



2

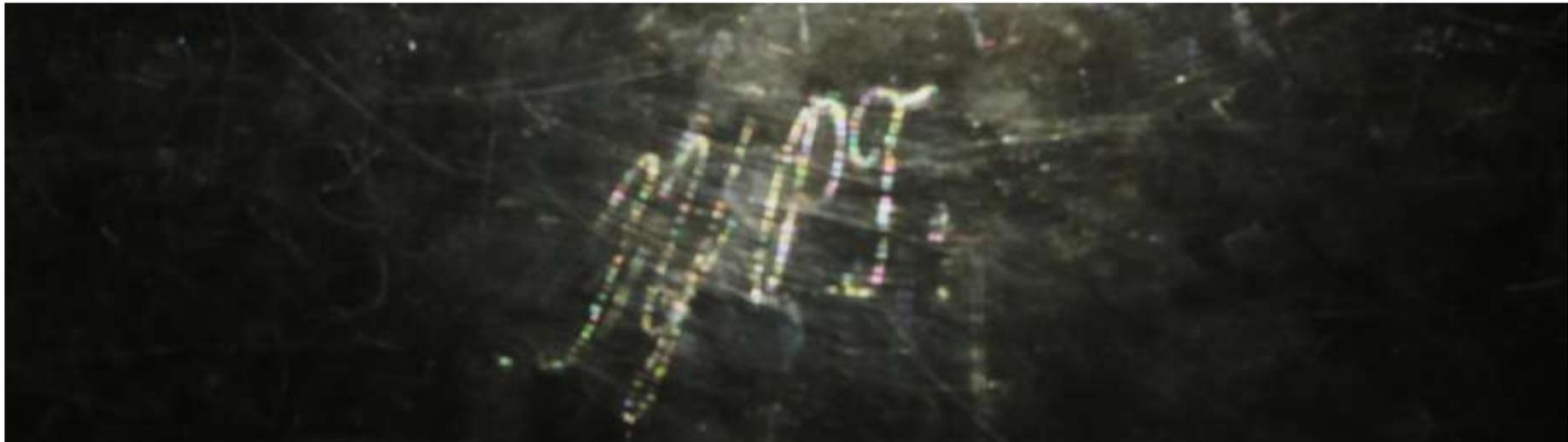
Hologram

Mário Lipovský

Task

It is argued that a hologram can be hand made by scratching a piece of plastic.

Produce such a 'hologram' with the letters 'IYPT' and investigate how it works.





Real hologram - 3D image stored in 2D



LASER

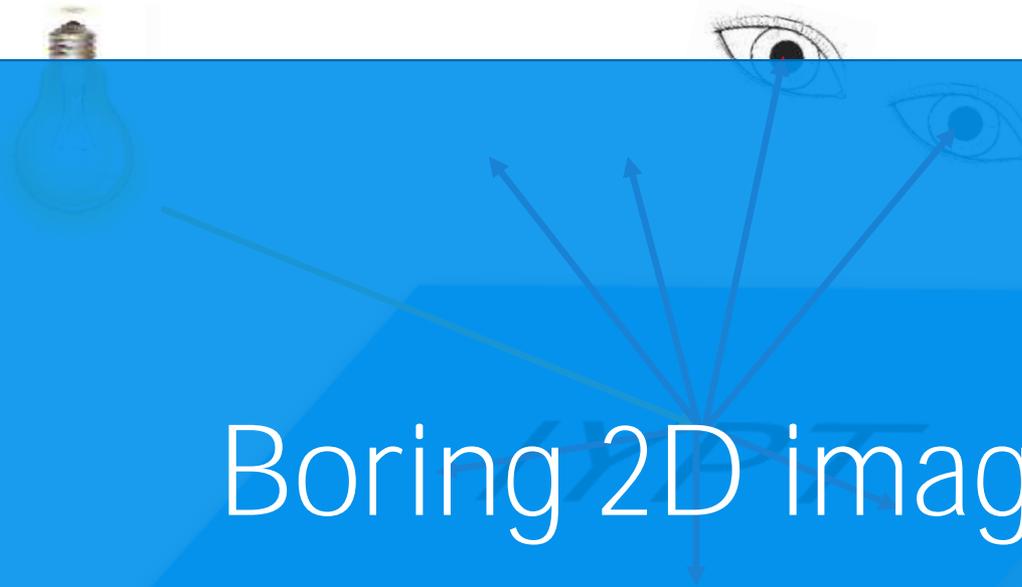
This is not our case

What is scratched “hologram”
in this task?



REFERENCE
BEAM

Simple scratch on the plastic



Boring 2D image

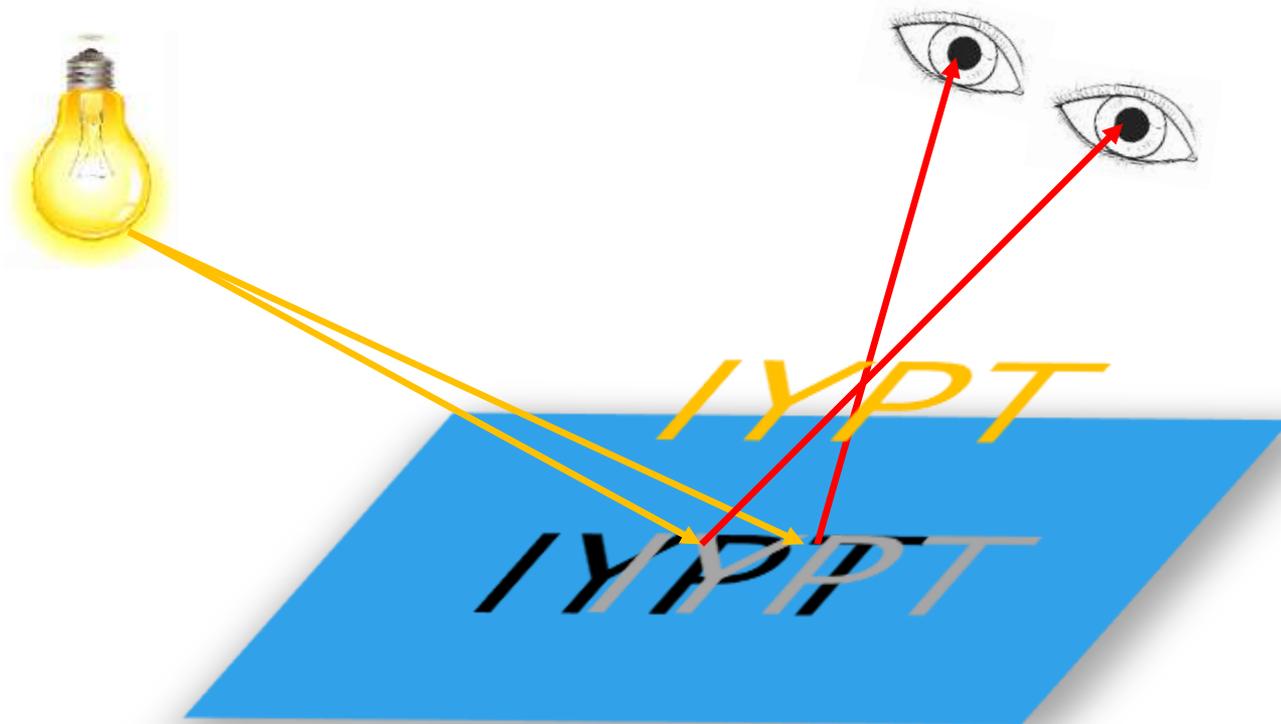
Light is scattered to all directions

Both eyes see the image at the same position

Whole image visible on the surface

“Hologram” = advanced image

If 2 eyes see 2 different images



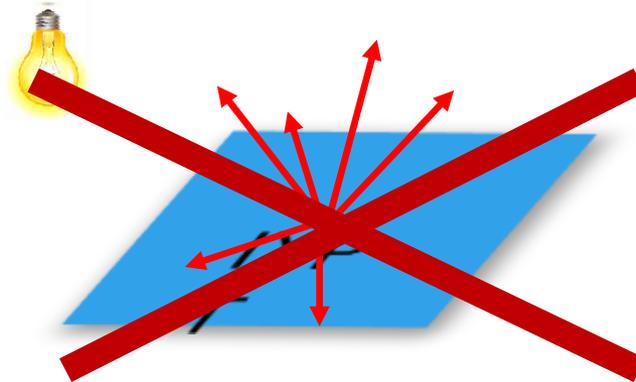
Final image is visible over/under the surface

“Hologram” = advanced image

2 eyes see 2 different images

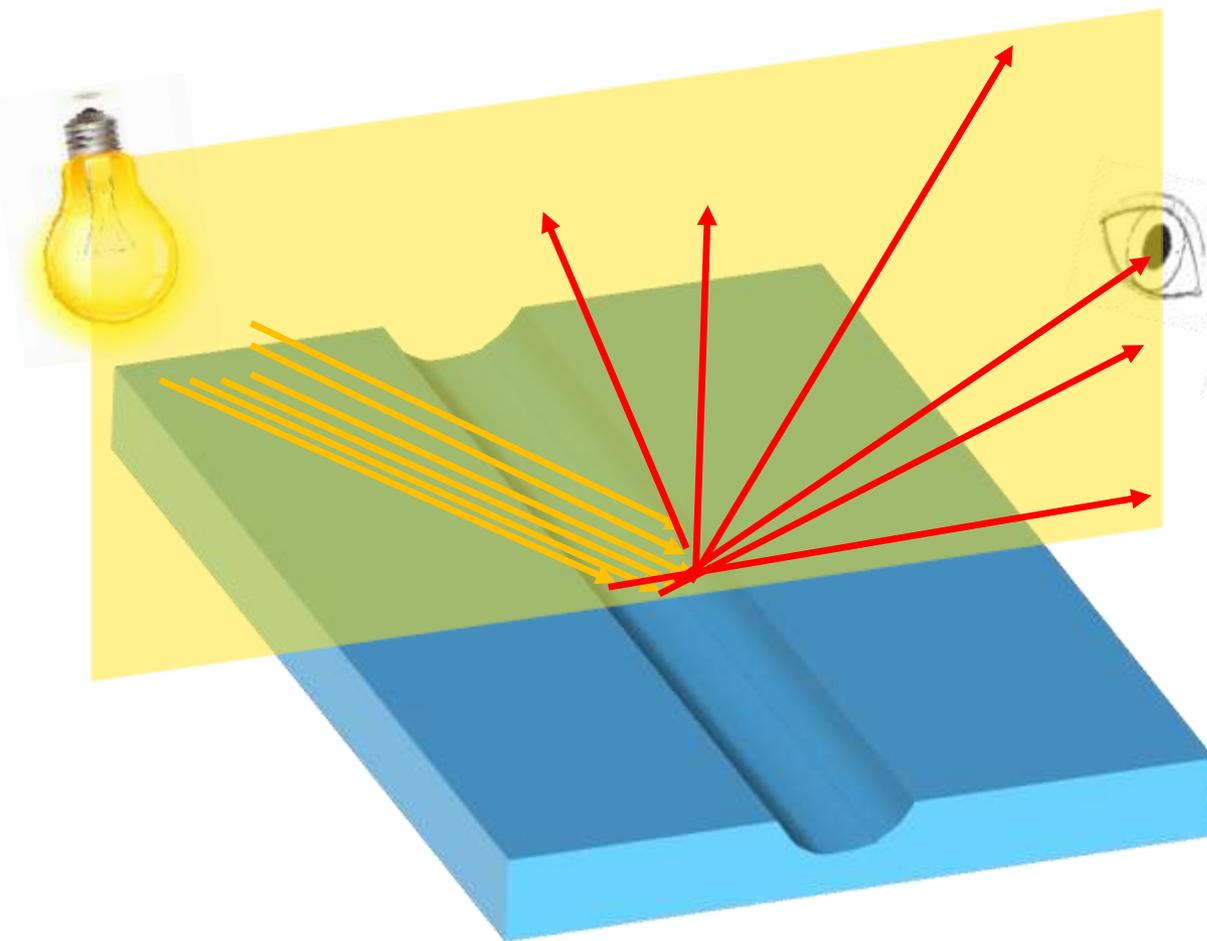
How can this be achieved?

Light can't be scattered to all directions



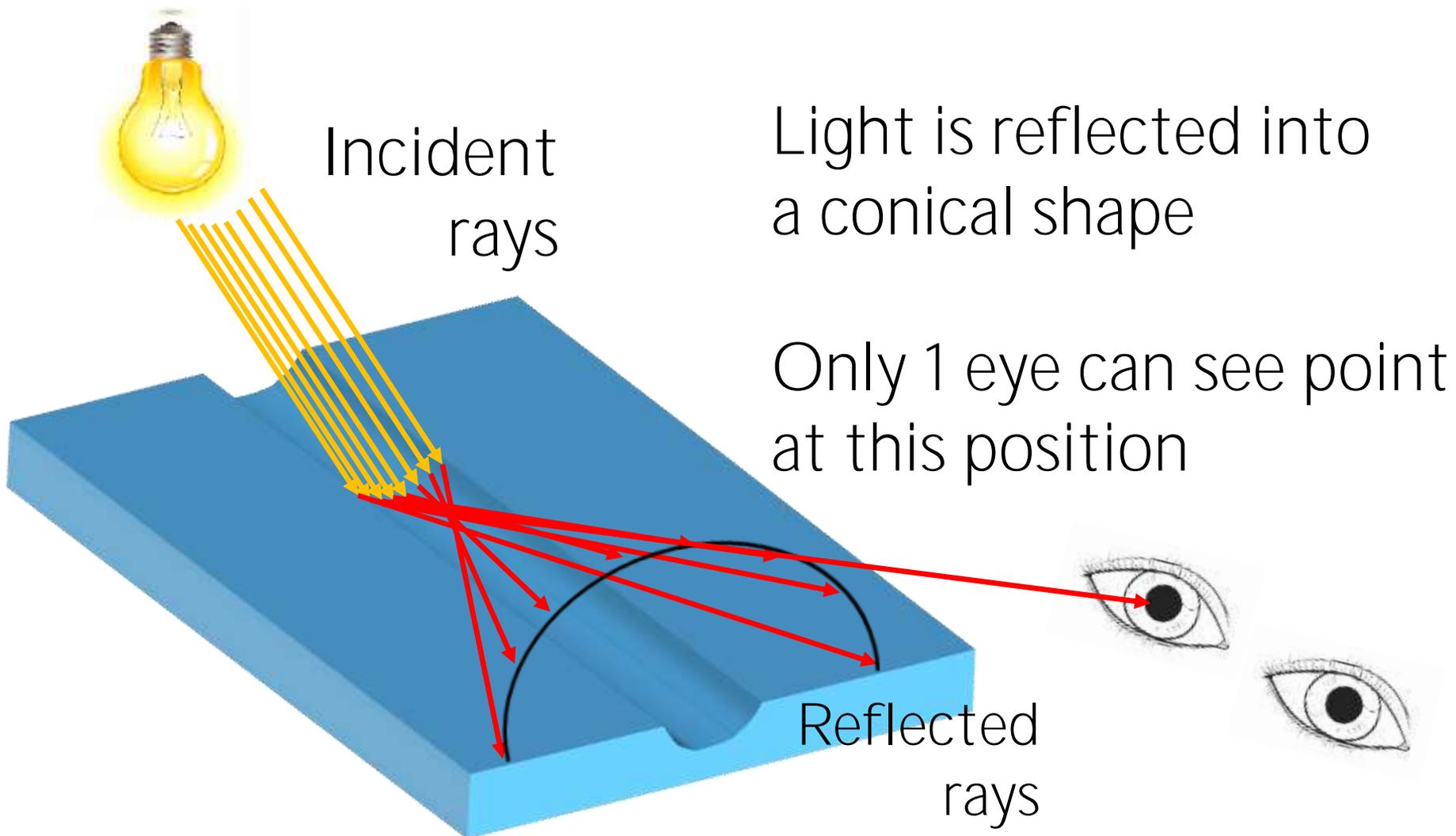
Smooth scratch – planar scatter

Light is scattered
in only 1 plane



Only 1 eye
can see the image
at this position

Smooth scratch – conical scatter



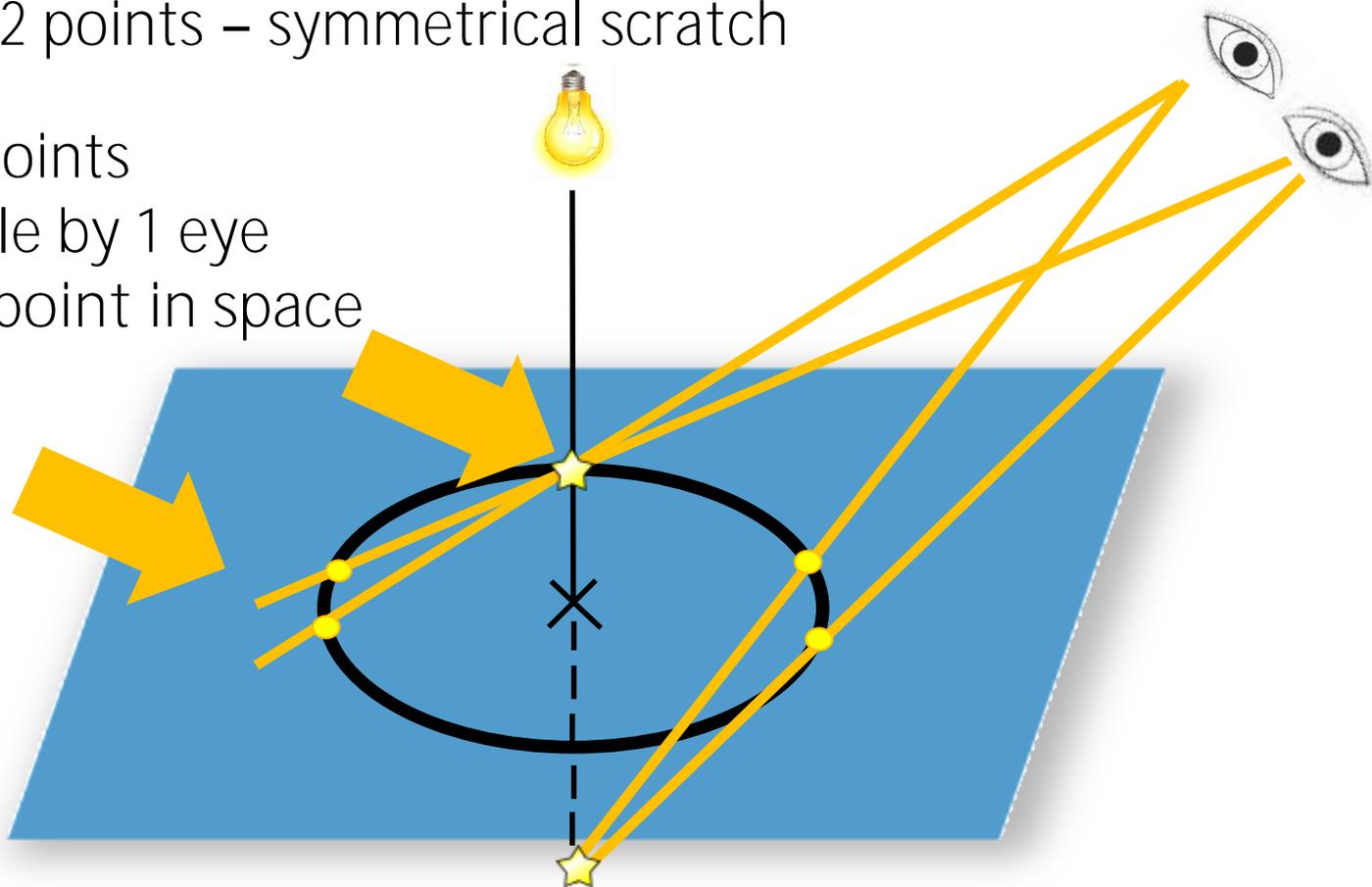
Circular scratch behaviour

Eye can see 2 points – symmetrical scratch

2 different points

each visible by 1 eye

form a point in space



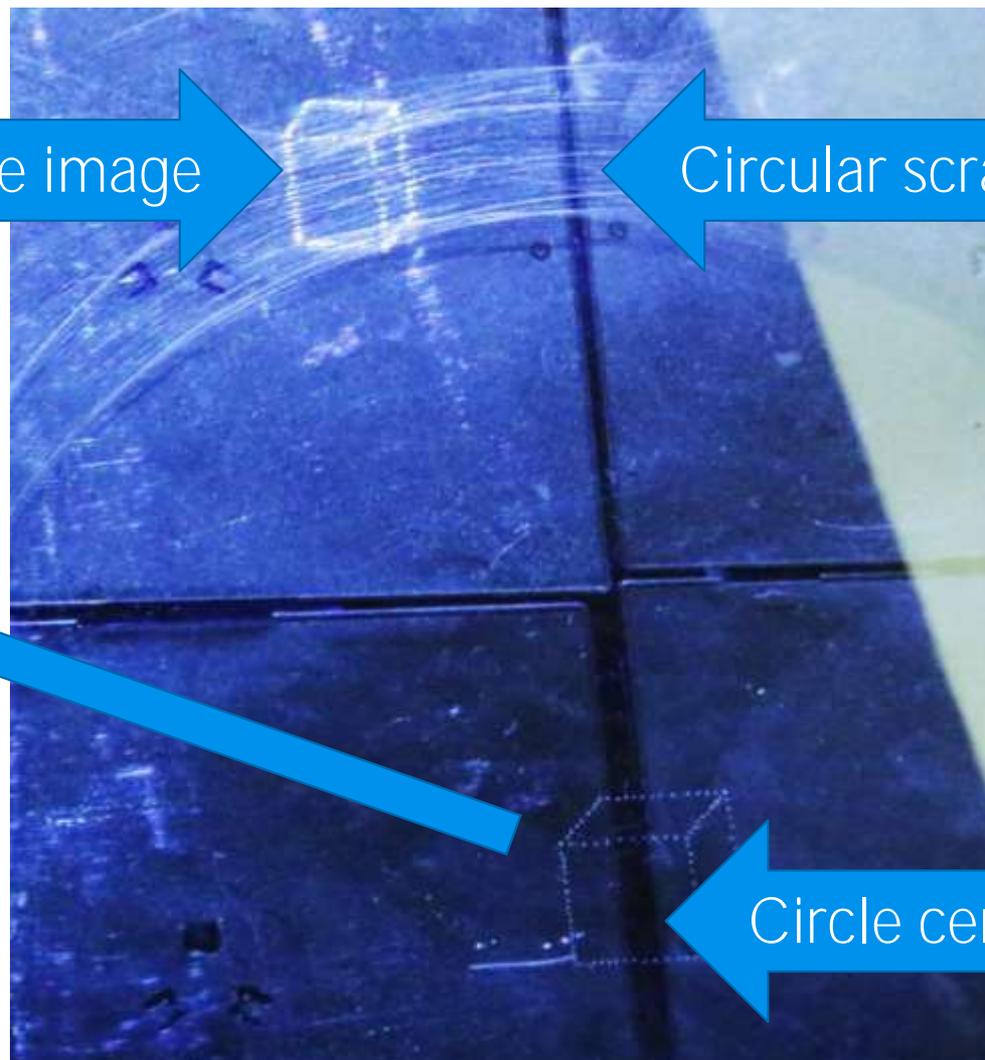
Hologram of 2D view of cube

Visible image

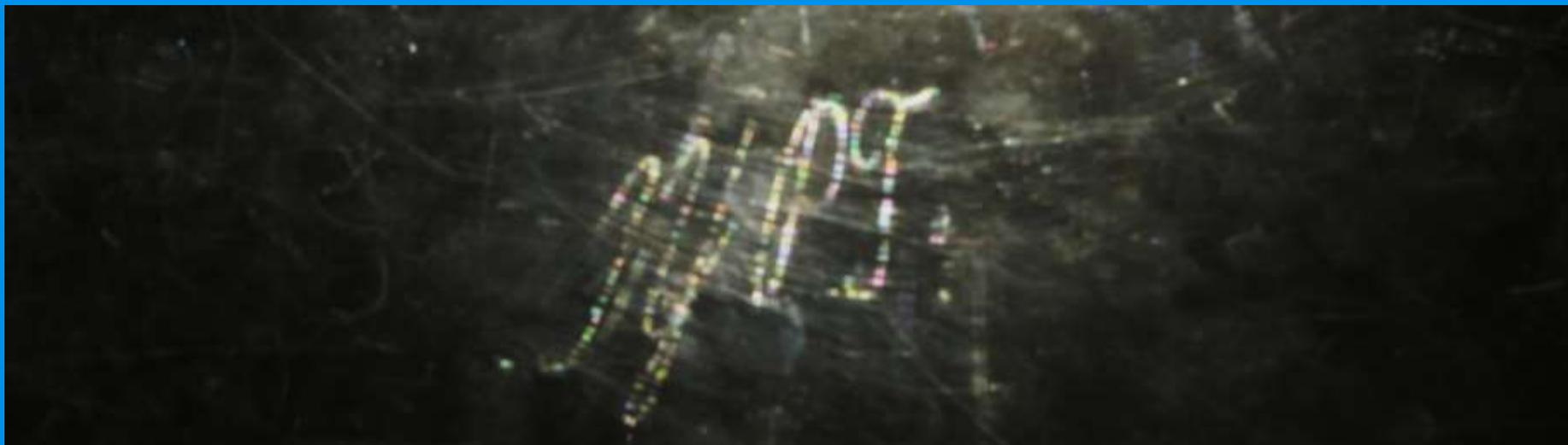
Circular scratches

Circle centres

More points of reflection
= reflected line



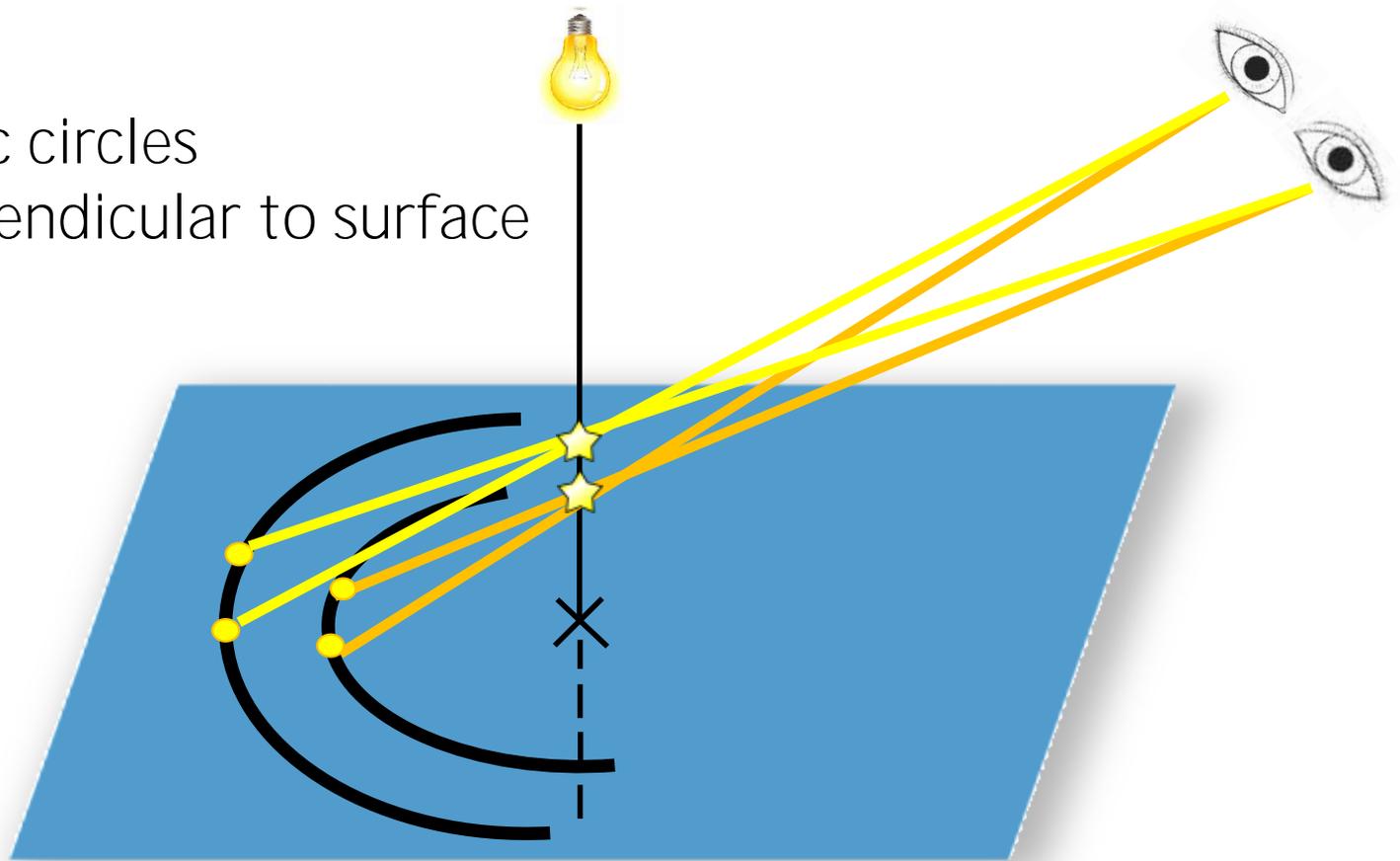
2D HOLOGRAM IS EASY TO CREATE



LET'S CREATE $3D$ HOLOGRAM

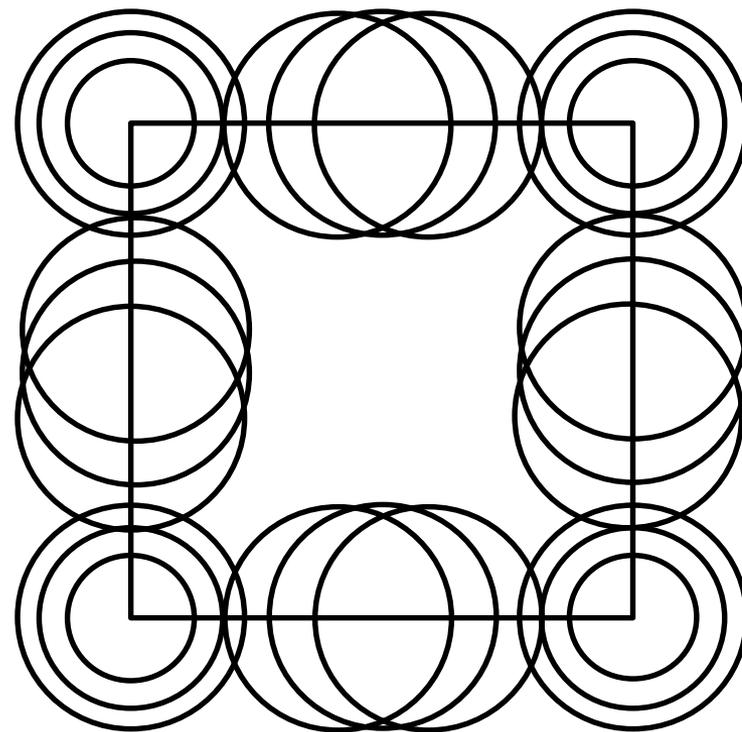
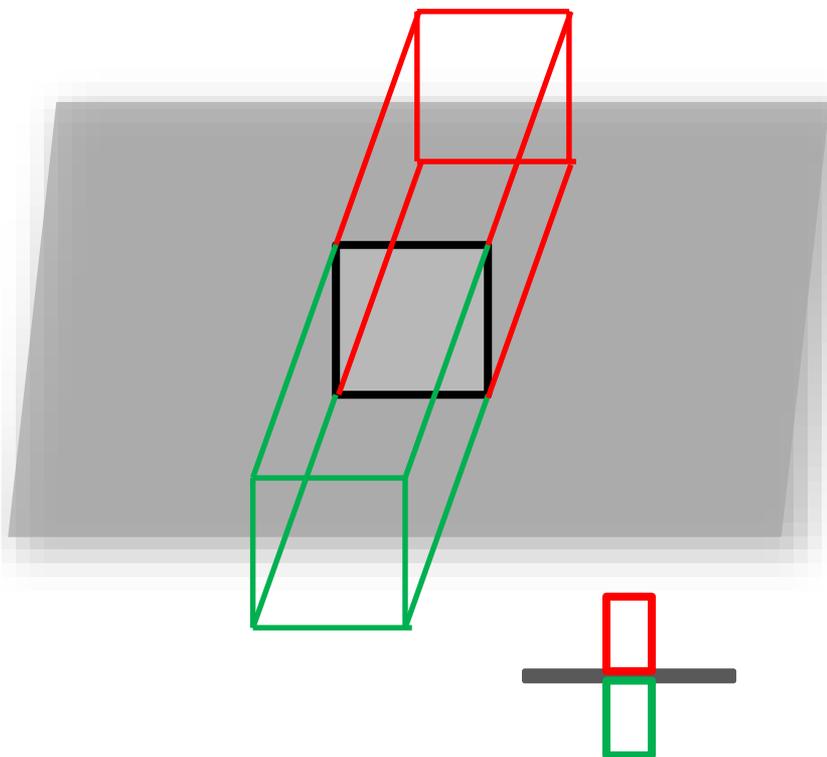
Depth of point vs. radius of circle

Concentric circles
= line perpendicular to surface

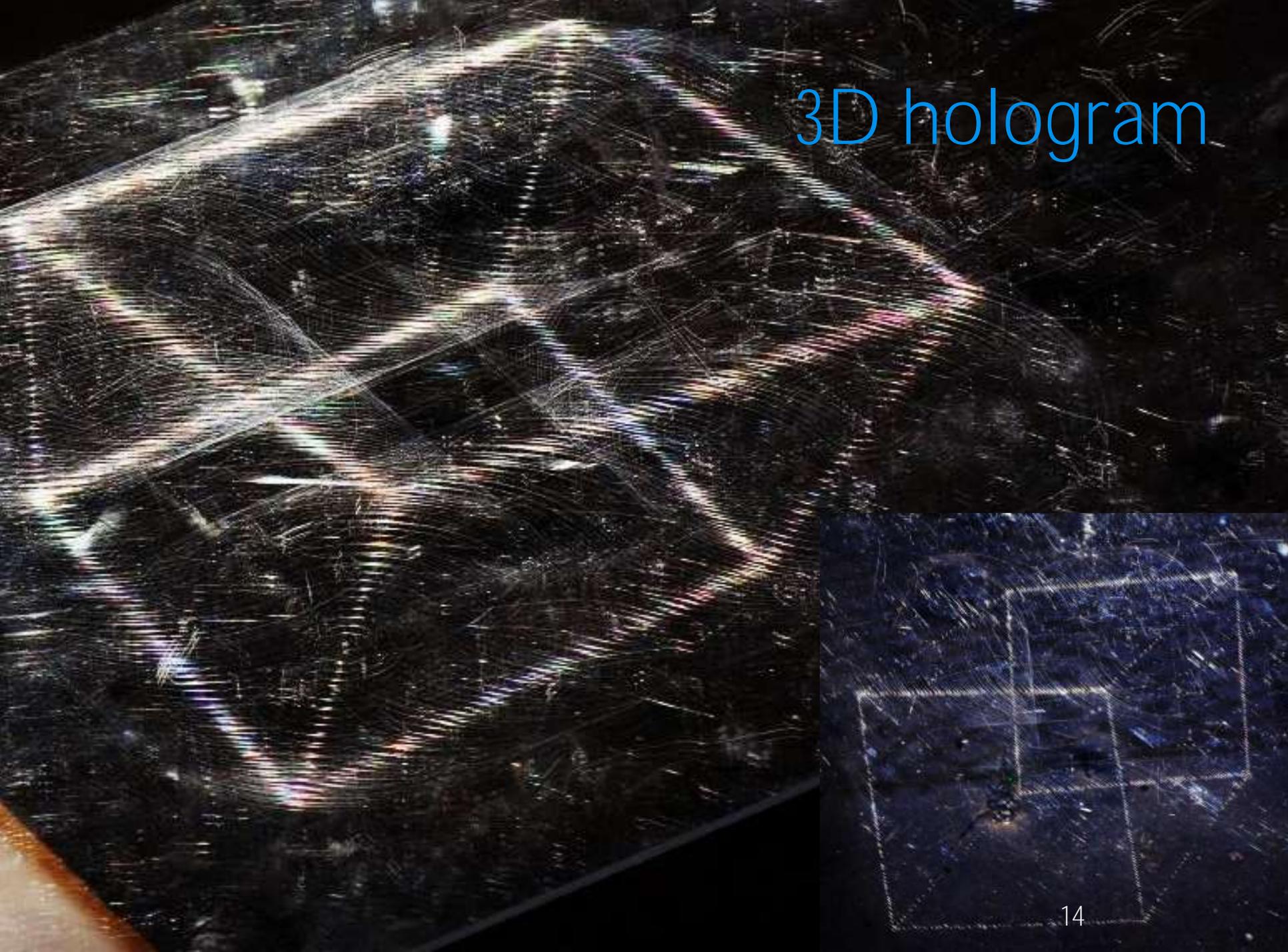


Creating 3D hologram

- 1) Sketch
- 2) Concentric circles = perpendicular
- 3) Constant radius = parallel



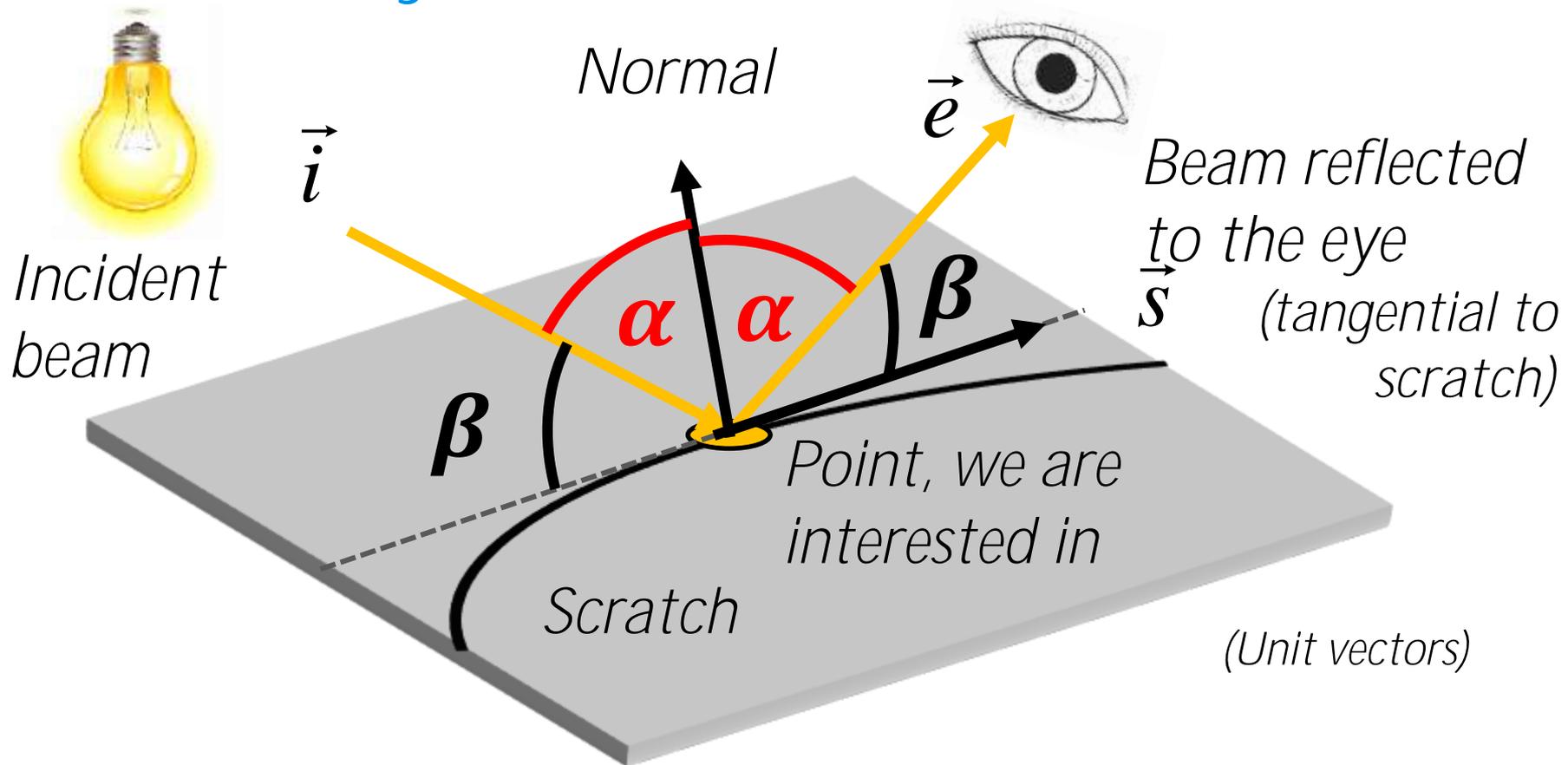
3D hologram





EXACT CALCULATION OF REFLECTION POINTS

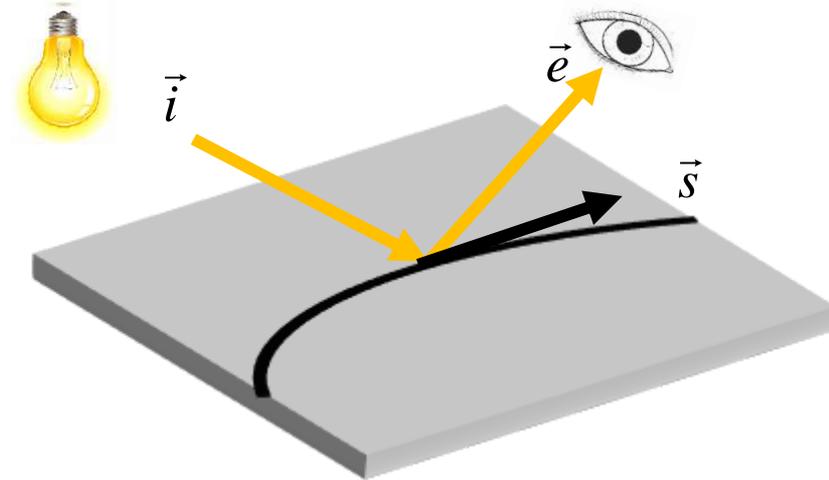
Geometry of the beam



Condition of shining: $\vec{i} \circ \vec{s} = \vec{e} \circ \vec{s}$

Condition of reflection

$$\vec{i} \circ \vec{s} = \vec{e} \circ \vec{s}$$



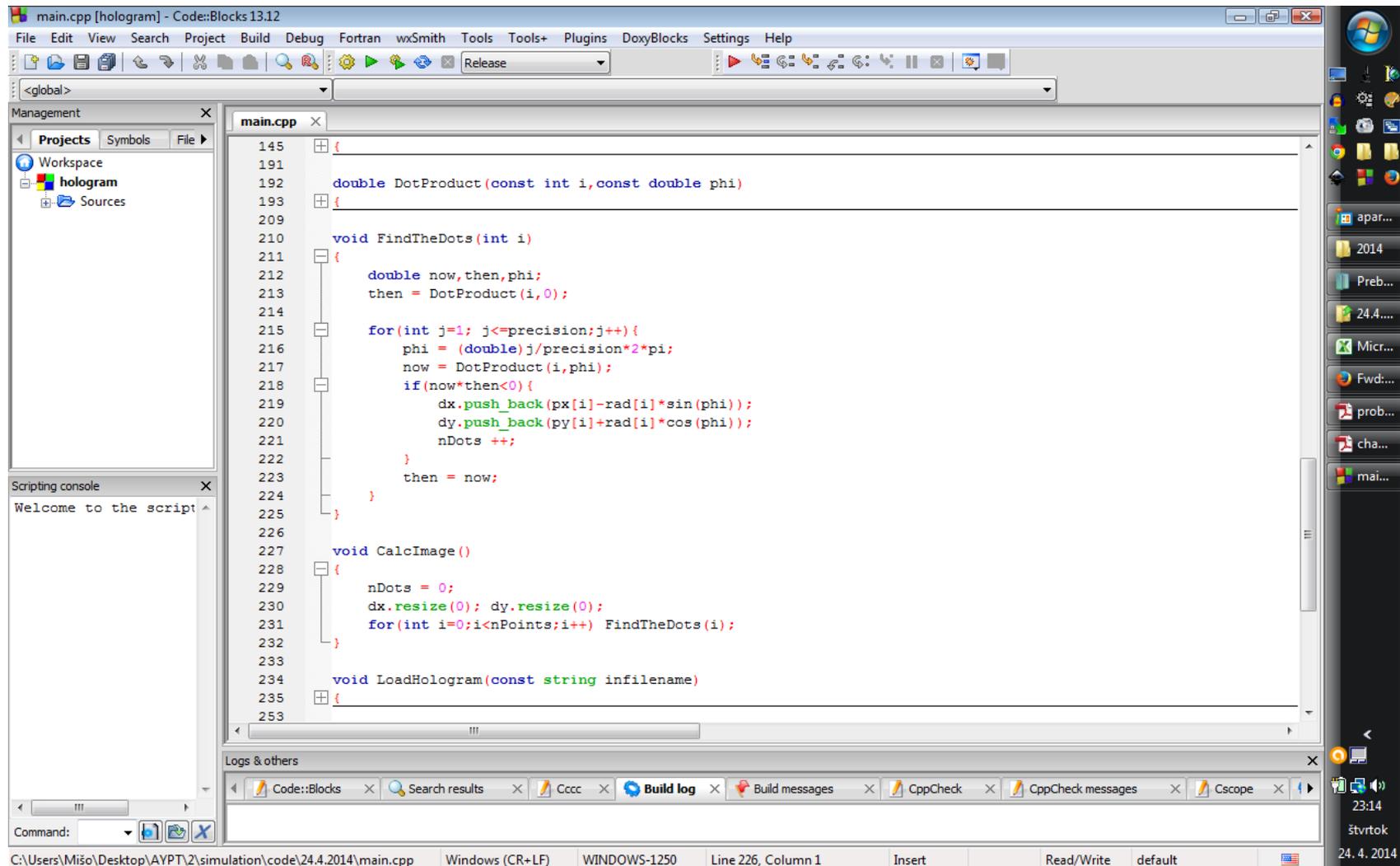
*Which points on a circle
fulfill this condition?*

Too difficult to solve analytically

Simulation

- C++, OpenGL 3D graphics
- Numerically checks the condition
 - for 600+ points on each circle

Simulation

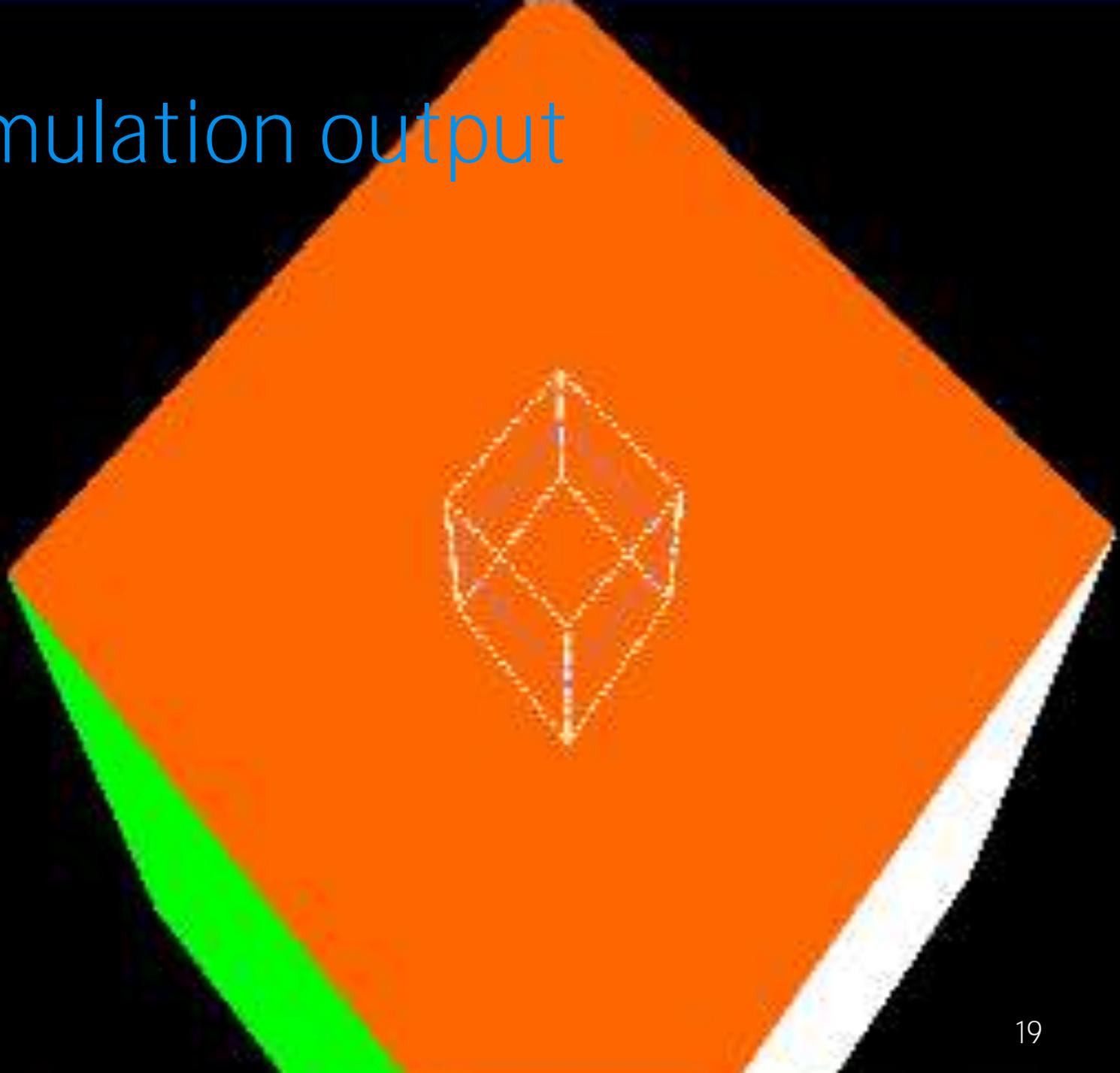


```
main.cpp [hologram] - Code::Blocks 13.12
File Edit View Search Project Build Debug Fortran wxSmith Tools Tools+ Plugins DoxyBlocks Settings Help
<global>
Management
Projects Symbols File
Workspace
hologram
Sources
Scripting console
Welcome to the script
main.cpp
145 {
191
192 double DotProduct(const int i,const double phi)
193 {
209
210 void FindTheDots(int i)
211 {
212     double now,then,phi;
213     then = DotProduct(i,0);
214
215     for(int j=1; j<=precision;j++){
216         phi = (double)j/precision*2*pi;
217         now = DotProduct(i,phi);
218         if(now*then<0){
219             dx.push_back(px[i]-rad[i]*sin(phi));
220             dy.push_back(py[i]+rad[i]*cos(phi));
221             nDots ++;
222         }
223         then = now;
224     }
225 }
226
227 void CalcImage()
228 {
229     nDots = 0;
230     dx.resize(0); dy.resize(0);
231     for(int i=0;i<nPoints;i++) FindTheDots(i);
232 }
233
234 void LoadHologram(const string infilename)
235 {
253 }
```

Code::Blocks x Search results x Cccc x Build log x Build messages x CppCheck x CppCheck messages x Cscope x

Command: | Windows (CR+LF) | WINDOWS-1250 | Line 226, Column 1 | Insert | Read/Write | default | 23:14 | 24. 4. 2014

Simulation output



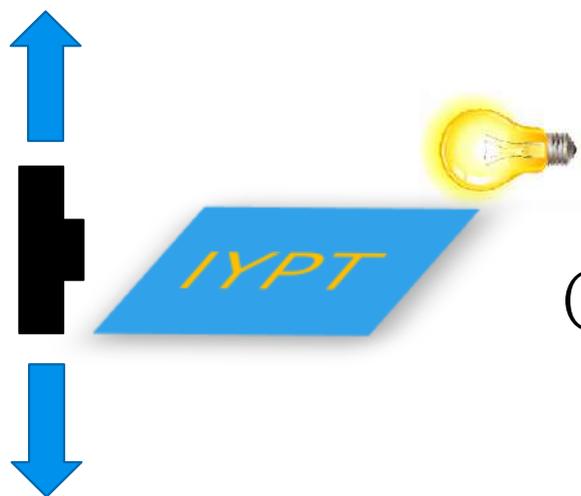
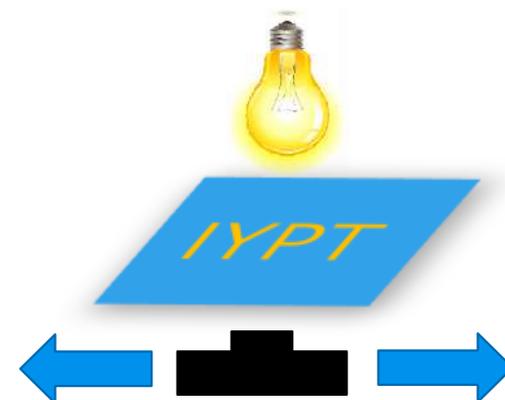


EXPERIMENTAL VERIFICATION OF THEORY

Experimental conditions

Light and hologram - stay at the same place

Camera moves horizontally



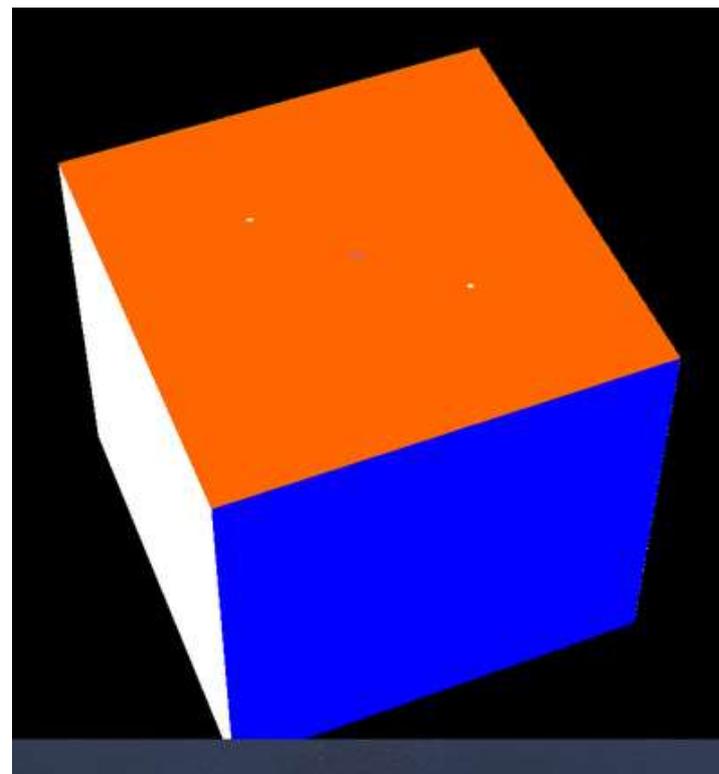
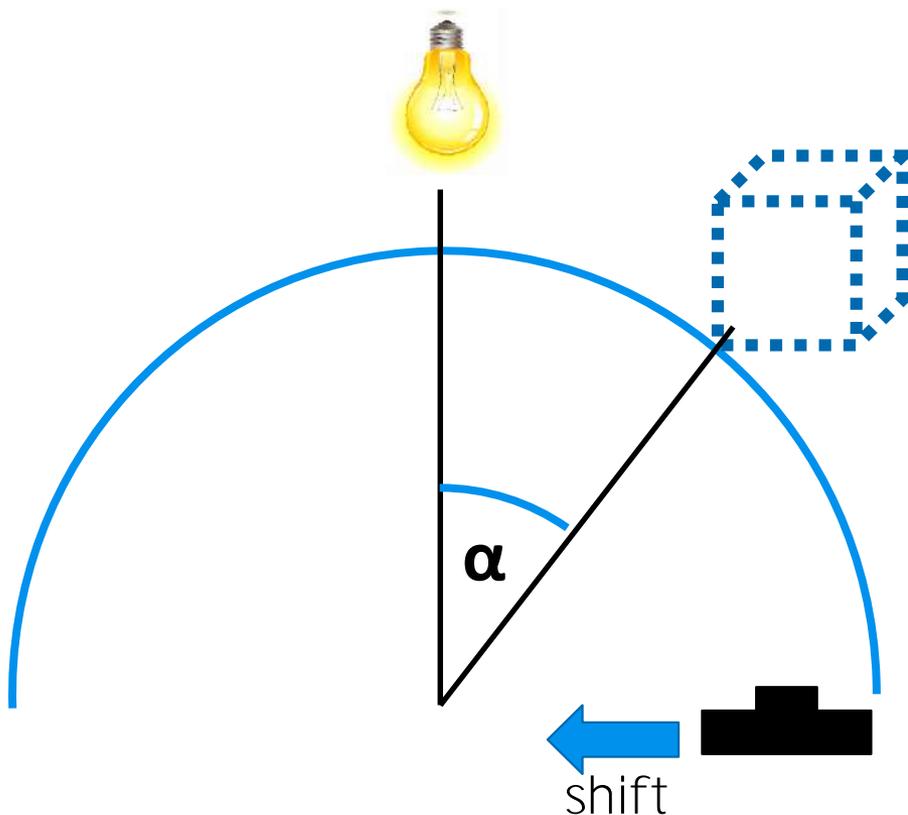
Camera moves vertically

Horizontal camera movement

Angular position
of 1 point

vs.

Horizontal displacement
of camera



Experimental setup

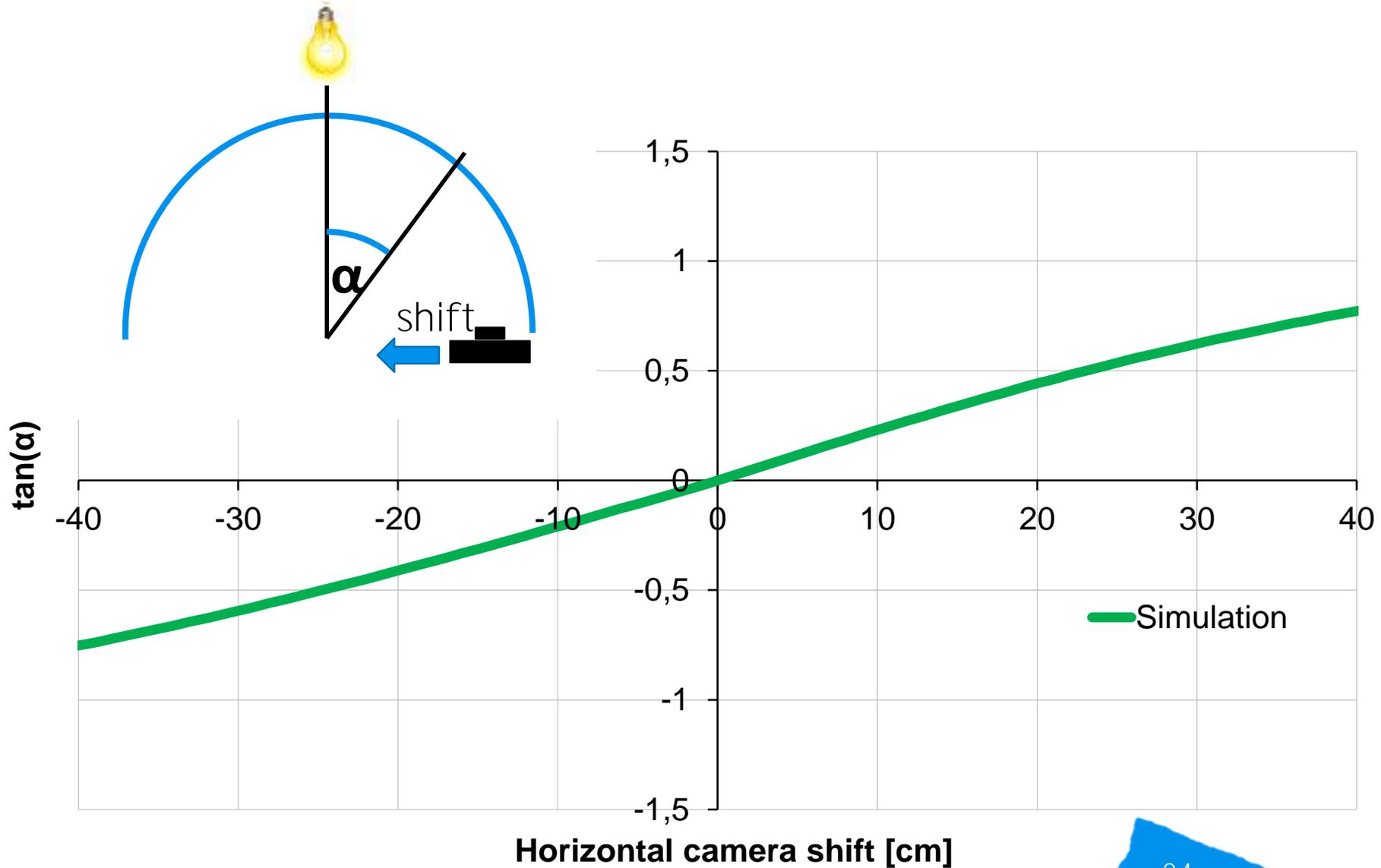


Camera shift

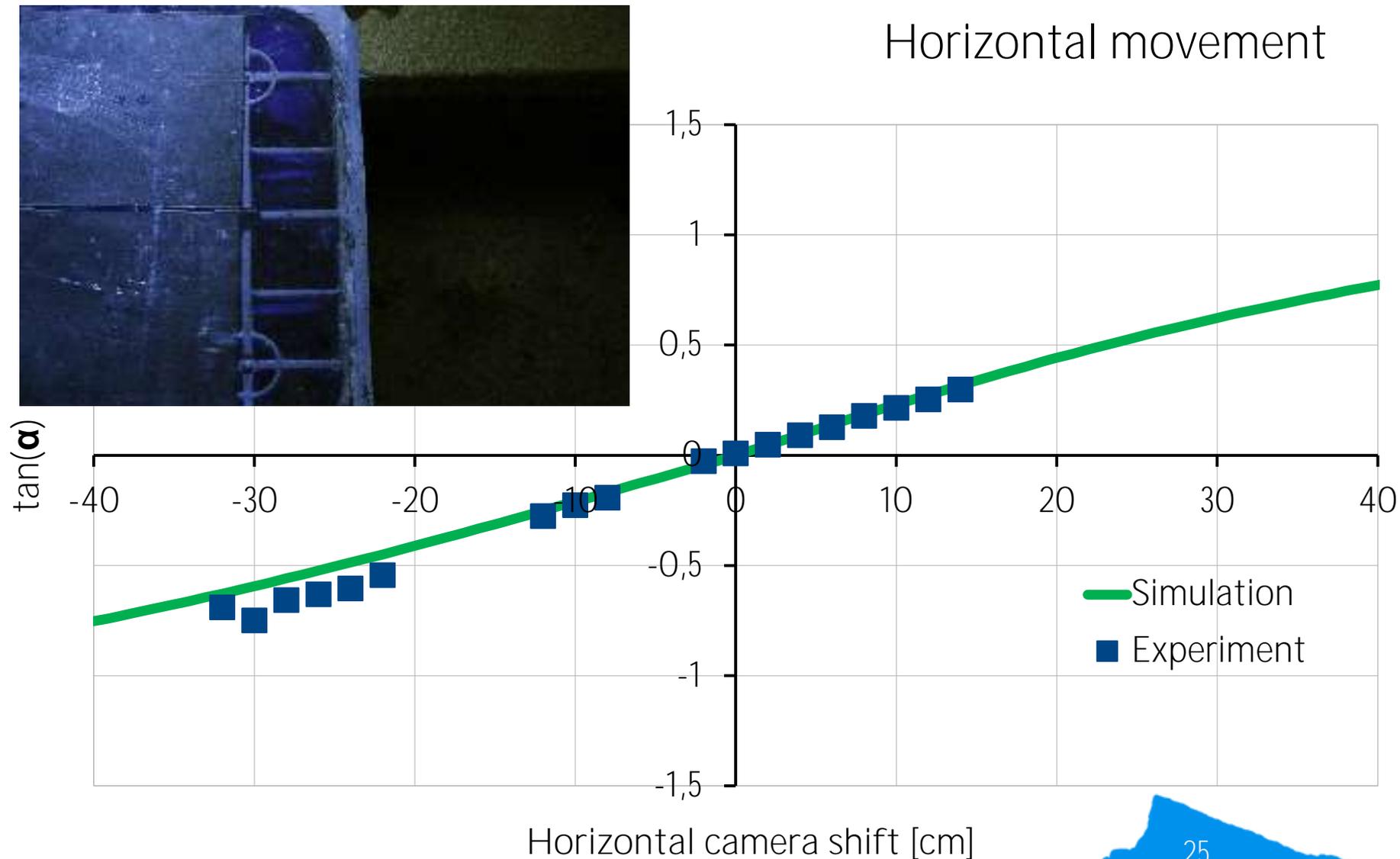


Hologram shift

Horizontal movement - simulation



Simulation vs. experiment

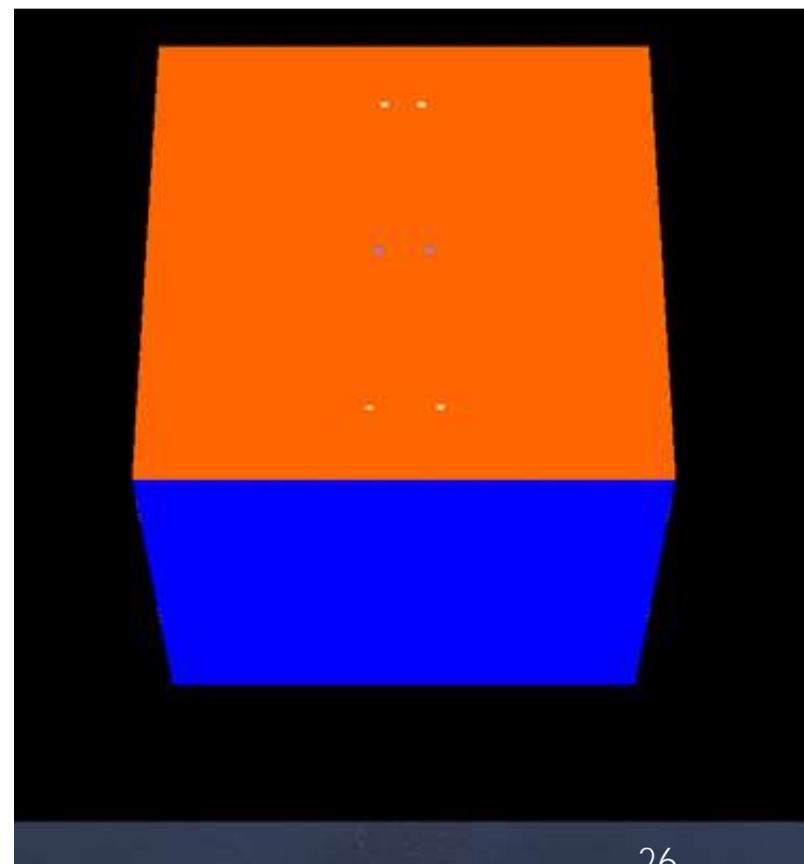
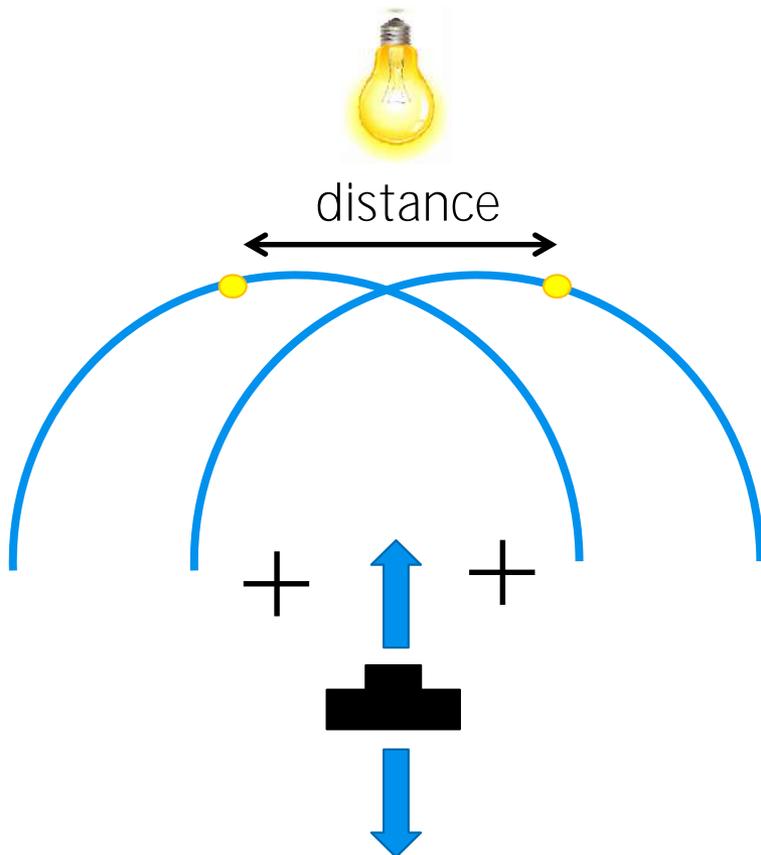


Vertical camera movement

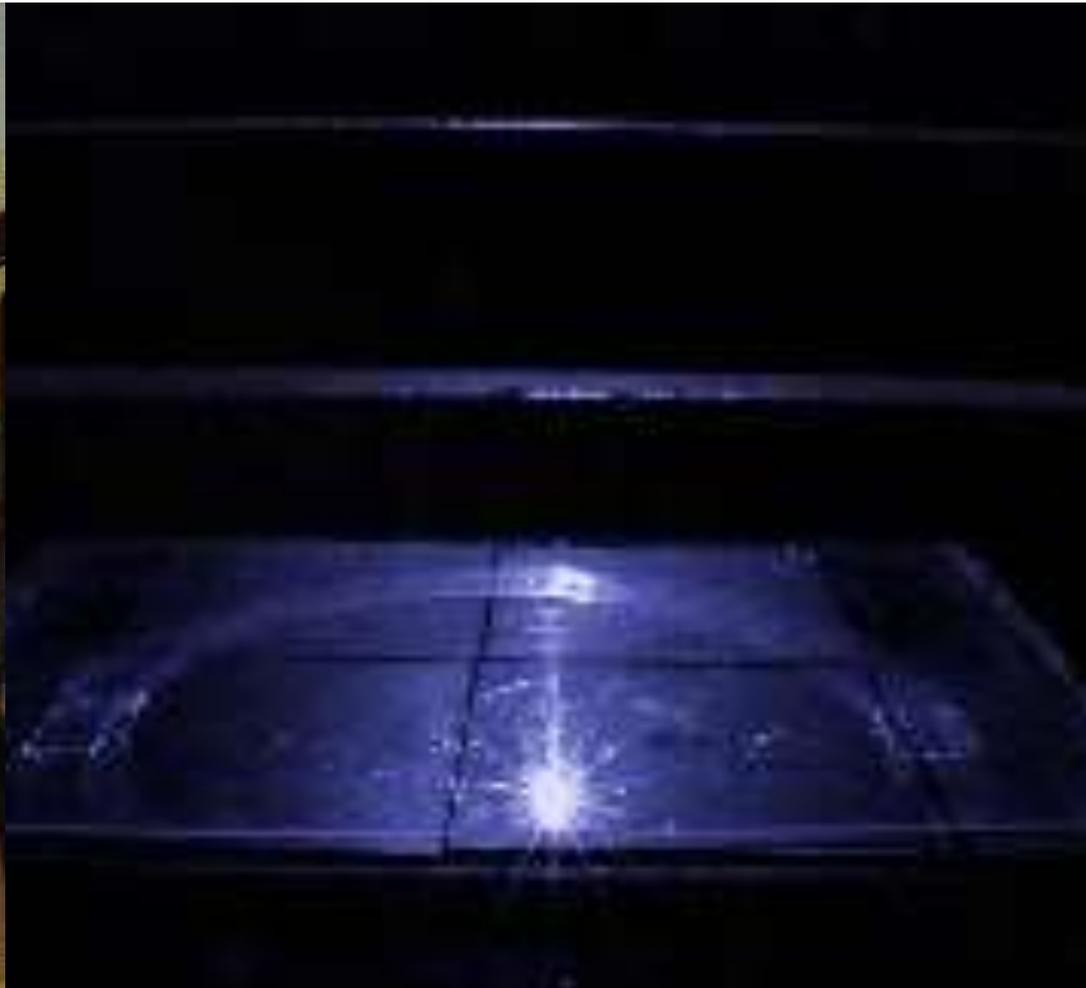
Distance
of 2 points

vs.

Vertical displacement
of camera

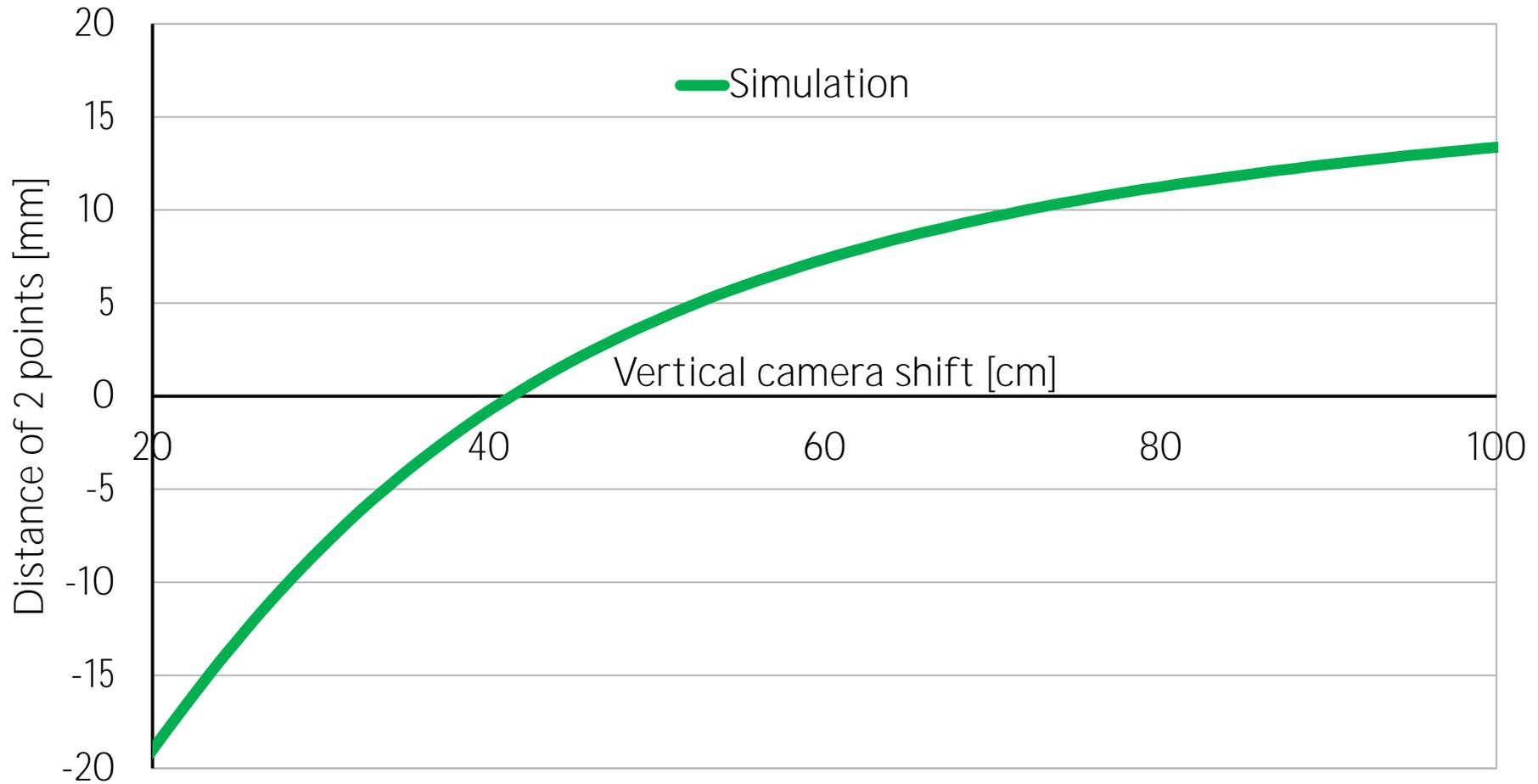


Experimental setup



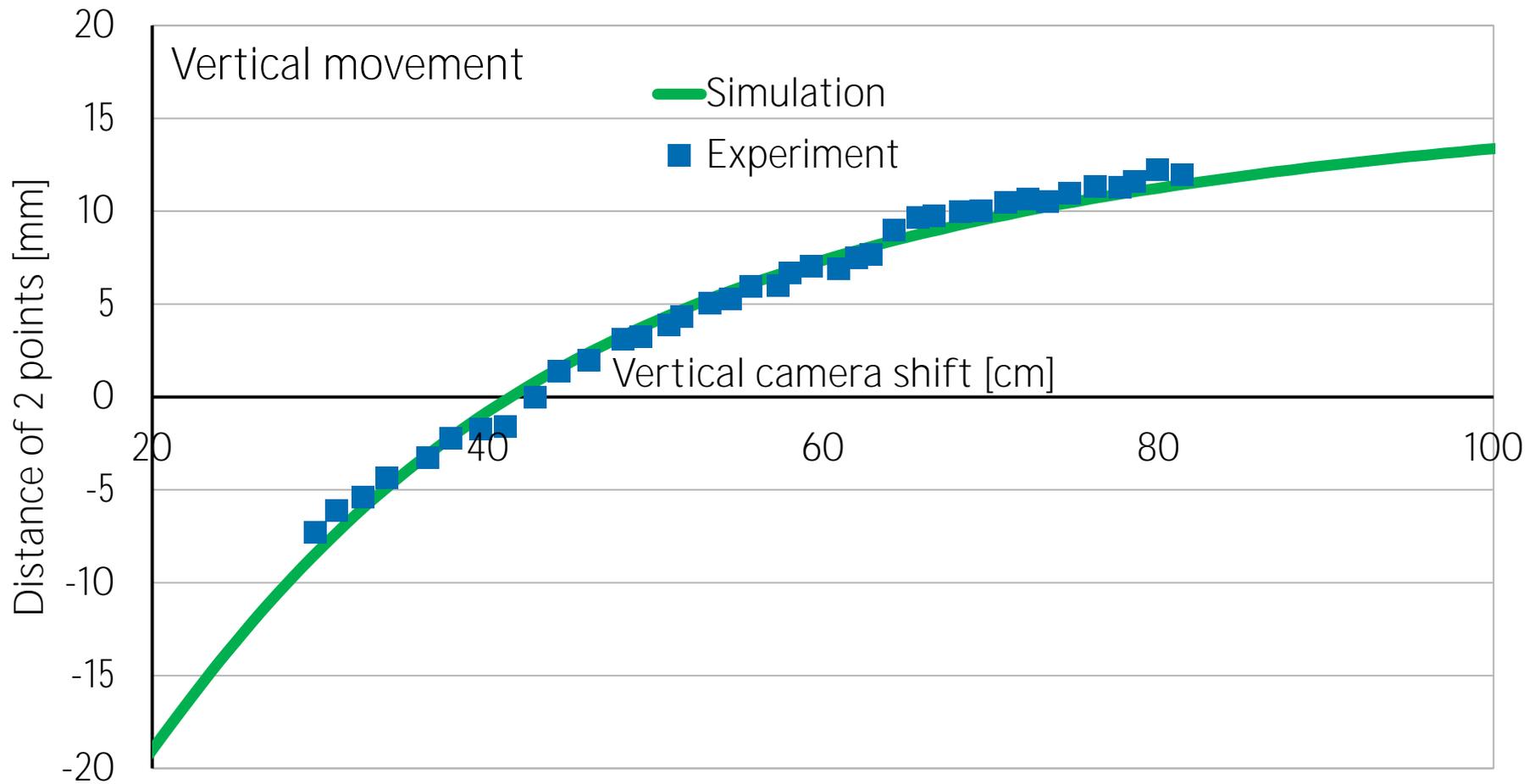


Vertical movement - simulation

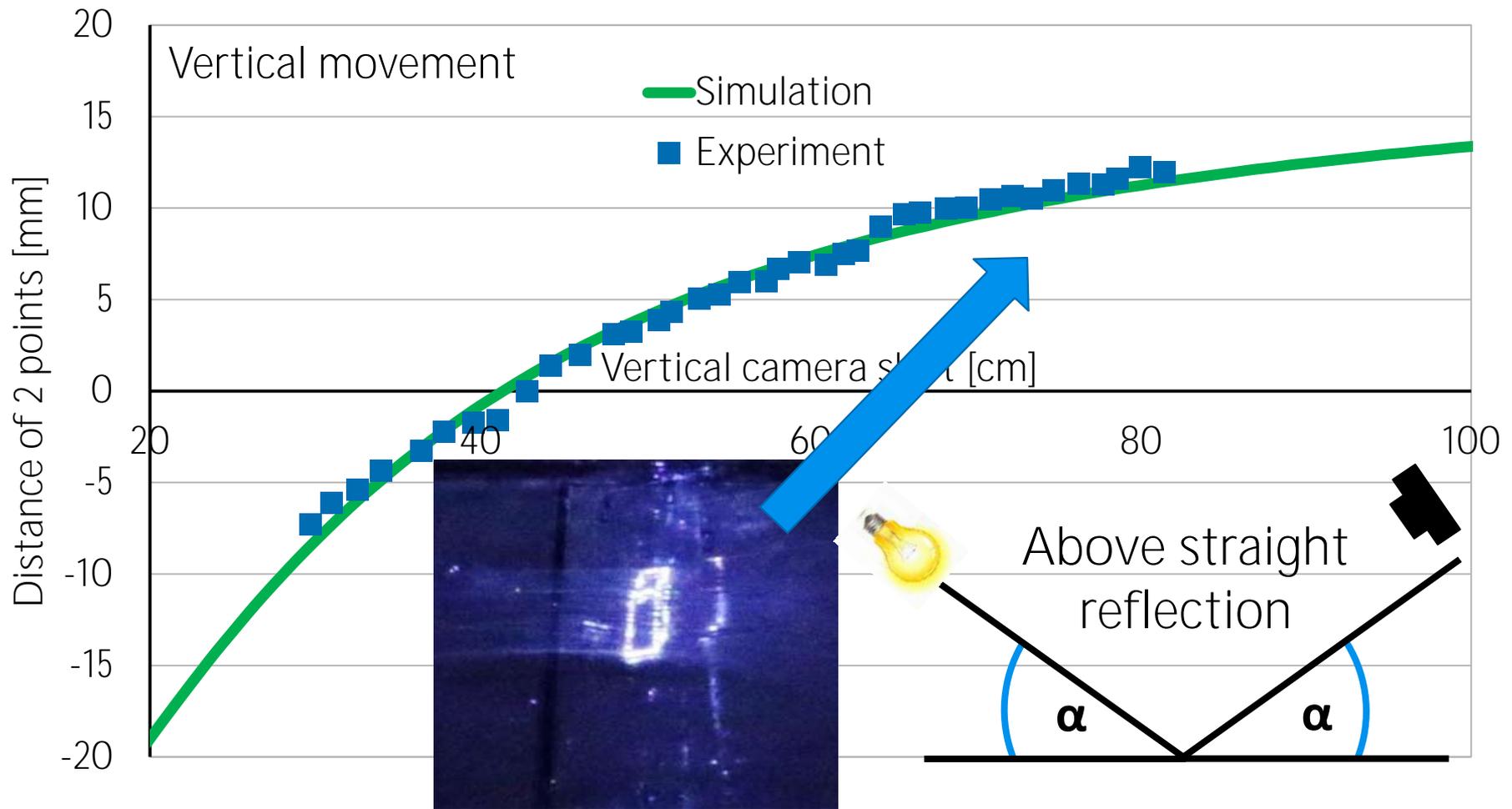




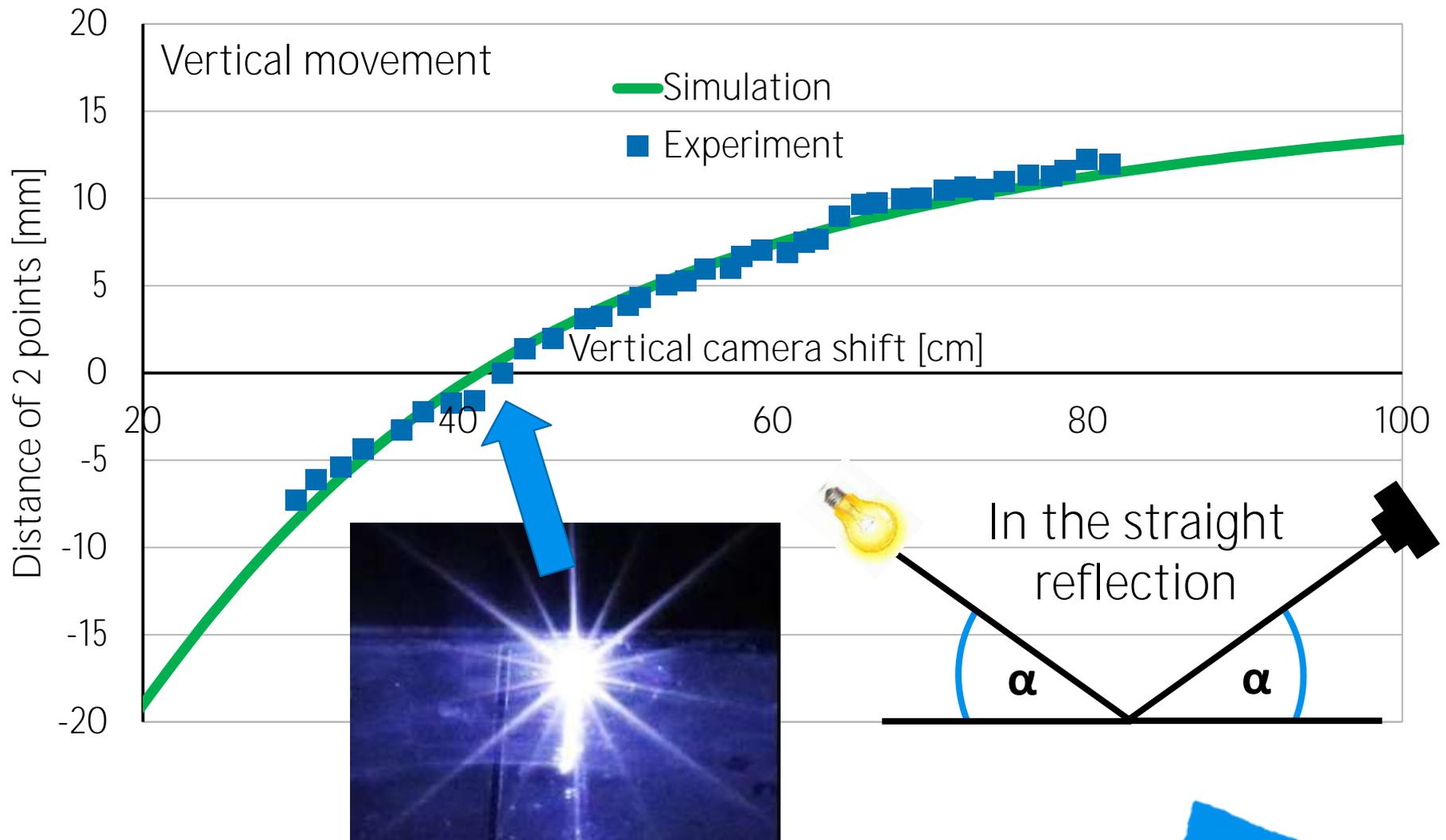
Simulation vs. experiment



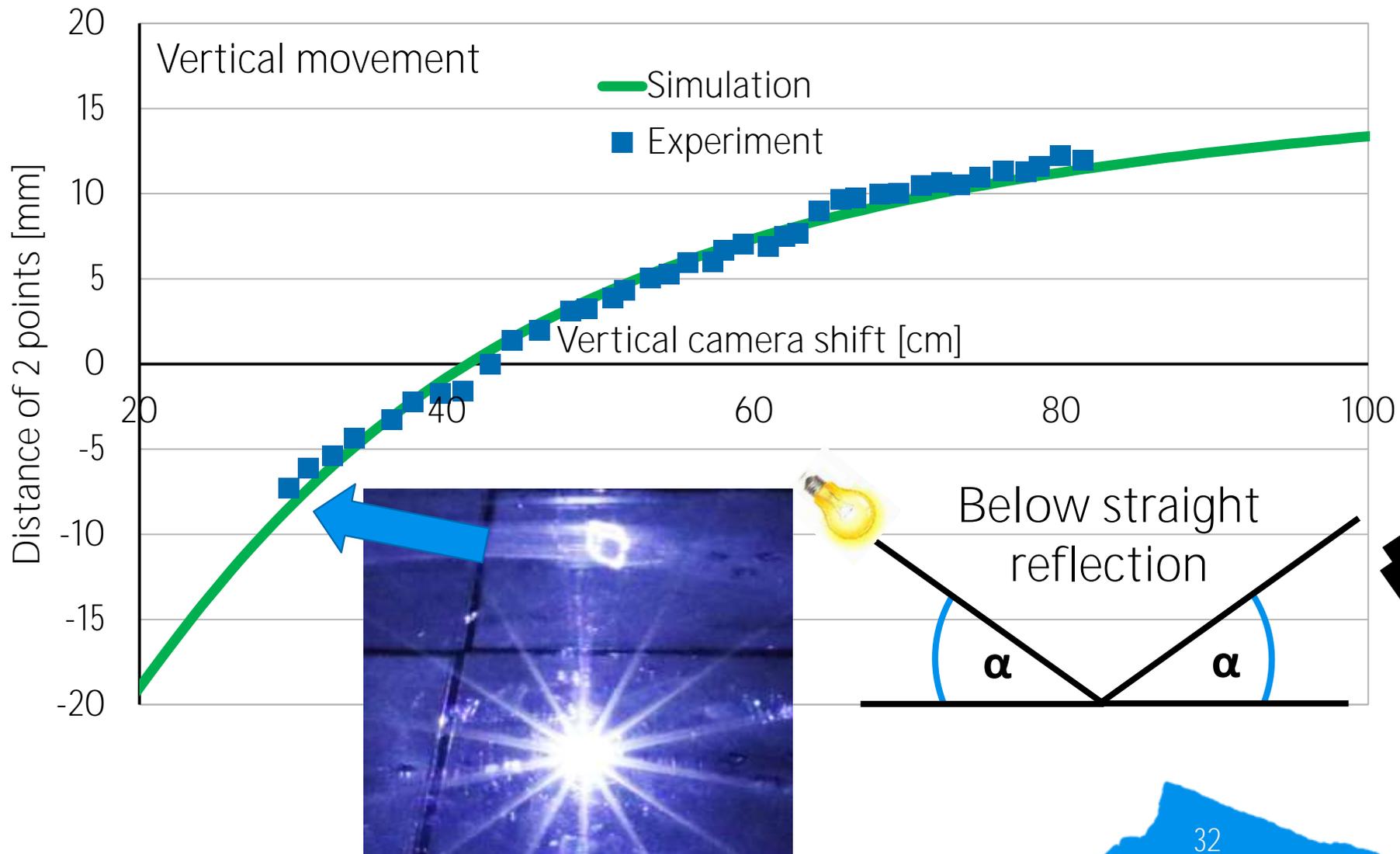
Simulation vs. experiment



Simulation vs. experiment



Simulation vs. experiment

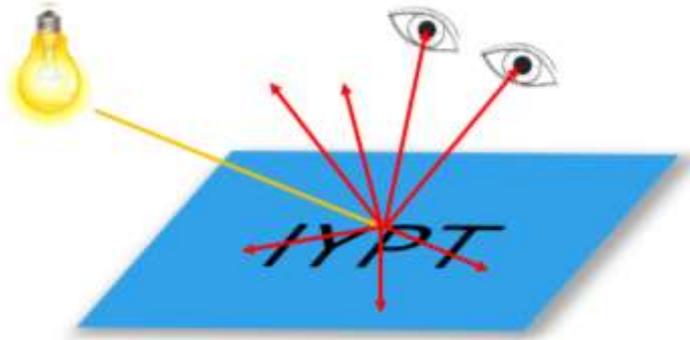




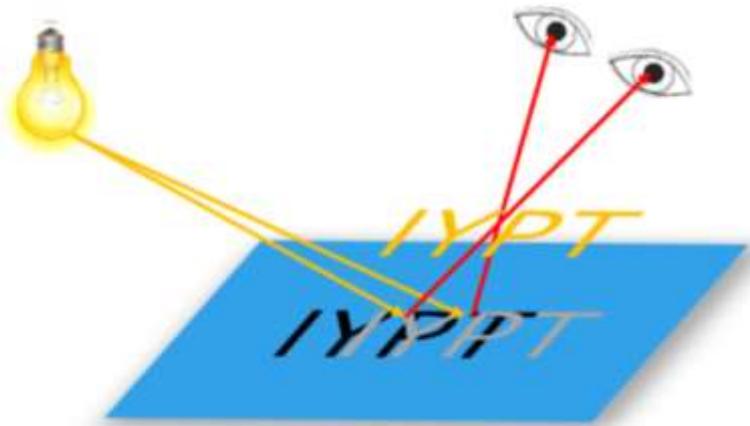
CONCLUSION

Conclusion – simple mechanism

Simple scratch = boring image

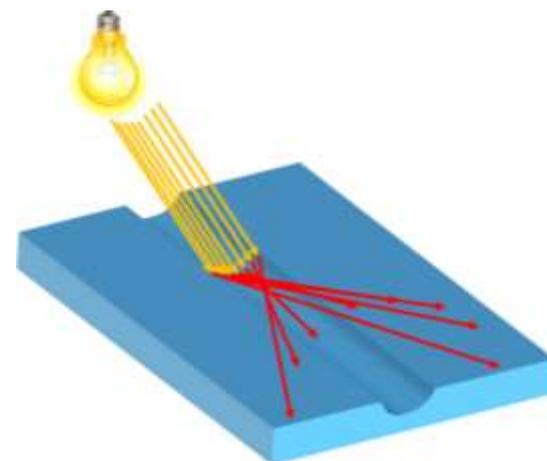
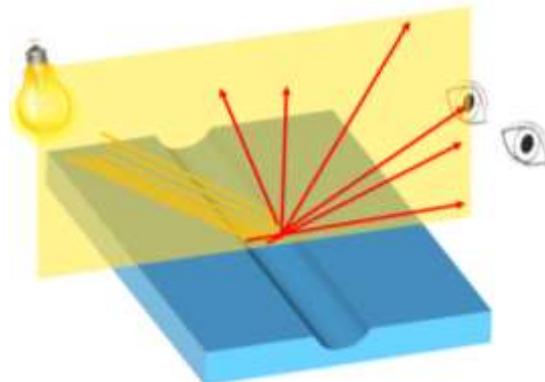


“Hologram” = image visible under/over the surface

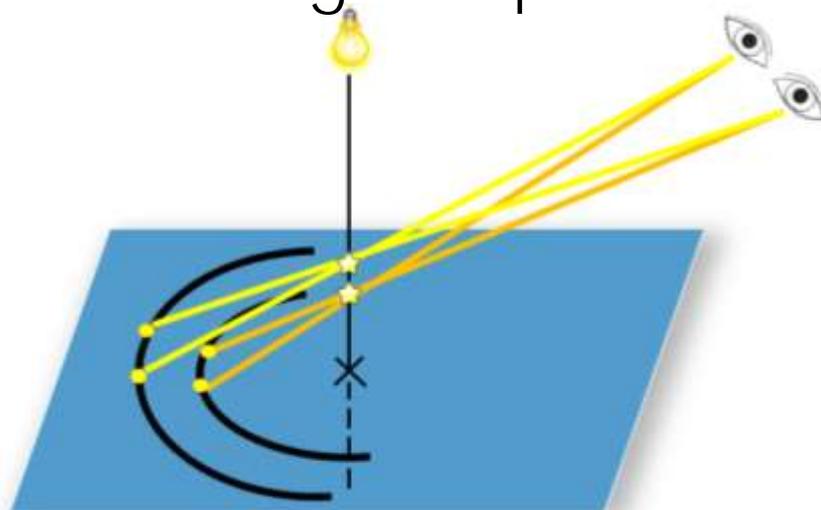


Conclusion – simple mechanism

Scratches = only part of space is lit

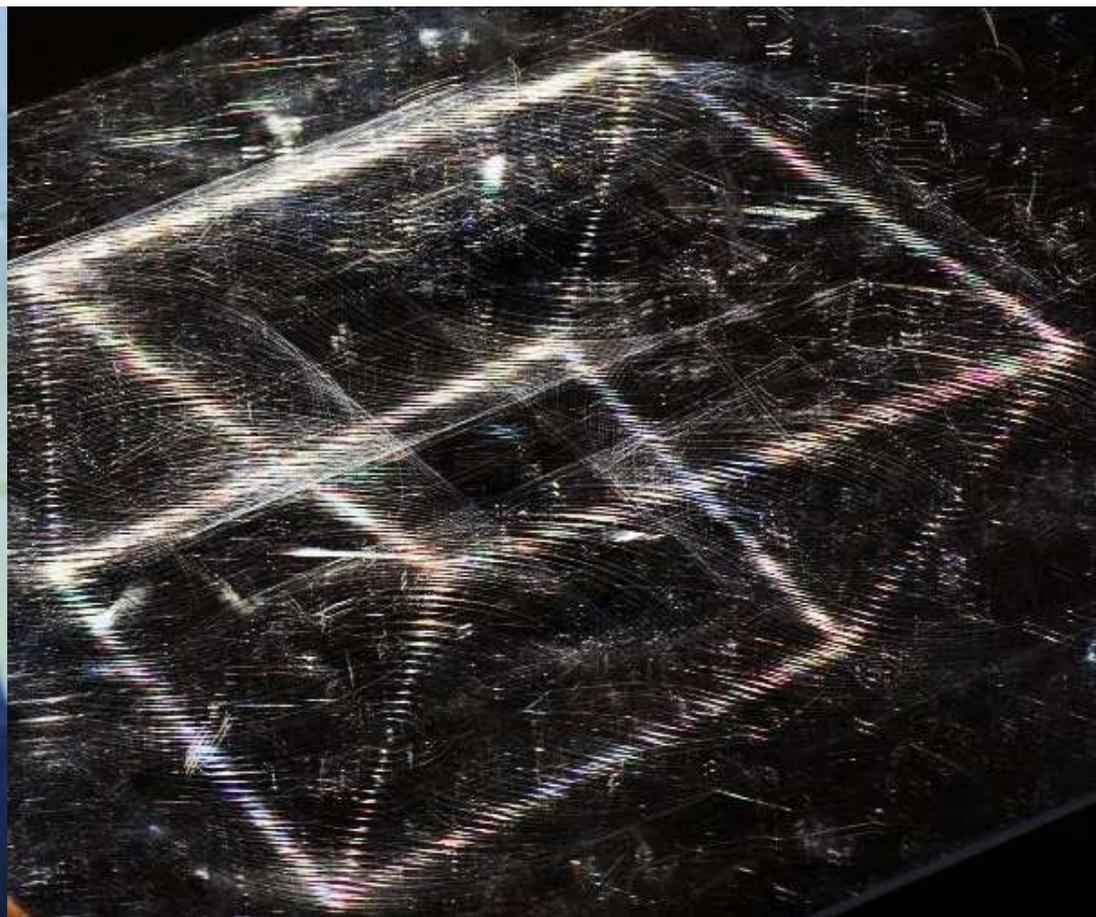


Eyes see 2 different images = points in space

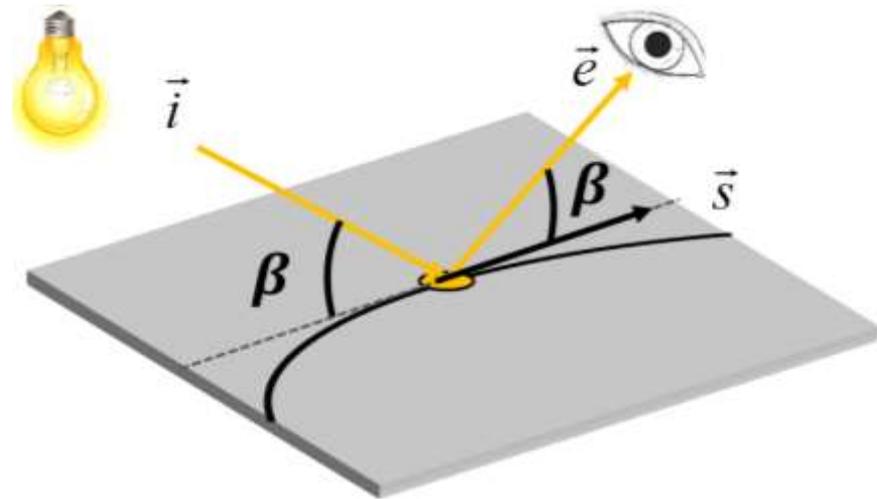
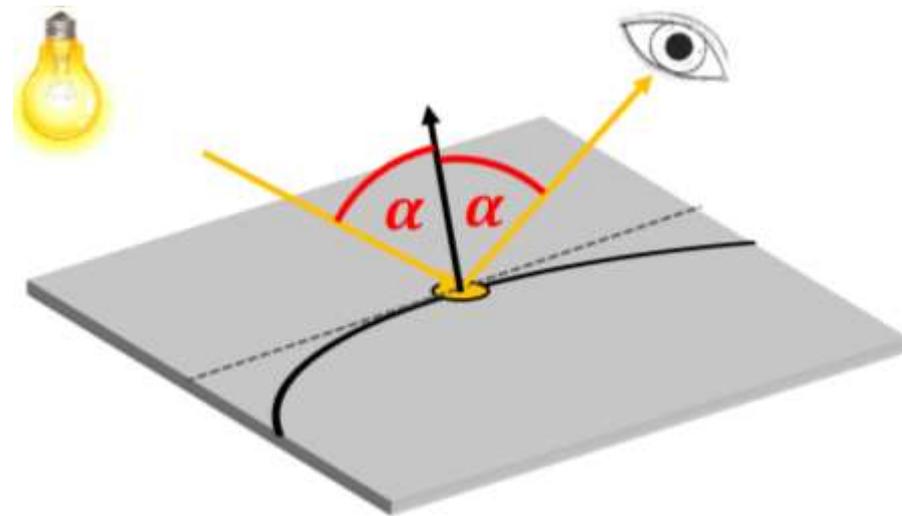


Conclusion – simple mechanism

Working 2D & 3D holograms

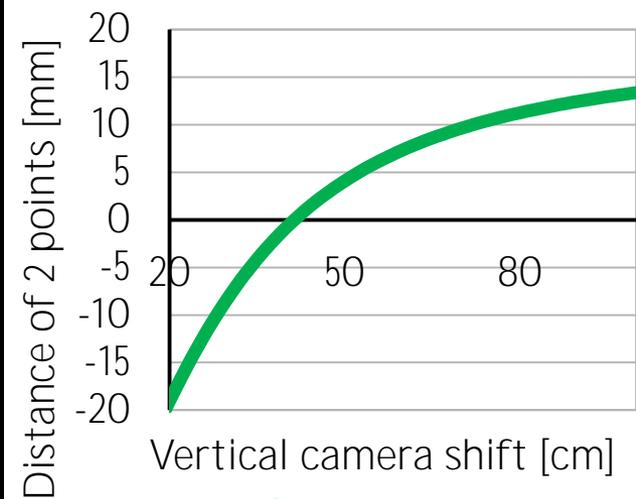
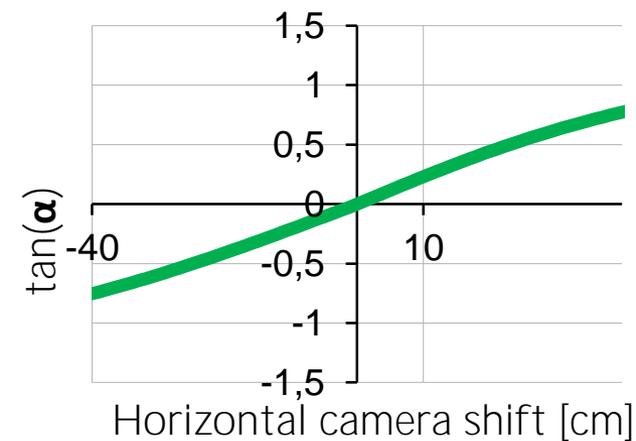
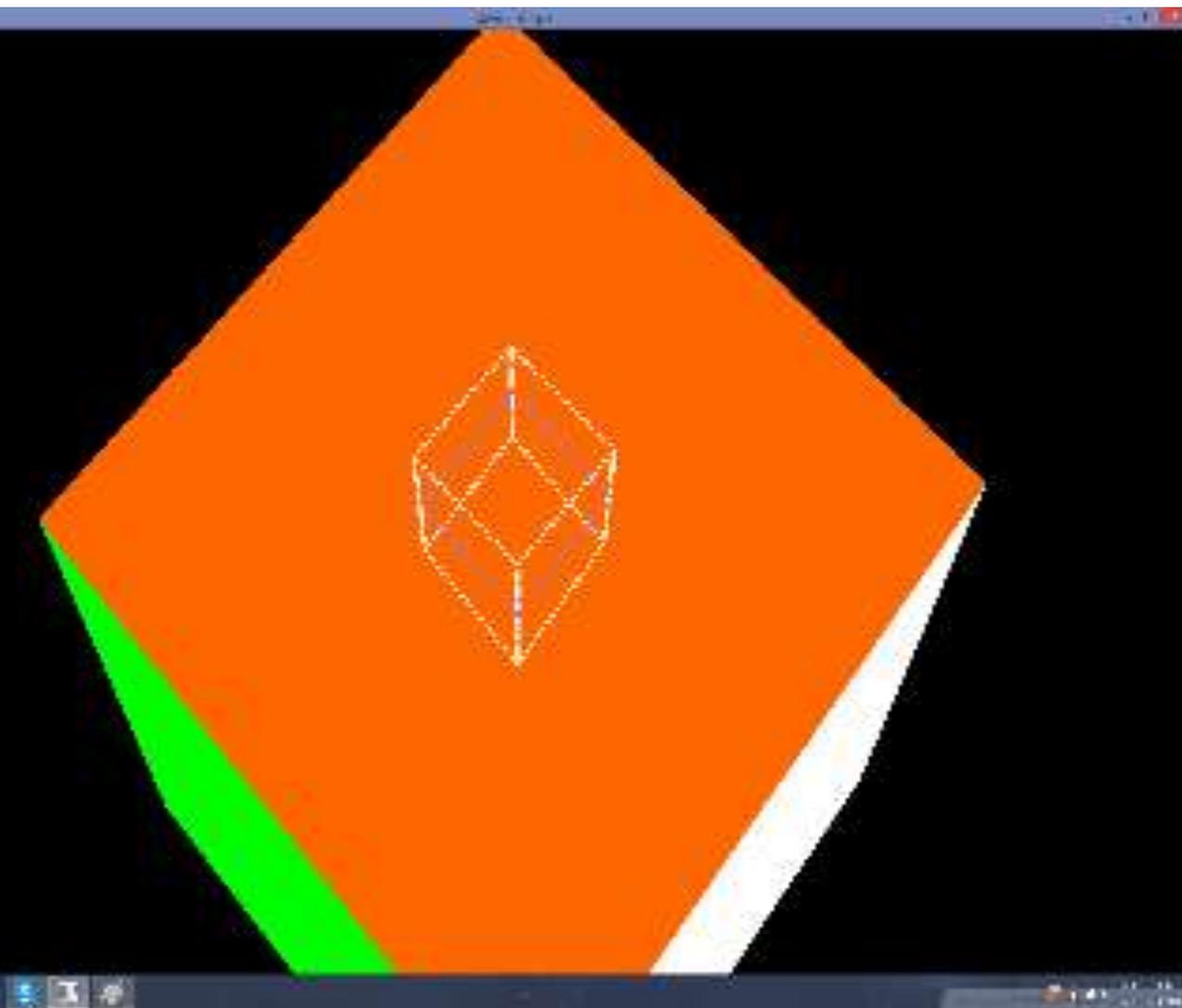


Theory = geometrical optics

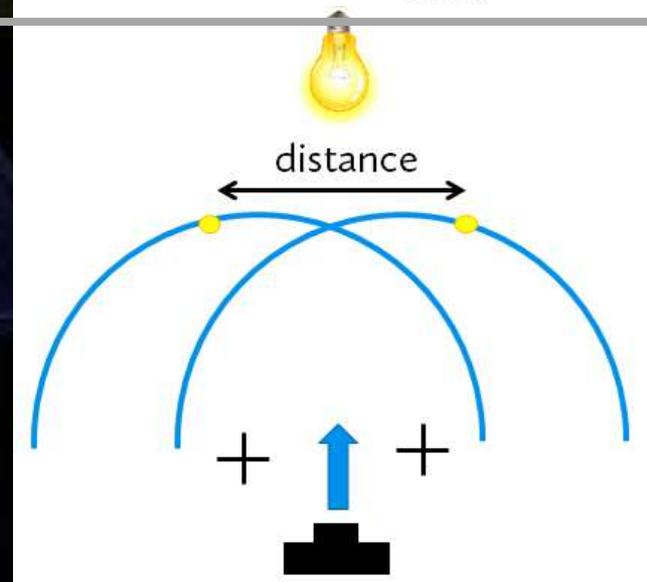
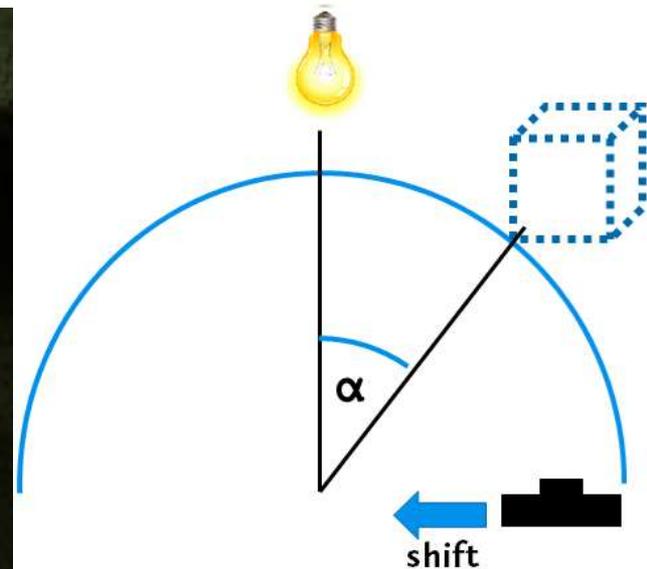


Law of reflection $\rightarrow \vec{i} \circ \vec{s} = \vec{e} \circ \vec{s}$

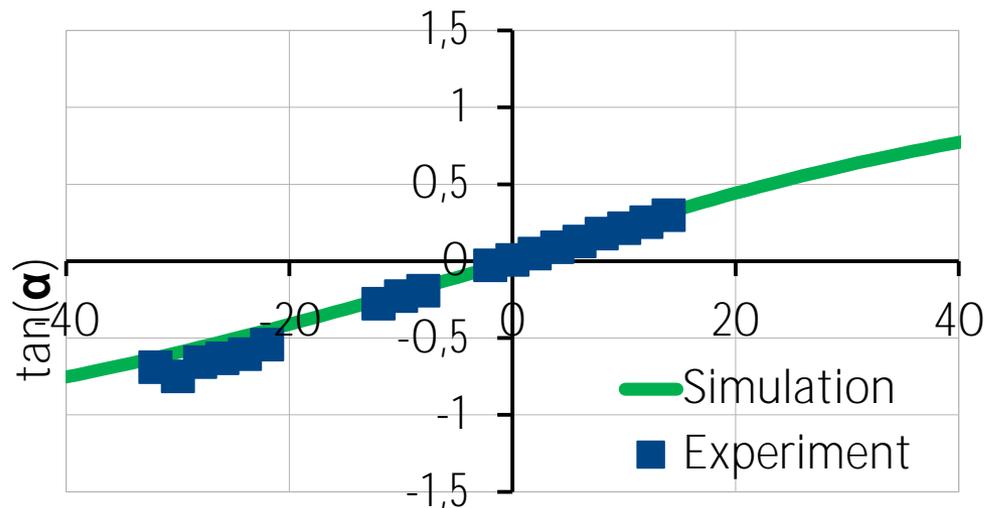
Simulation = practical use of theory



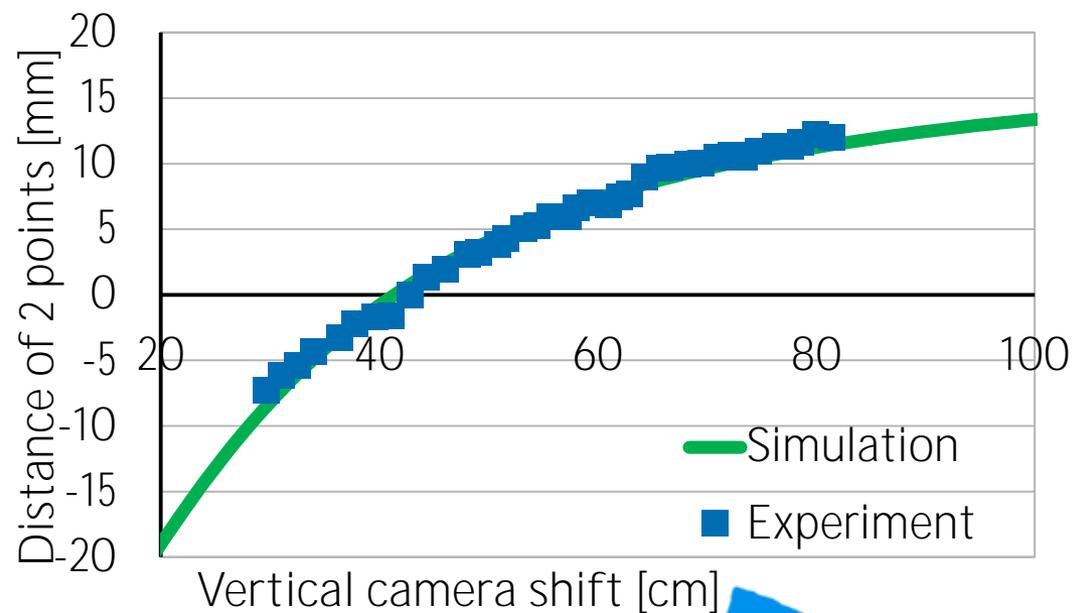
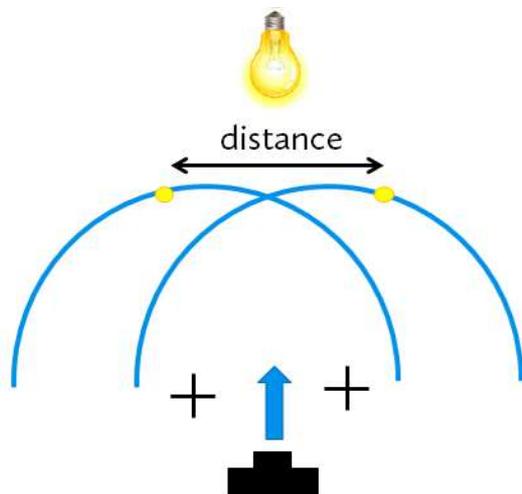
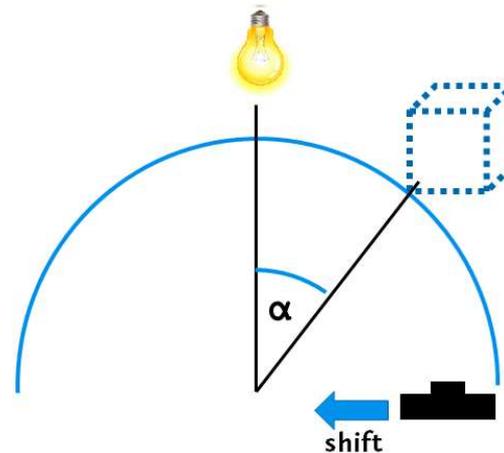
Conclusion - Experiments



Experimental verification of theory



Horizontal camera shift [cm]



Vertical camera shift [cm]

Thank you for your attention

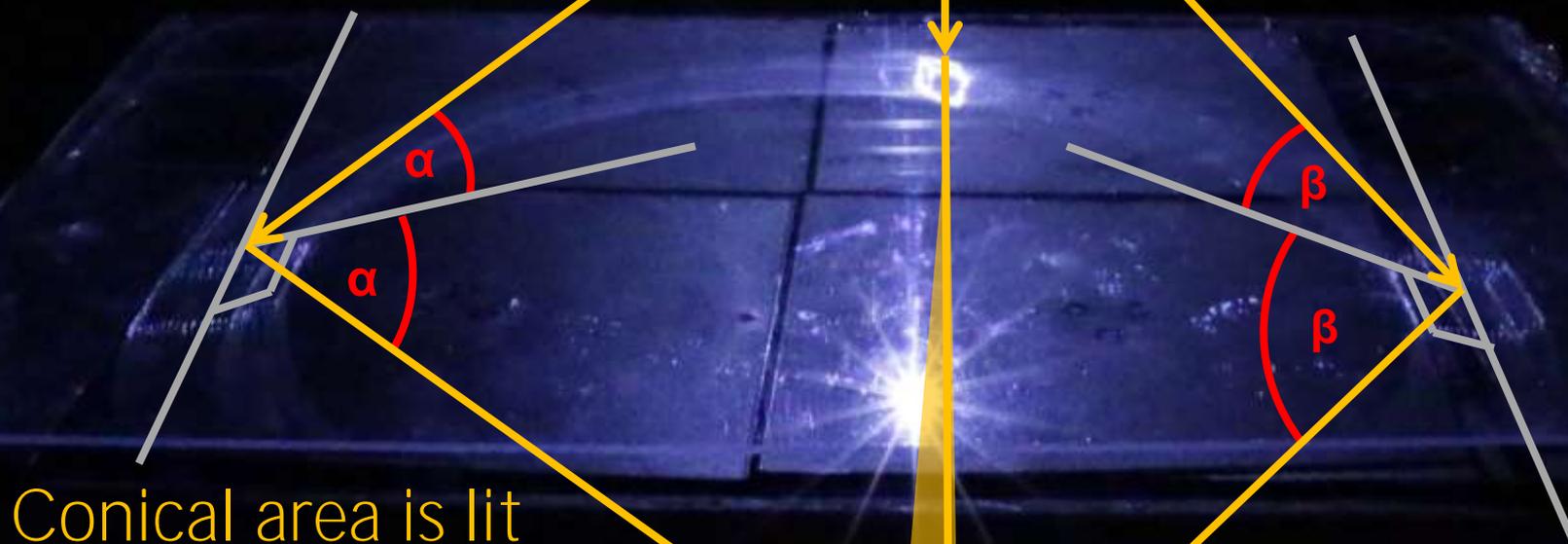




APPENDICES

More than 1 image visible?

Perpendicular reflection = Whole plane is lit

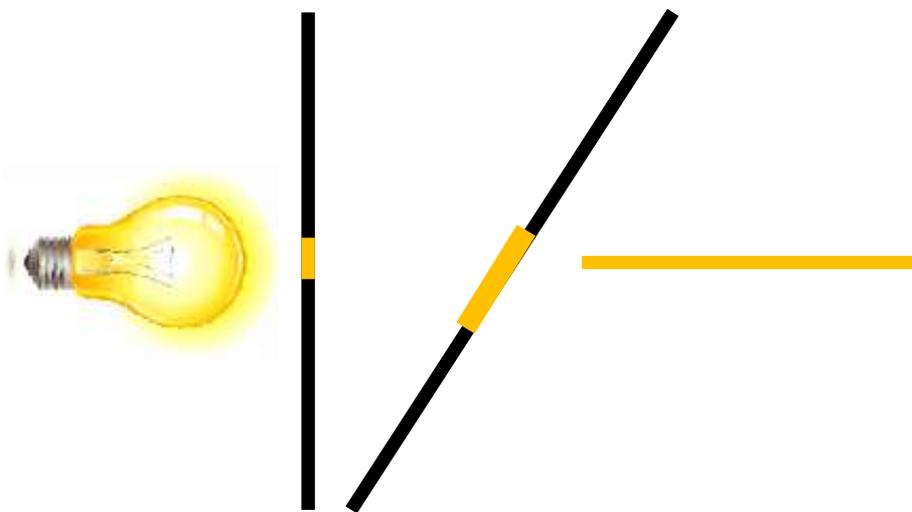


more points on circle may reflect light

Circular scratch

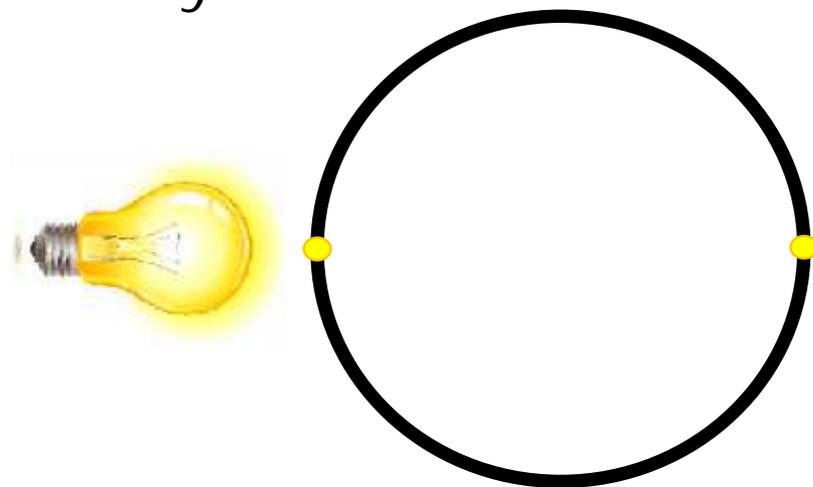
Line

- Line segments visible



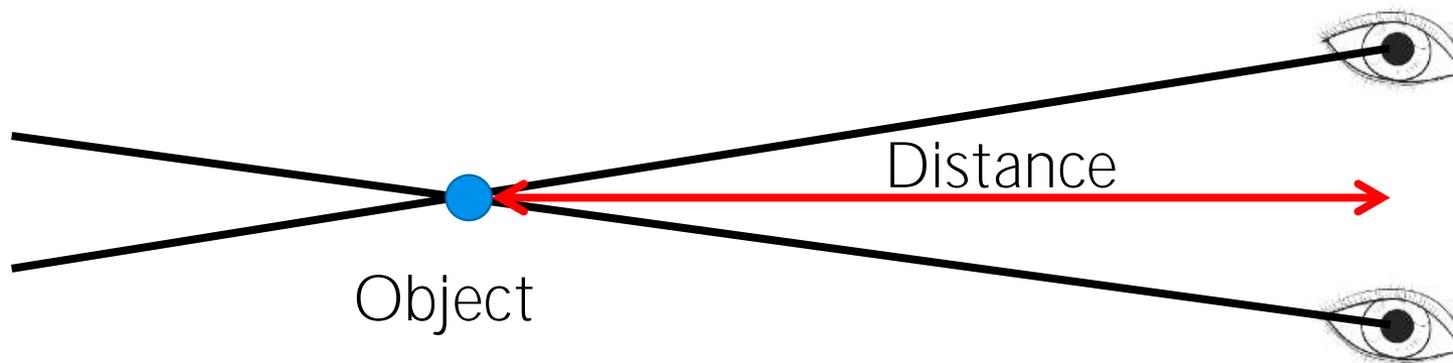
Circle

- Small segments
always visible





Human 3D vision mechanism



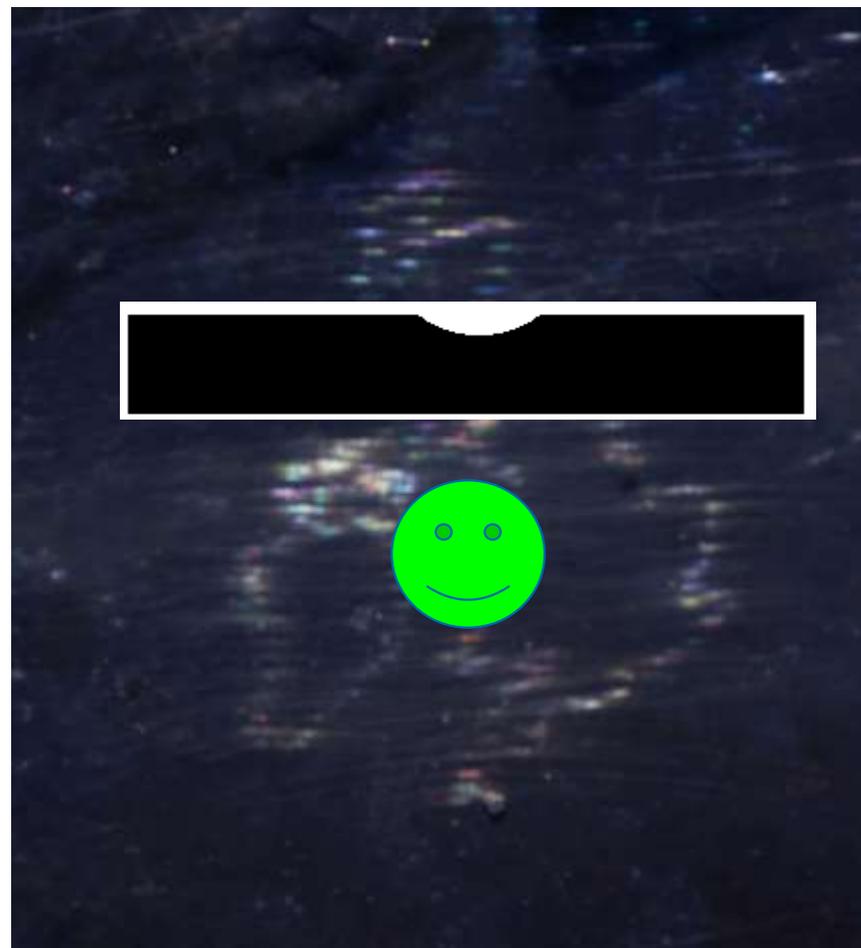
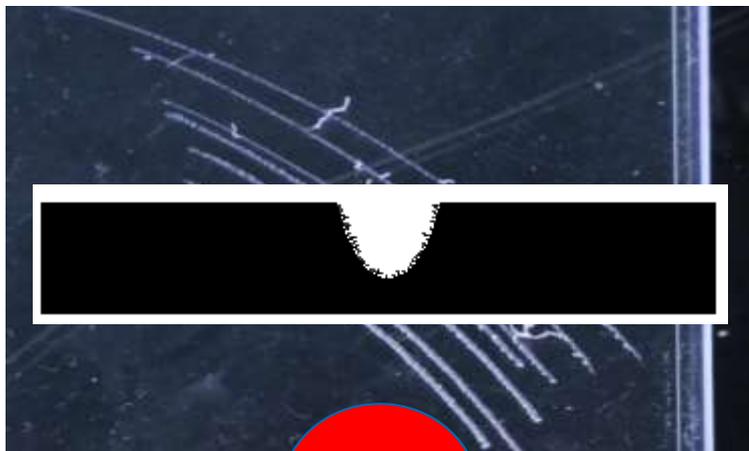


Position of shining point on circle

$$\tan \alpha = -\frac{(x_{light} - x_{point})D_{eye} - (x_{eye} - x_{point})D_{light}}{(y_{light} - y_{point})D_{eye} - (y_{eye} - y_{point})D_{light}}$$



Scratch on the plastic



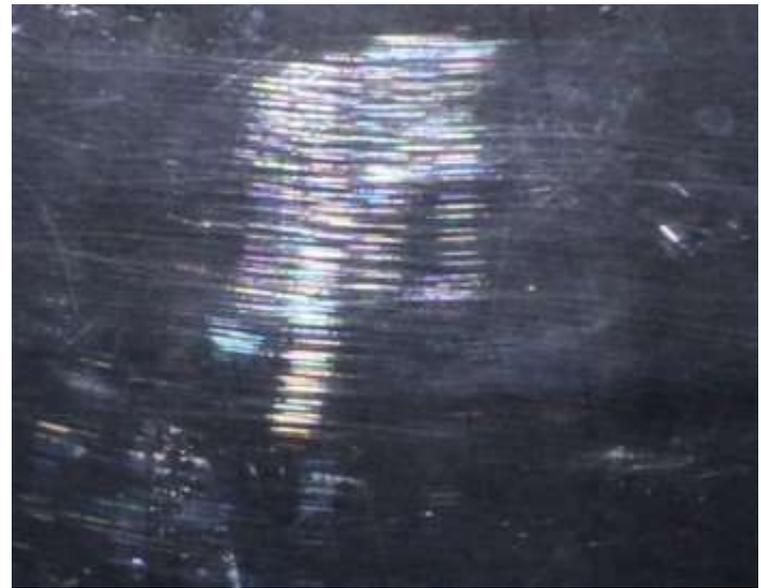
Radius of the circle scratch

We see section of a circle \rightarrow **radius** \propto length of the shining part

Small radius 13cm



Large radius 30cm



Distance vs. radius

Distance is proportional to radius



We can create straight
line through space

