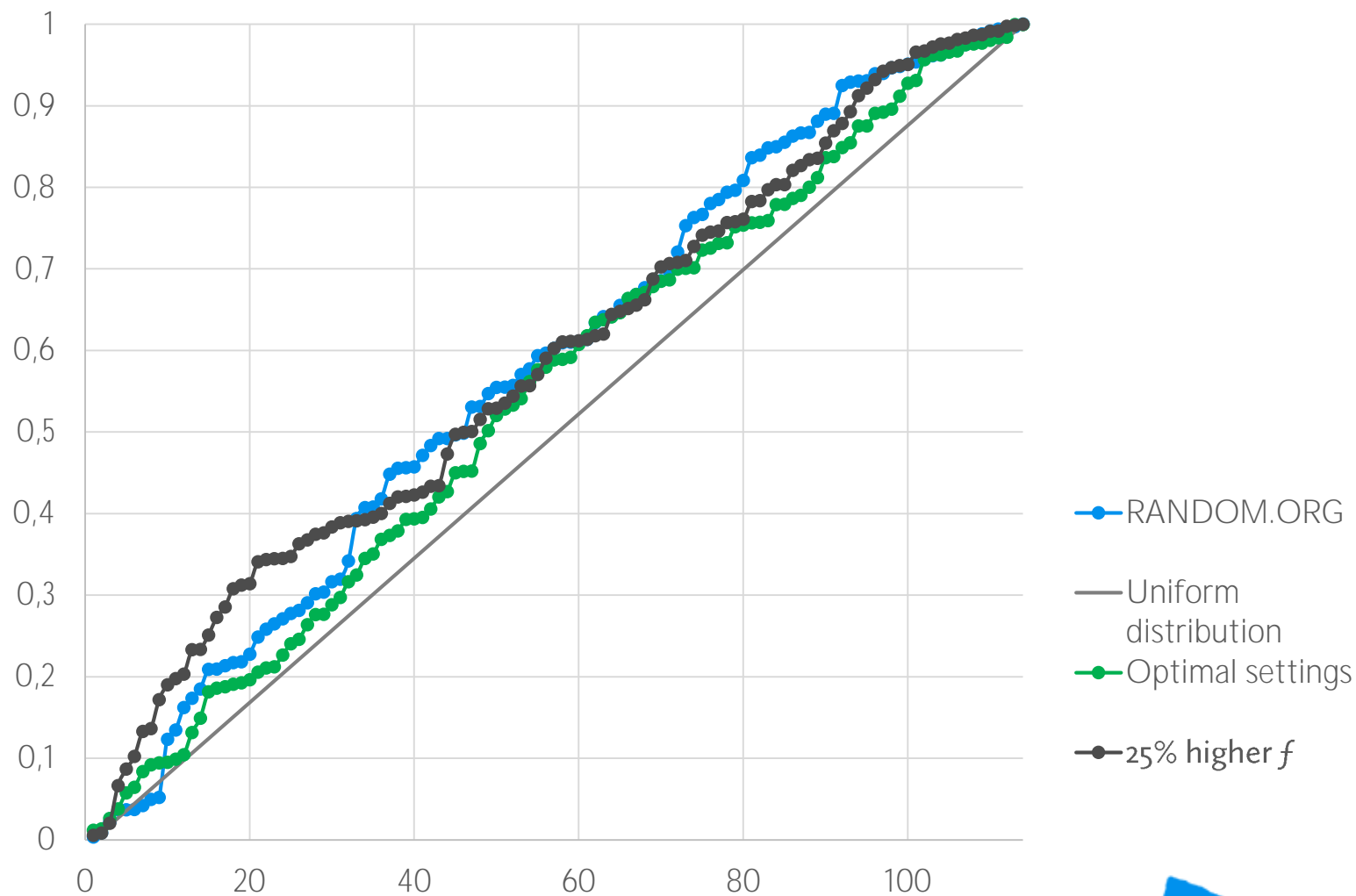
25% increase in f : output quality

Avg. bit value





25% increase in f : DIEHARDER





Conclusion

1. Created a mechanical device + processing software (automated tracking, all algorithms, heat maps, position data,...)

2. Analyzed the randomness: **Extremely high**

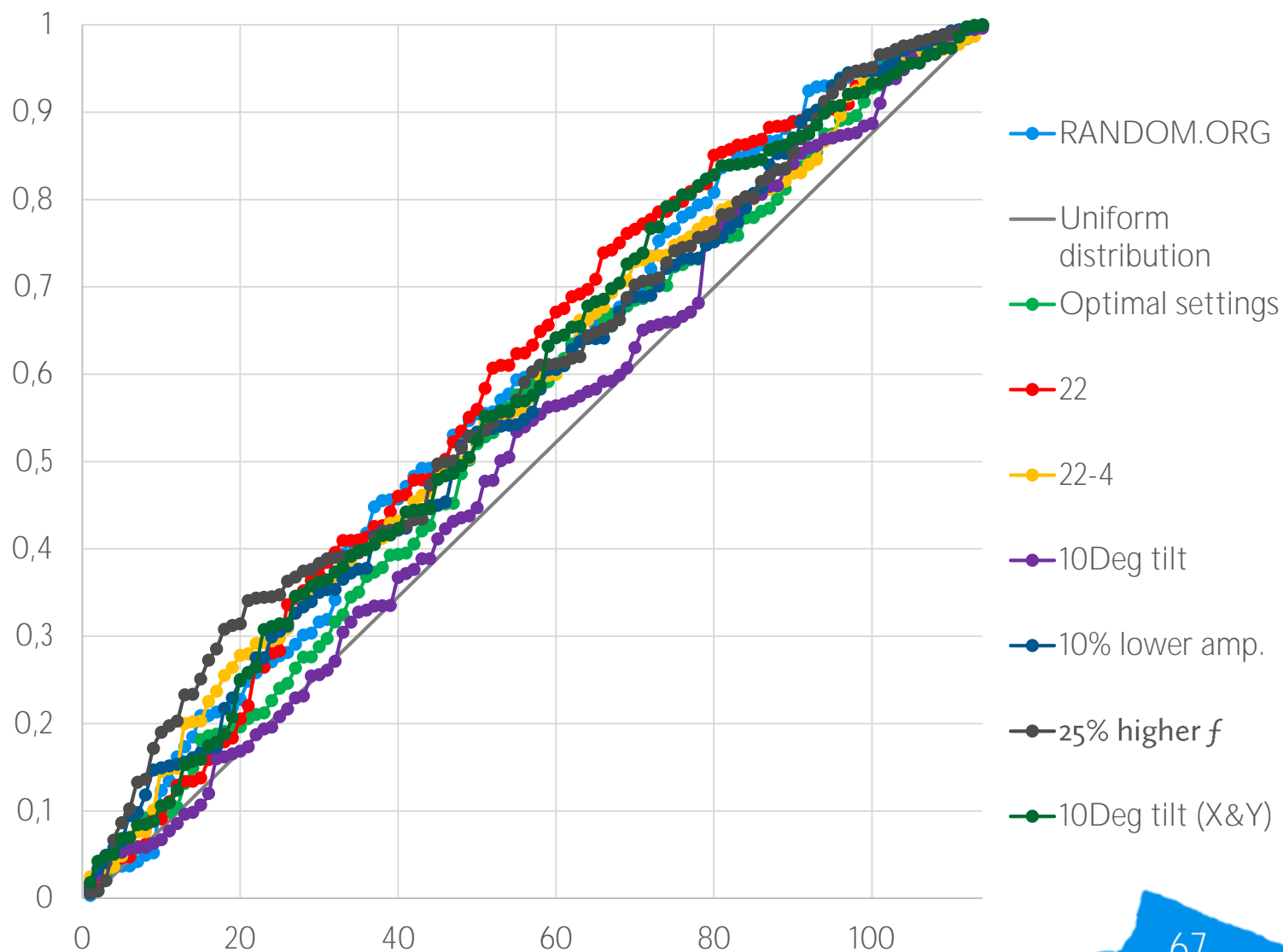
3. Analyzed safeness against tampering: **Extremely safe**

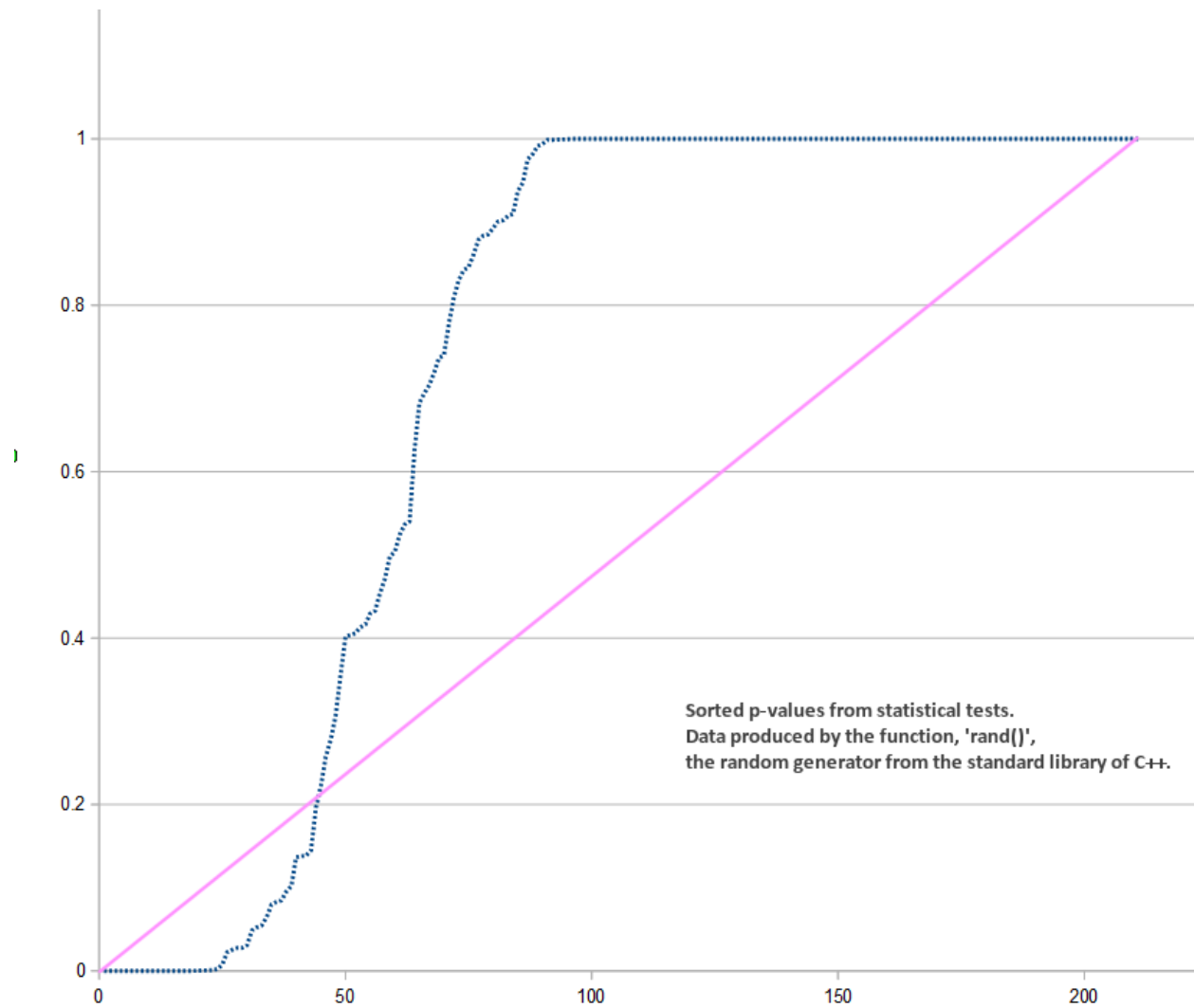


APPENDIX



All DIEHARDER tests







Acceleration Data

-4	1	00	00
-4	1	01	00
0	0	02	04
0	0	03	0-1
-1	0	00	0-1
-1	0	-37	03
0	-1	0	0
0	0	0	0
0	0	0	0
0	0	0	0
0	0	0	0
0	0	0	0
1	-2	0	0
0	0	5	6
0	0	0	0
0	0	0	0
0	0	-2	-2
		0	0
		0	0
		0	0
		0	0
		-3	-5
		0	-1



~~x, y~~ \longrightarrow ~~\dot{x}, \dot{y}~~ \longrightarrow \ddot{x}, \ddot{y}

Contionous

Contionous

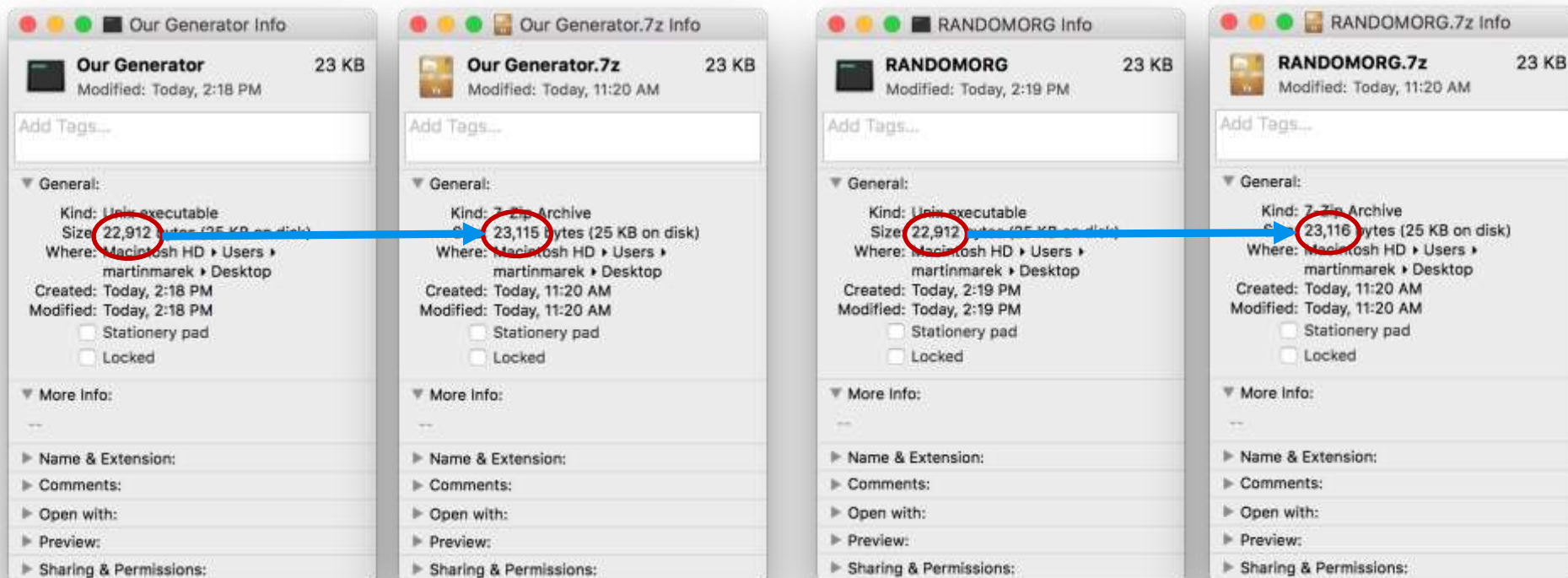
Discrete

Imbalanced

↓
Too long
time interval

↓
most
data

LZMA2 Compression



22,912 → 23,115

22,921 → 23,116

Average Value of all Bits

0.4988

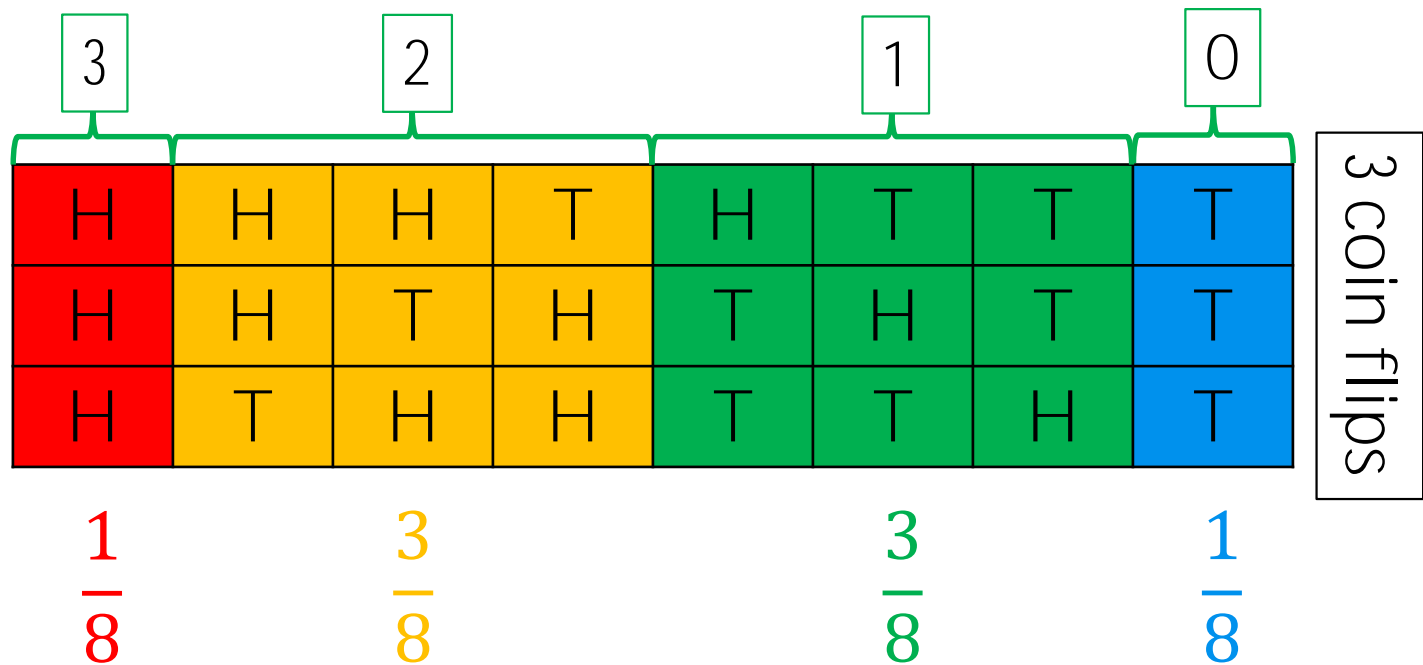
P-value
(the probability of a distribution at least this extreme)
is 14.91%



DIEHARDER

- Battery of 114 statistical test on RNG
- Better parameterized DIEHARD tests
 - Expanded by National Institute for Standards and Technology's tests
- Output of each test: p-values compared to a perfect TRNG

What are p-values? – Example: No. of Heads





Acceleration	Coding
0	01010
1	01011
-1	01001
-2	01000
2	01100
-3	00111
3	01101
-4	00110
-5	00101
4	01111
-6	00100
5	10000
6	10001
-7	00011
-8	00010
7	10010
-9	00001
8	10011
9	10100
-10	00000
10	10101

Compression



2.75x size
reduction

Acceleration	Coding	Probab.
0	1	72.06%
1	011	9.07%
-1	000	5.31%
-2	0011	2.79%
2	01011	2.29%
-3	01000	1.66%
3	00100	1.13%
-4	010100	1.03%
-5	010010	0.77%
4	001011	0.74%
-6	0101010	0.48%
5	0100111	0.47%
6	0010101	0.35%
-7	0010100	0.34%
-8	01001101	0.22%
7	01001100	0.22%
-9	010101110	0.16%
8	010101101	0.15%
9	010101100	0.11%
-10	0101011111	0.10%
10	0101011110	0.06%

Std. coding → 5 bit.

Comp. → 1.82 bit.



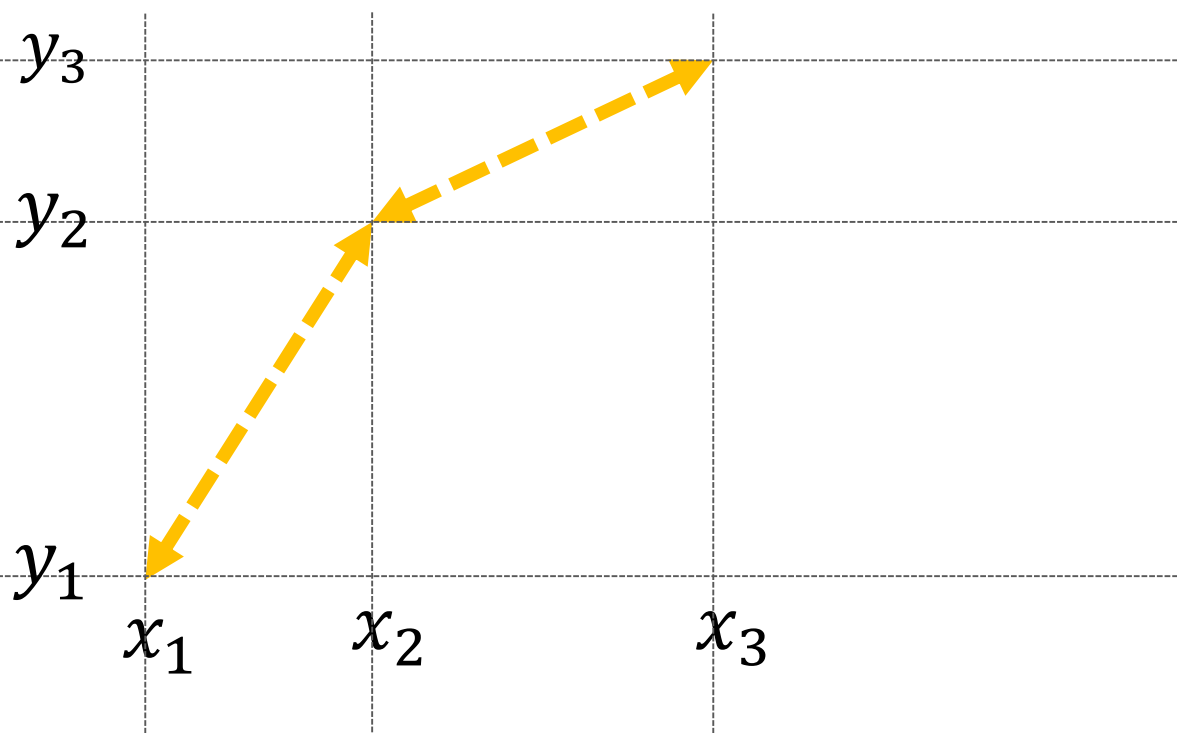
Acc.	Coding
0	1
1	011
-1	000
-2	0011
2	01011
-3	01000
3	00100
-4	010100
-5	010010
4	001011
-6	0101010
5	0100111
6	0010101
-7	0010100
-8	01001101
7	01001100
-9	010101110
8	010101101
9	010101100
-10	0101011111
10	0101011110

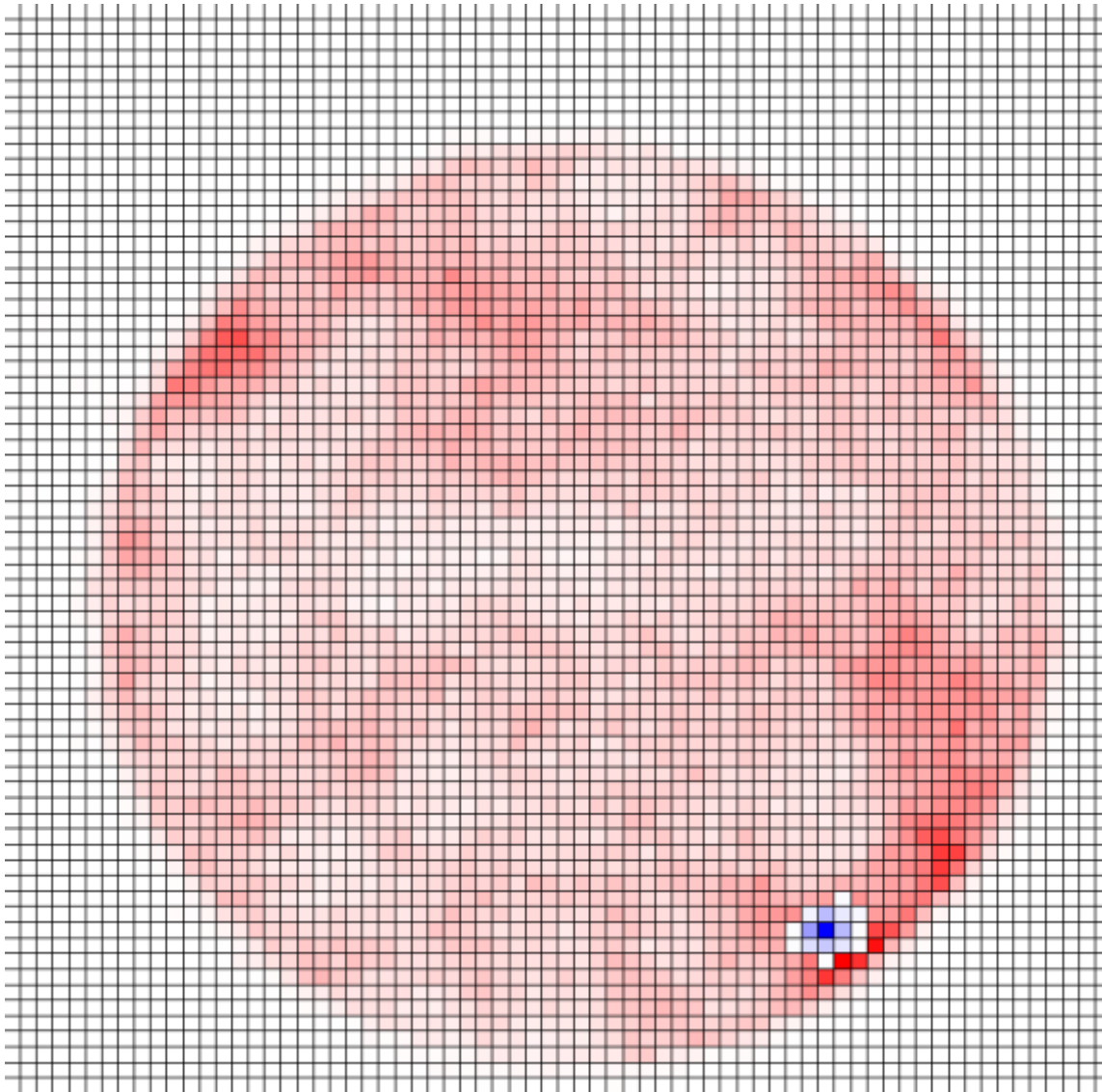
0,0,0,-4,0,0,-2,1,-2,1,0,-2

1 1 1 0101001 1 0011 011 1 0011 1 011



$$v_1 = (x_2 - x_1, y_2 - y_1)$$
$$v_2 = (x_3 - x_2, y_3 - y_2)$$
$$a = (2x_2 - x_1 - x_3, 2y_2 - y_1 - y_3)$$





~~x, y~~

Position



~~x, y~~



Acceleration Histogram

