



Russia IYPT

Moving brush

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A brush may start moving when placed on a vibrating horizontal surface. Investigate the motion.

First observations

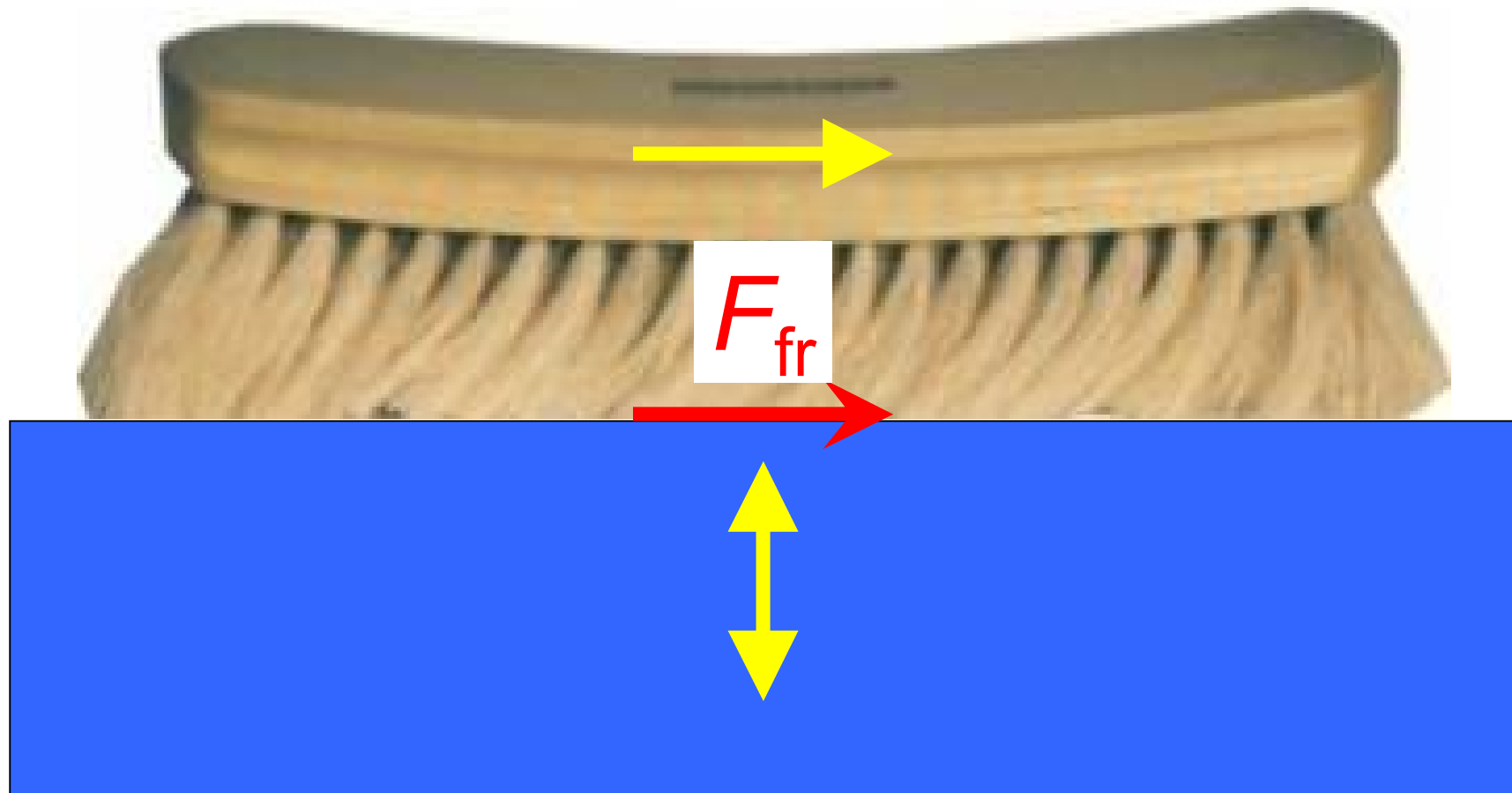
Simple brush (240 fps)

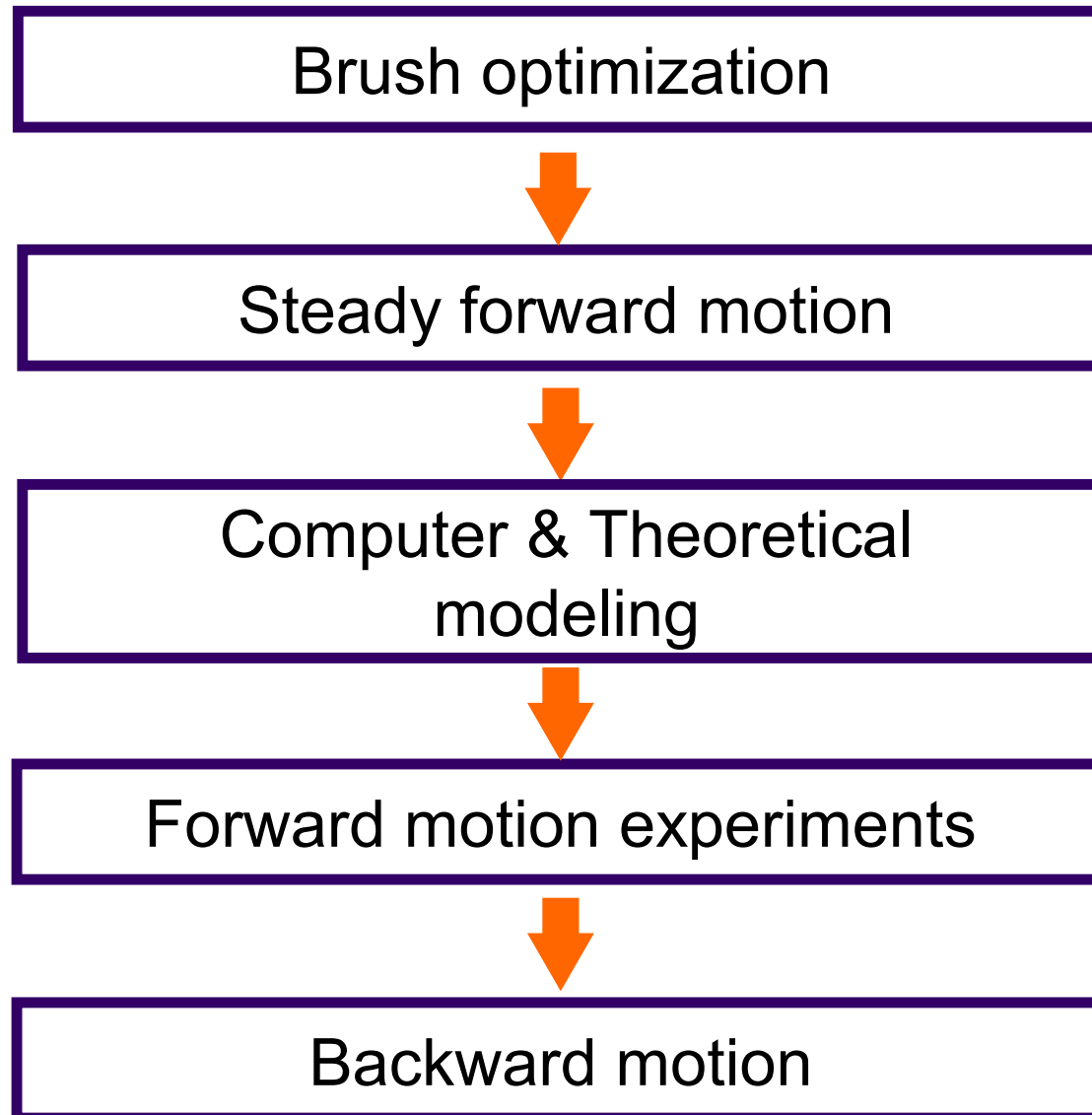
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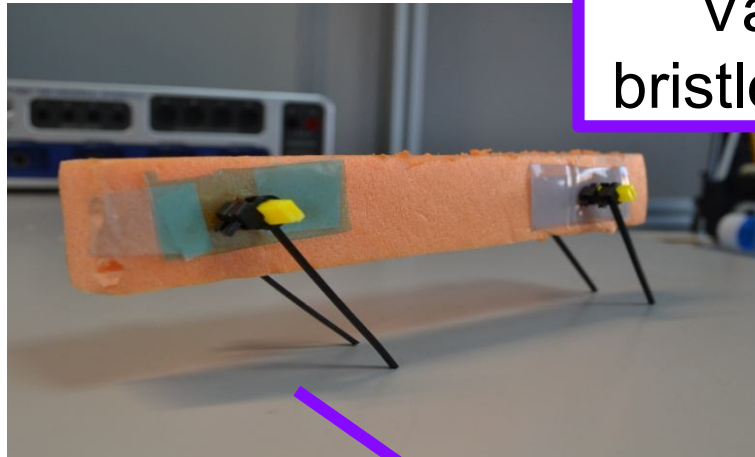
Conversion of vibration into motion

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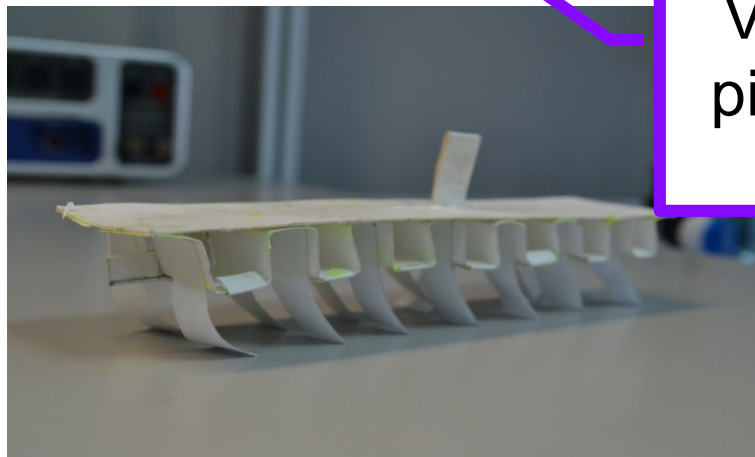
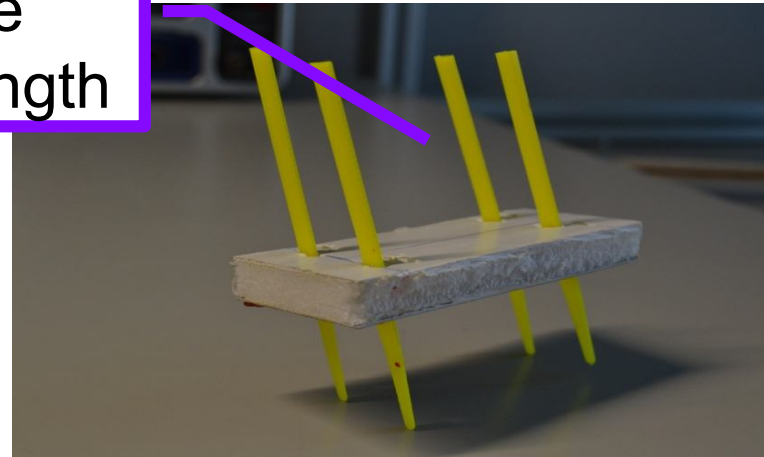




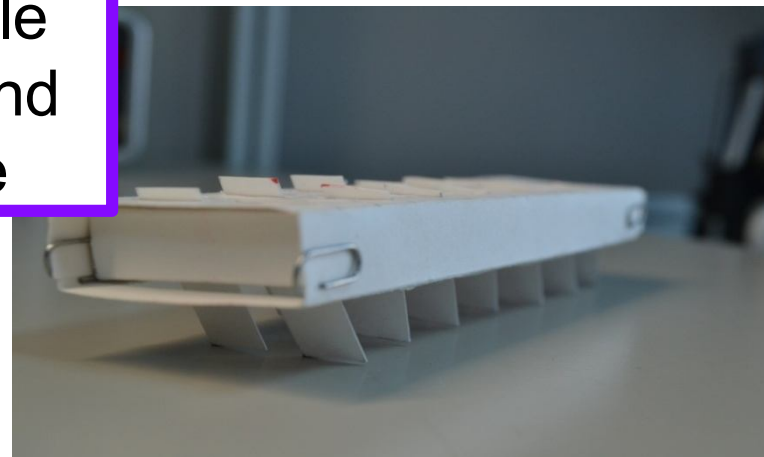
Optimized brush construction

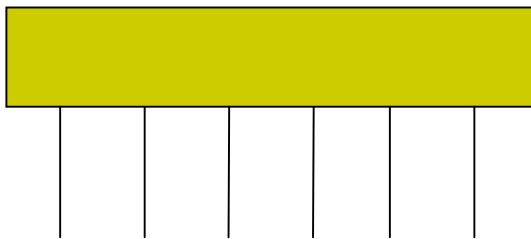


Variable
bristles' length

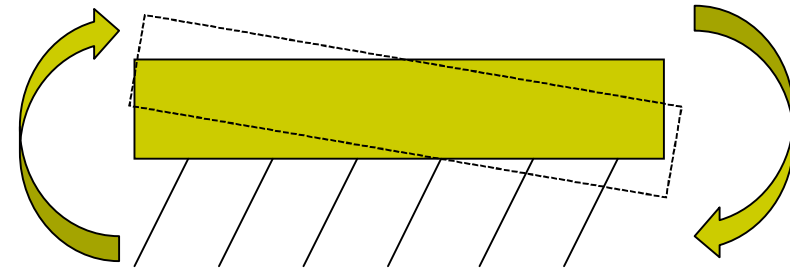


Variable
pitch and
angle





No preferred bristles' direction
Chaotic motion
Unstable construction

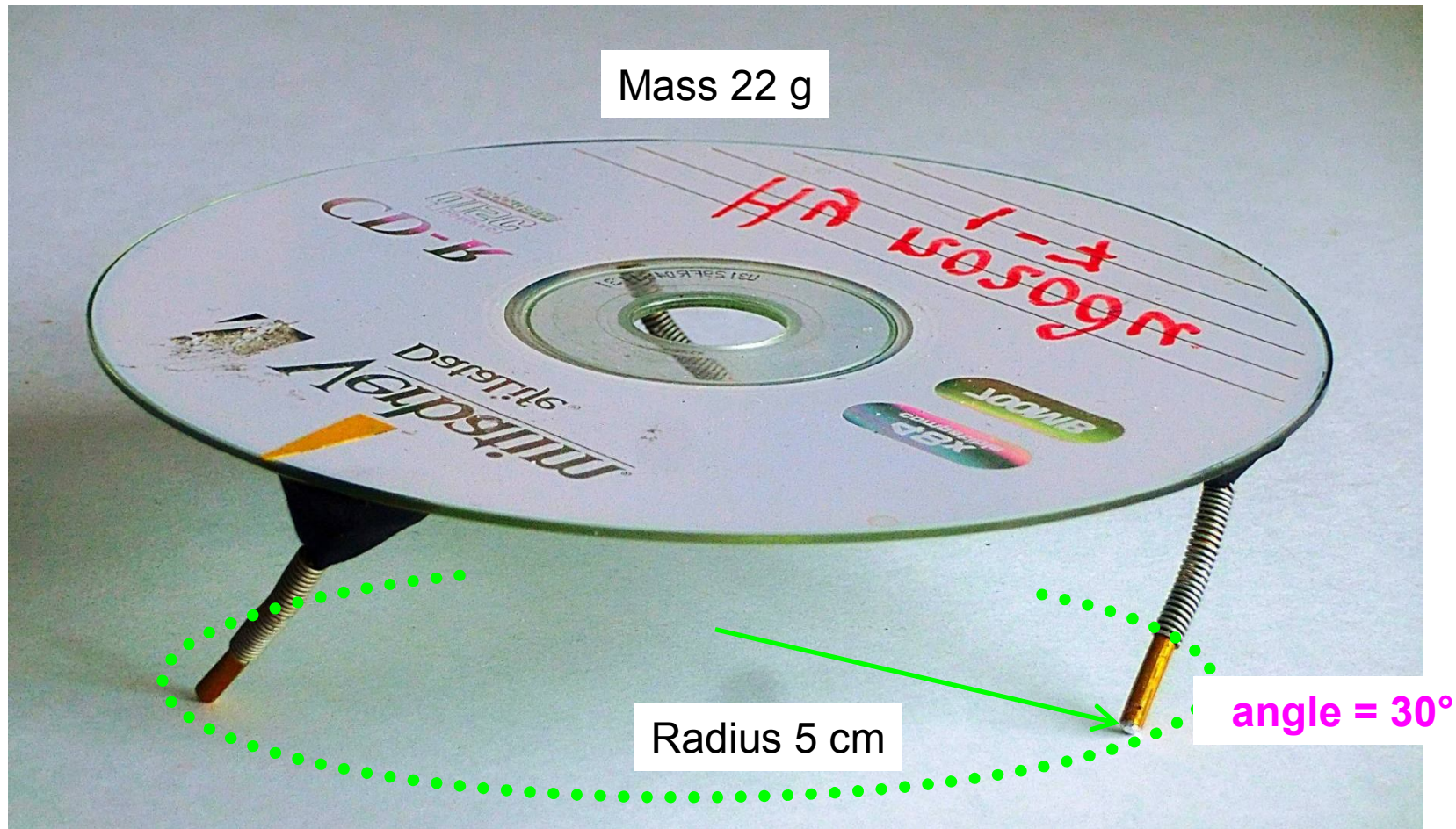


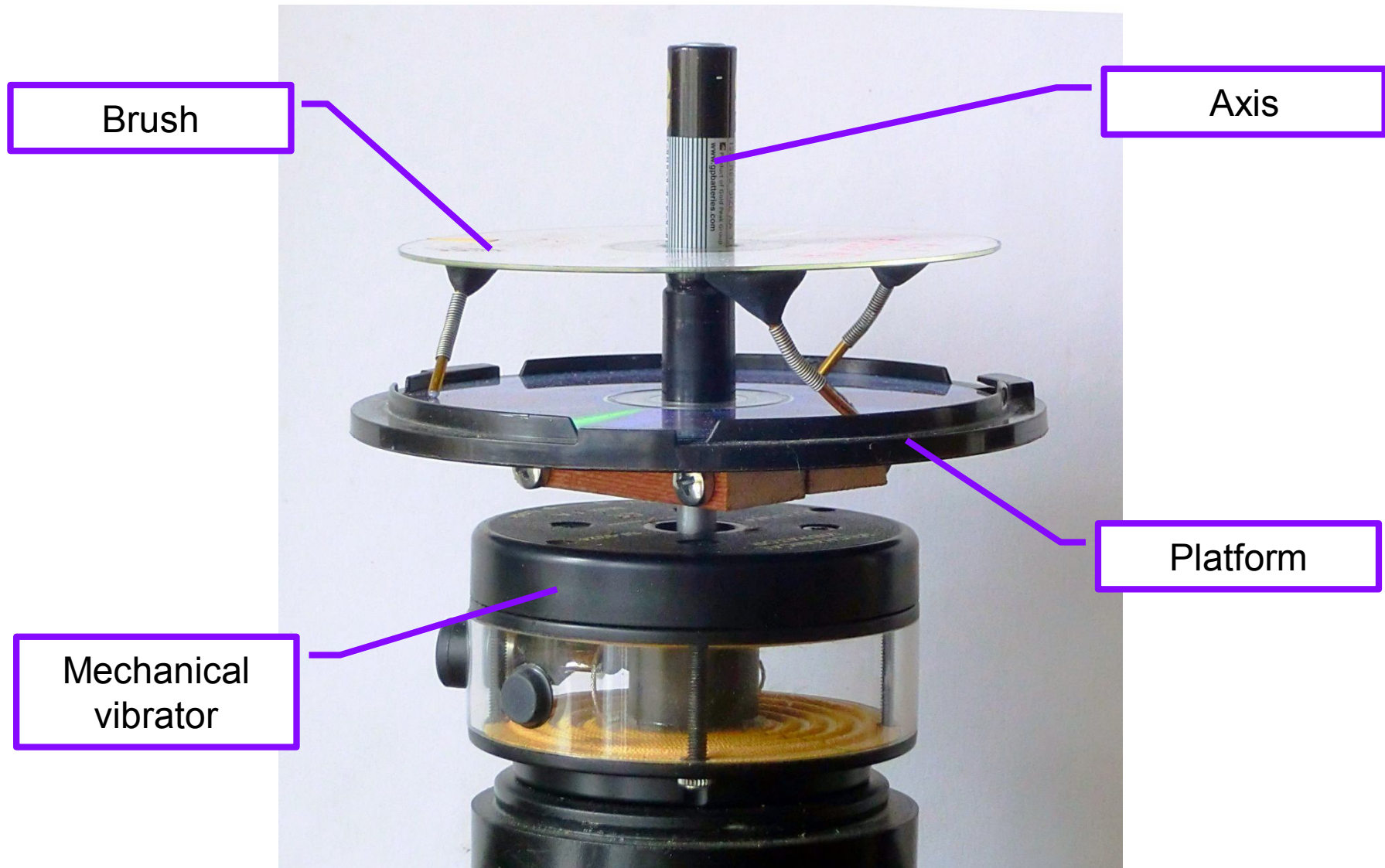
Non-uniform load distribution
Strong pitching
Not identical bristles

Experimental setup

Tripod rotating brush

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Starting of forward motion



Frequency 40 Hz

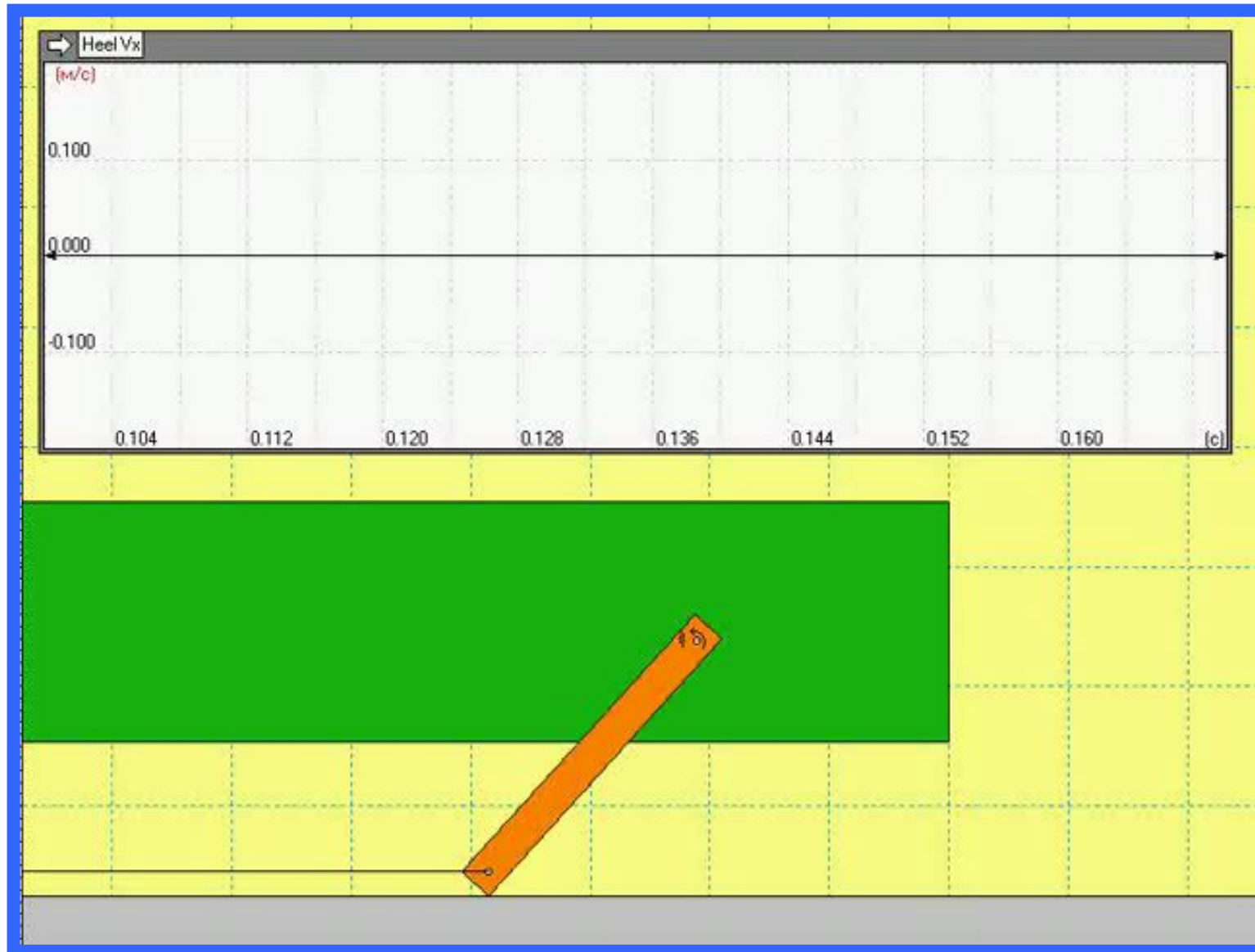
Vertical motion of the brush is negligible

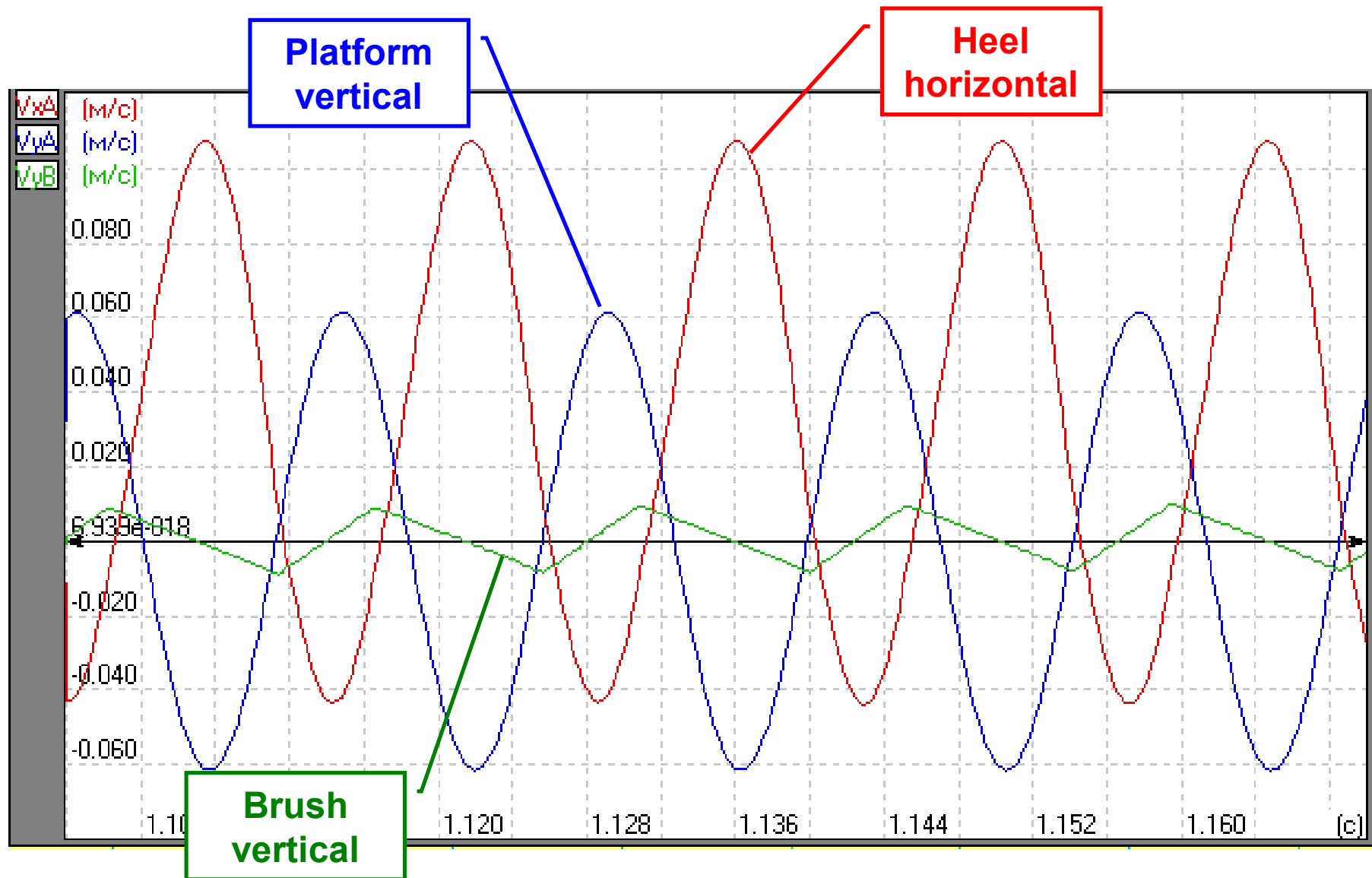
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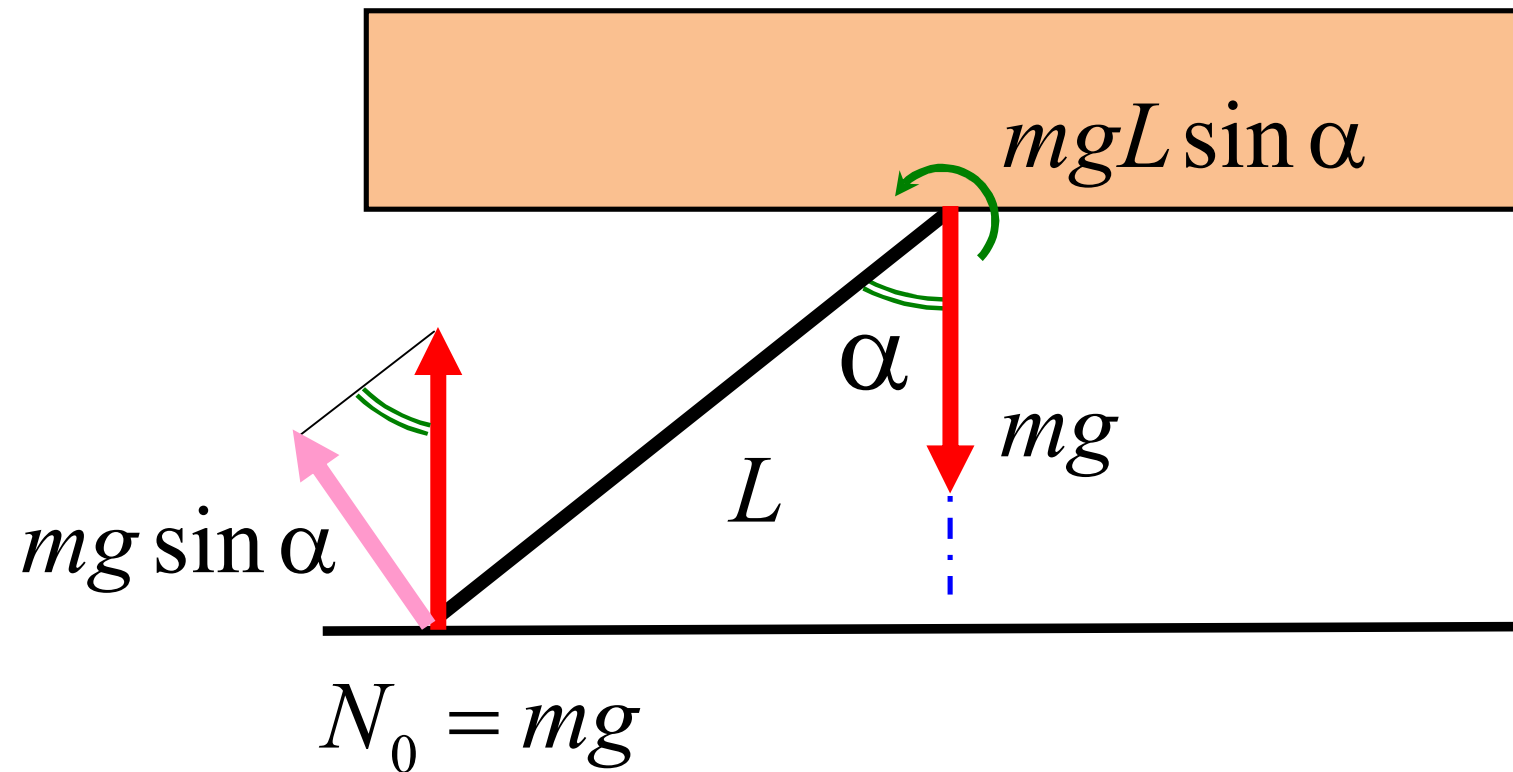
Permanent heel slippage

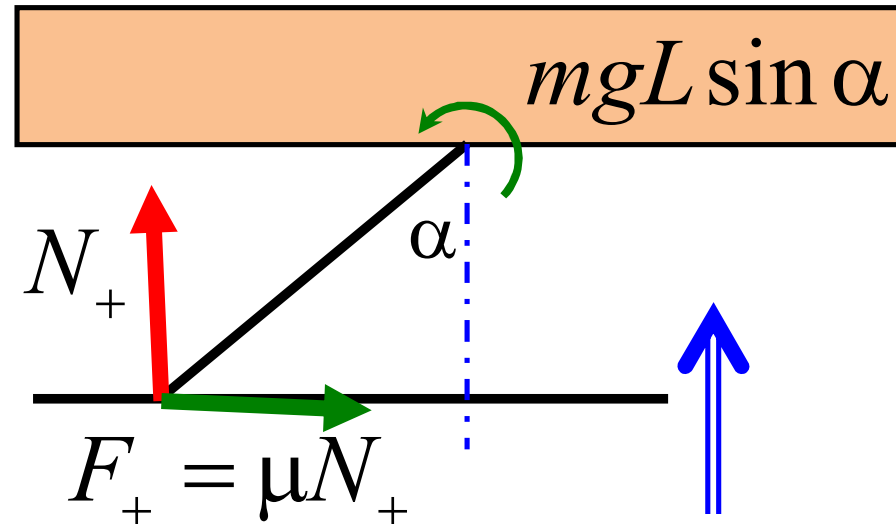
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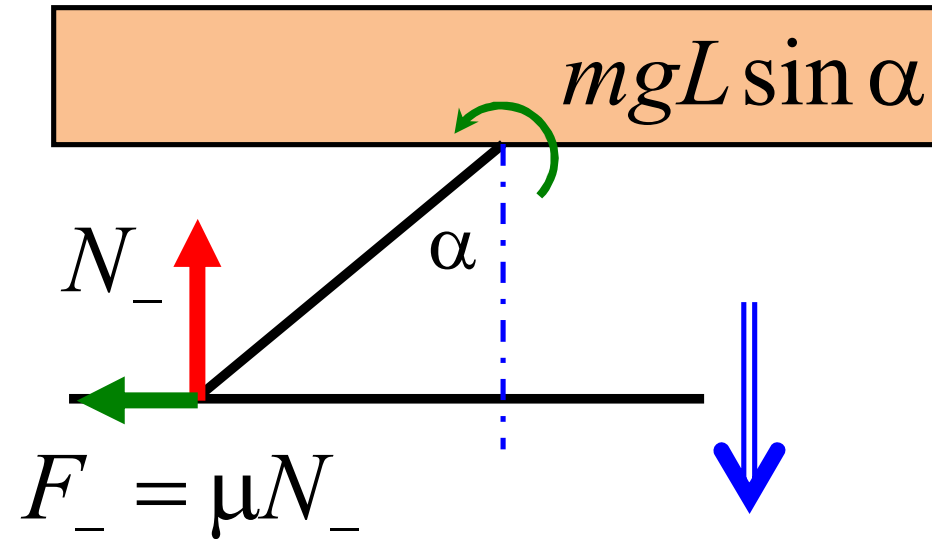
Theoretical model





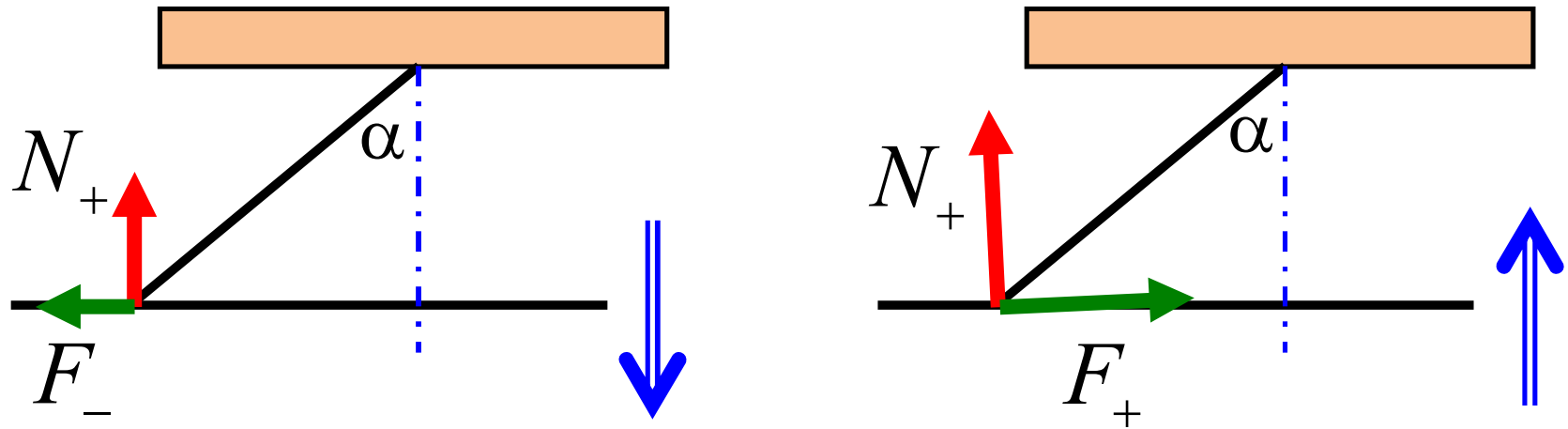
$$(N_+ \sin \alpha - F_+ \cos \alpha)L = mgL \sin \alpha$$

$$F_+ = \frac{\mu \cdot mg}{1 - \mu \operatorname{ctg} \alpha}$$



$$(N_- \sin \alpha + F_- \cos \alpha)L = mgL \sin \alpha$$

$$F_- = \frac{\mu \cdot mg}{1 + \mu \operatorname{ctg} \alpha}$$

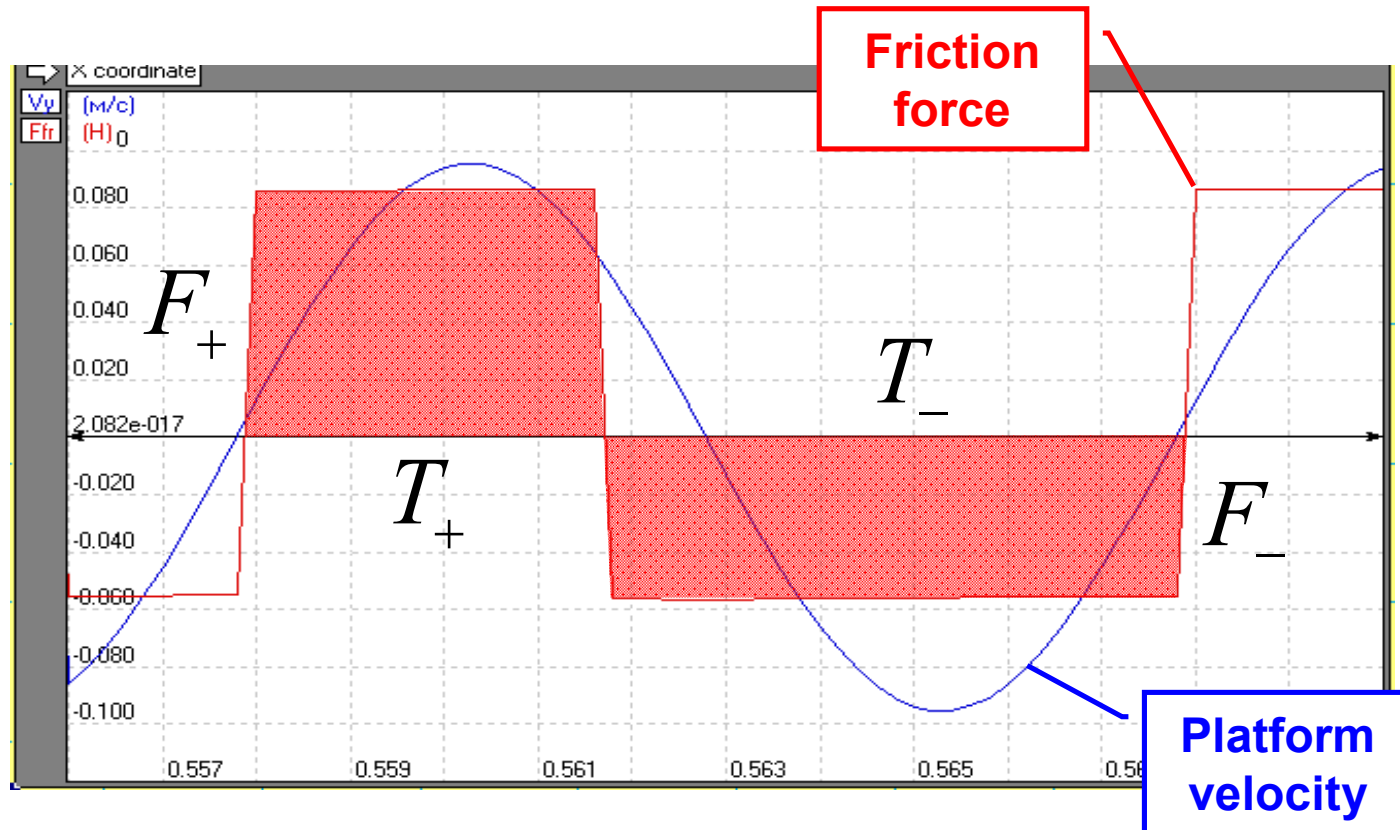


$$F_- = \frac{\mu \cdot mg}{1 + \mu \operatorname{ctg} \alpha} < F_+ = \frac{\mu \cdot mg}{1 - \mu \operatorname{ctg} \alpha}$$

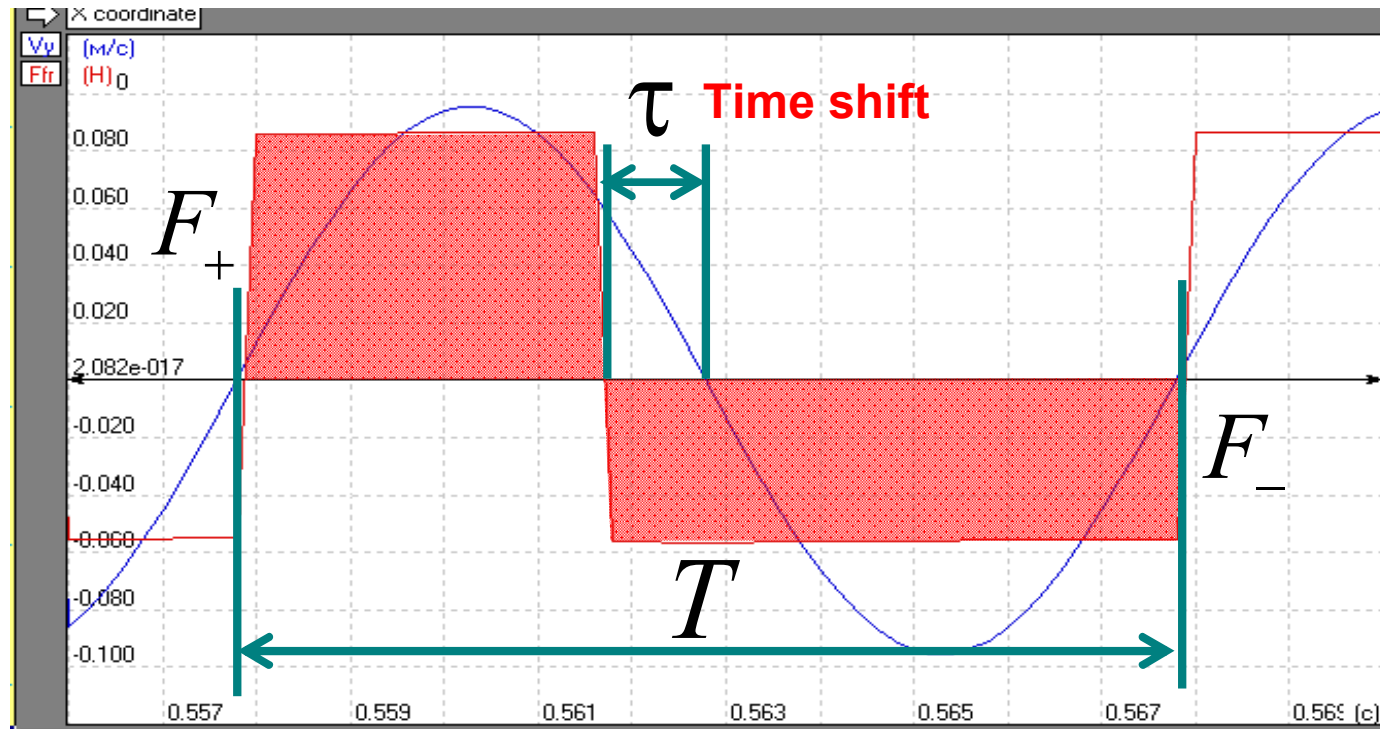
F_+ defines the direction of motion

- Difference between F_- and F_+ causes a brush's acceleration.
- Experimental results are in contradiction with theory – the brush moves with **constant speed!**

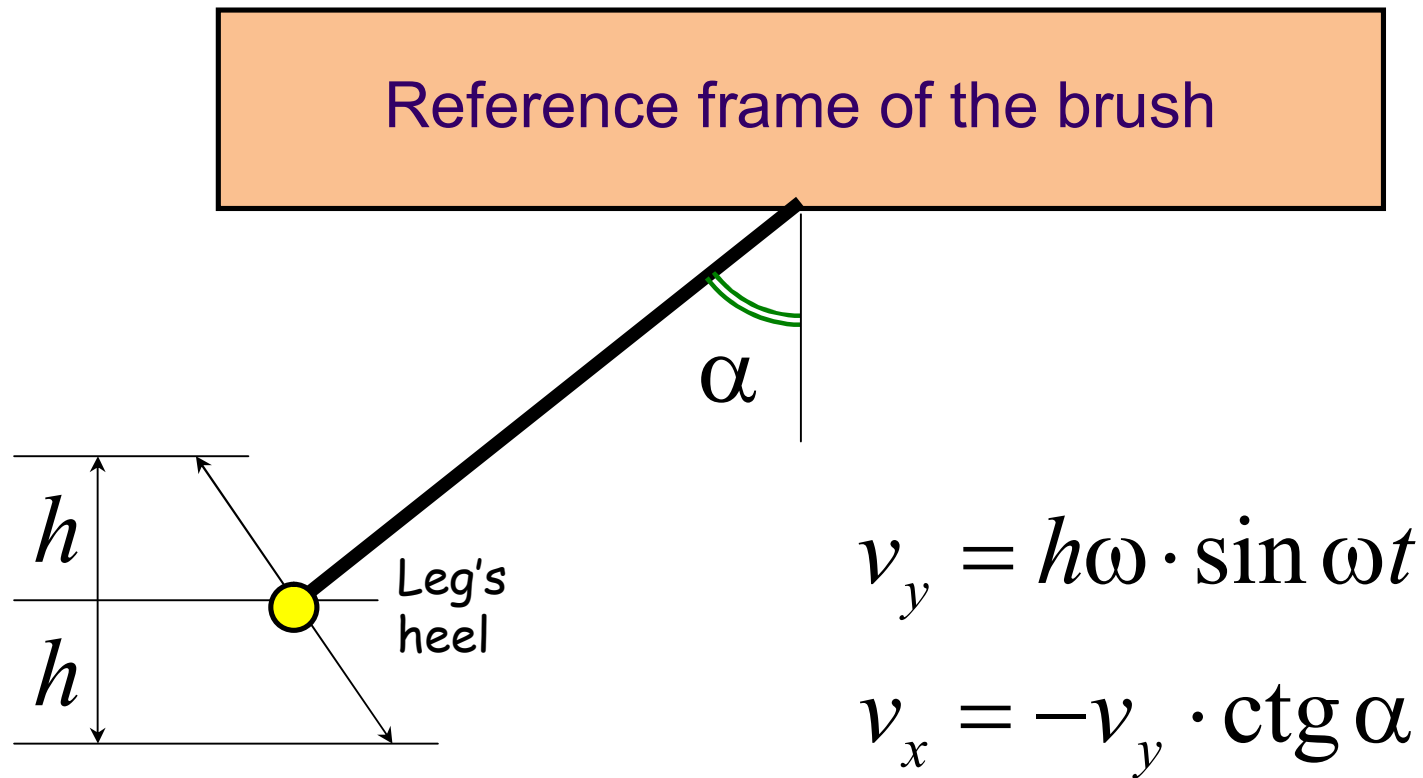
$$\vec{F} = \frac{d\vec{p}}{dt} = 0 \quad \Rightarrow \quad F_+ \cdot \Delta t_1 = F_- \cdot \Delta t_2$$

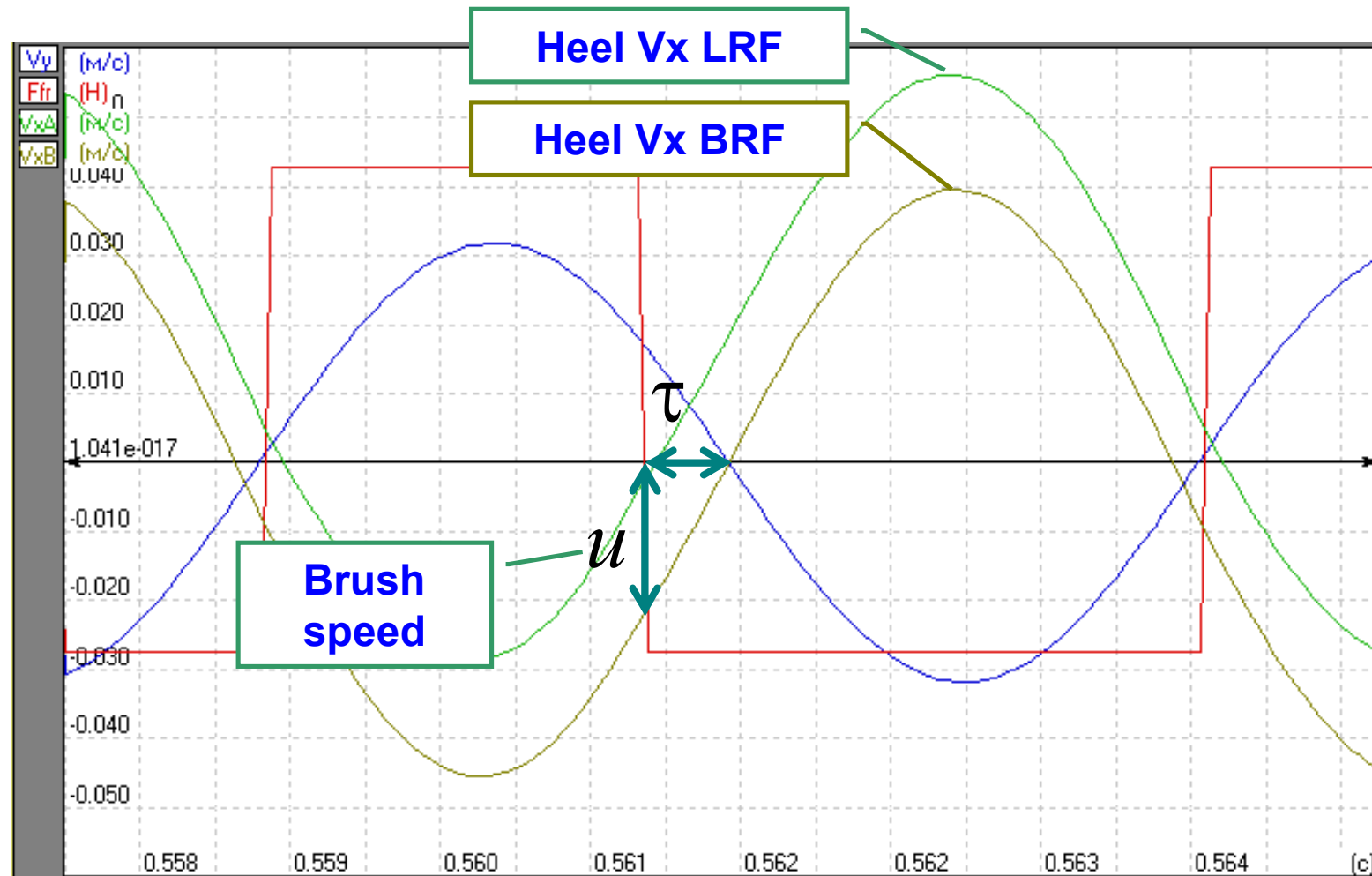


$$F_+ T_+ = F_- T_-$$

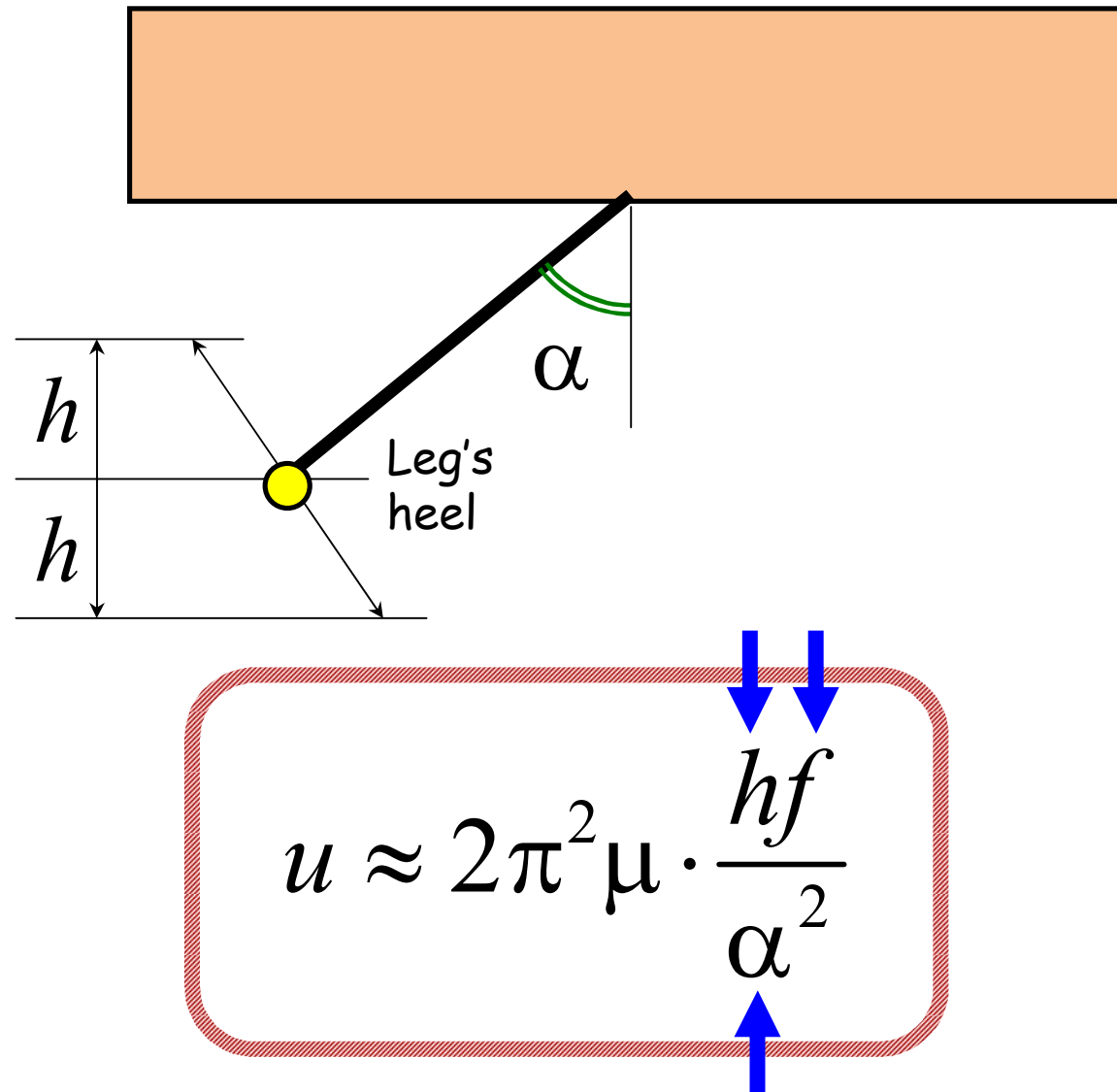


$$\tau = \frac{T}{2} \cdot \frac{F_+ - F_-}{F_+ + F_-} = \frac{T}{2} \cdot \mu \operatorname{ctg} \alpha$$



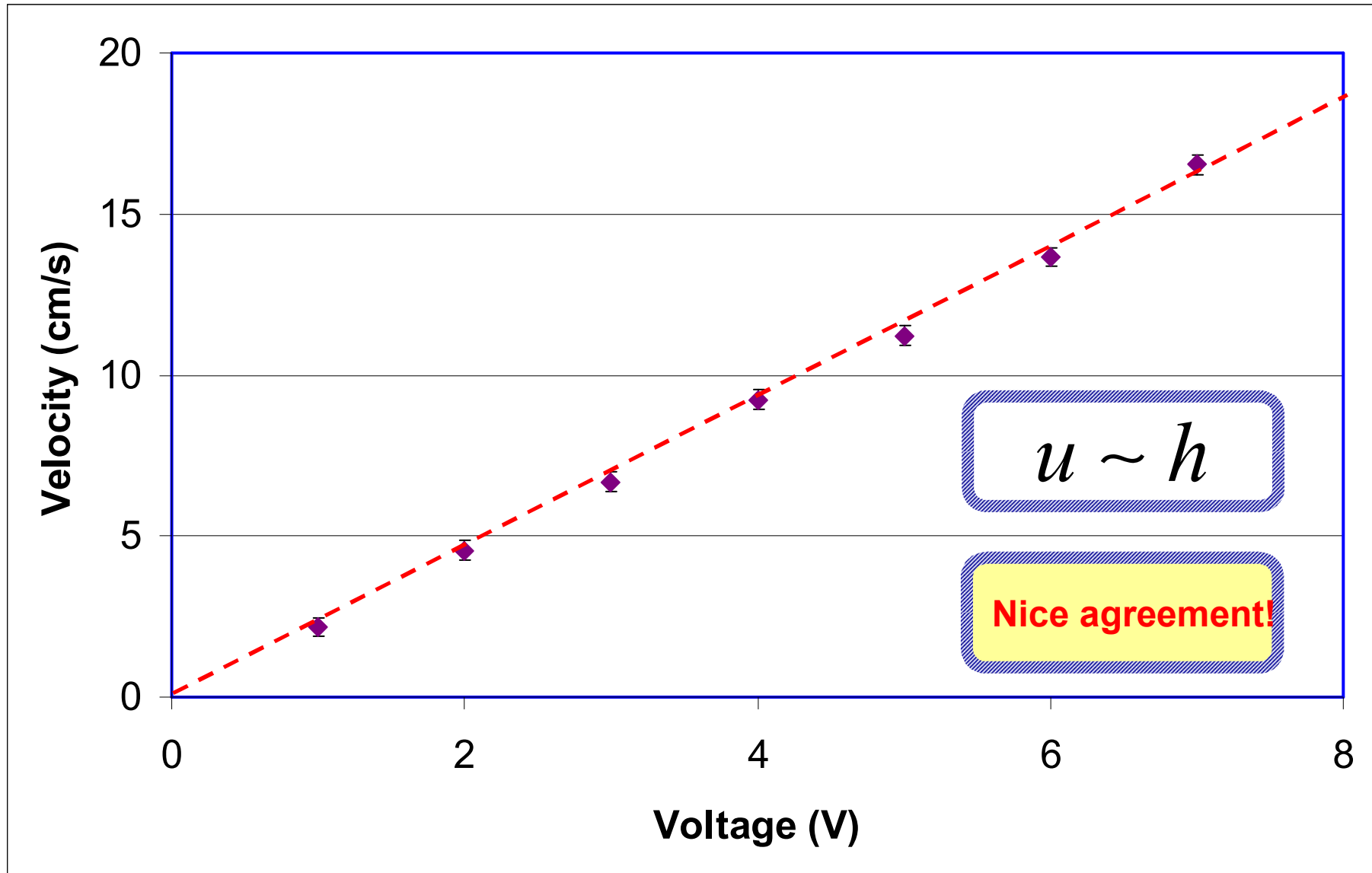


$$u = h\omega \cdot \sin(\omega\tau) \cdot \text{ctg} \alpha = h\omega \cdot \sin(\pi\mu \text{ctg} \alpha) \cdot \text{ctg} \alpha$$



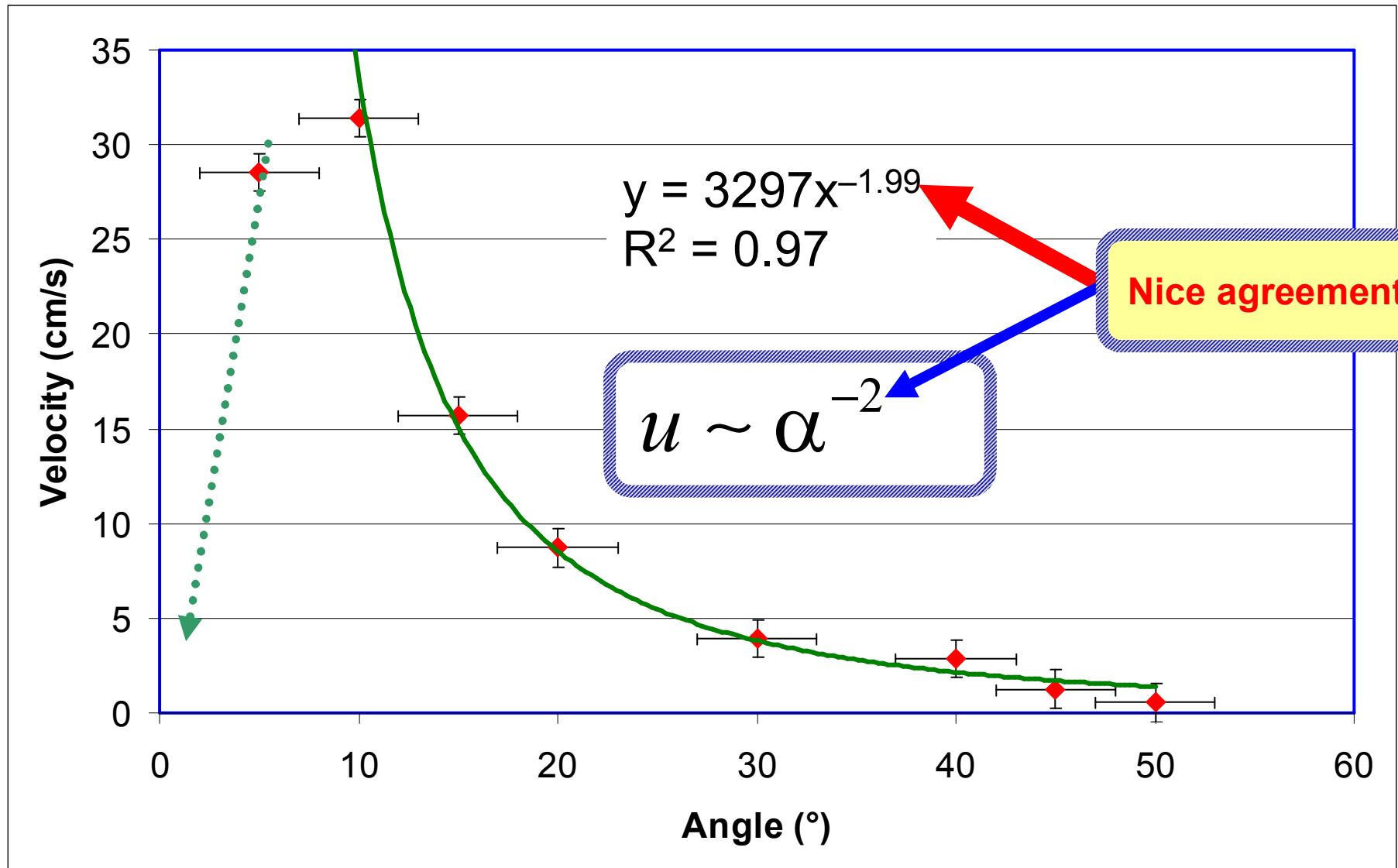
Experiment

Velocity vs. amplitude (voltage)



Velocity vs. angle of bristles

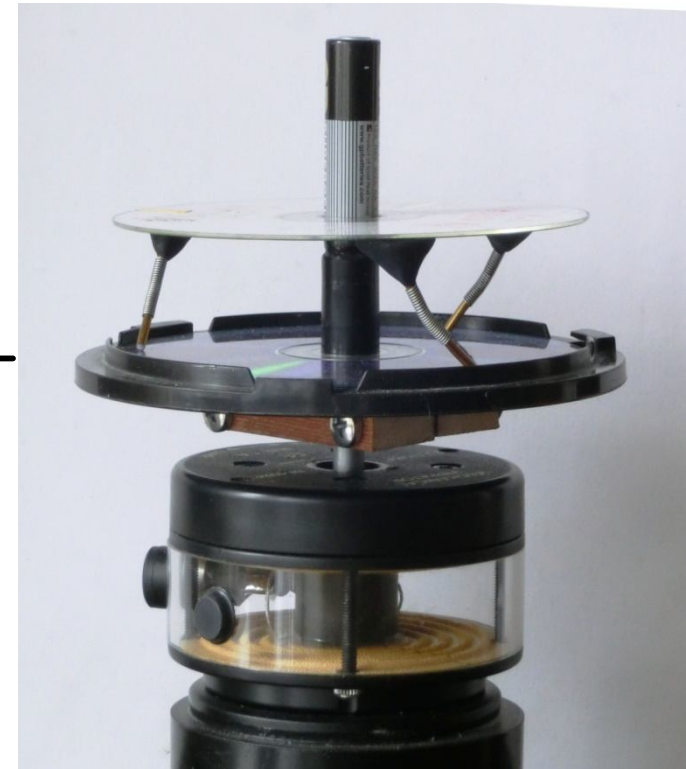
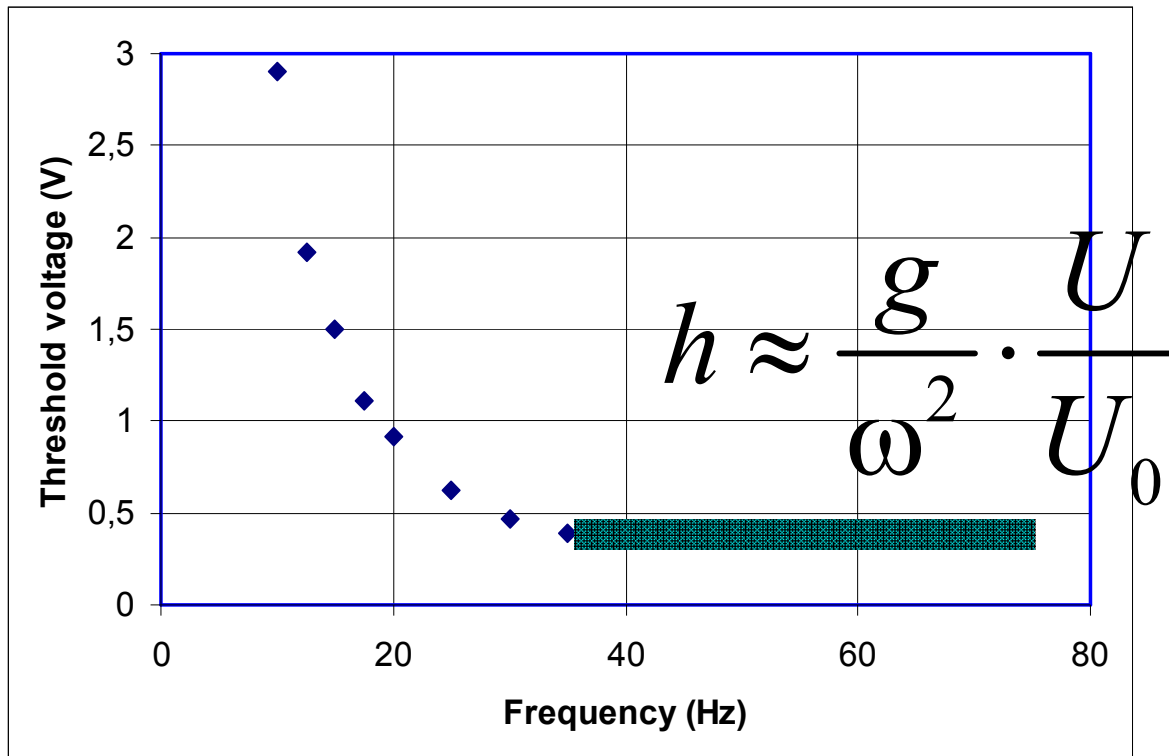
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Vibrator frequency response

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$$h\omega^2 = g$$

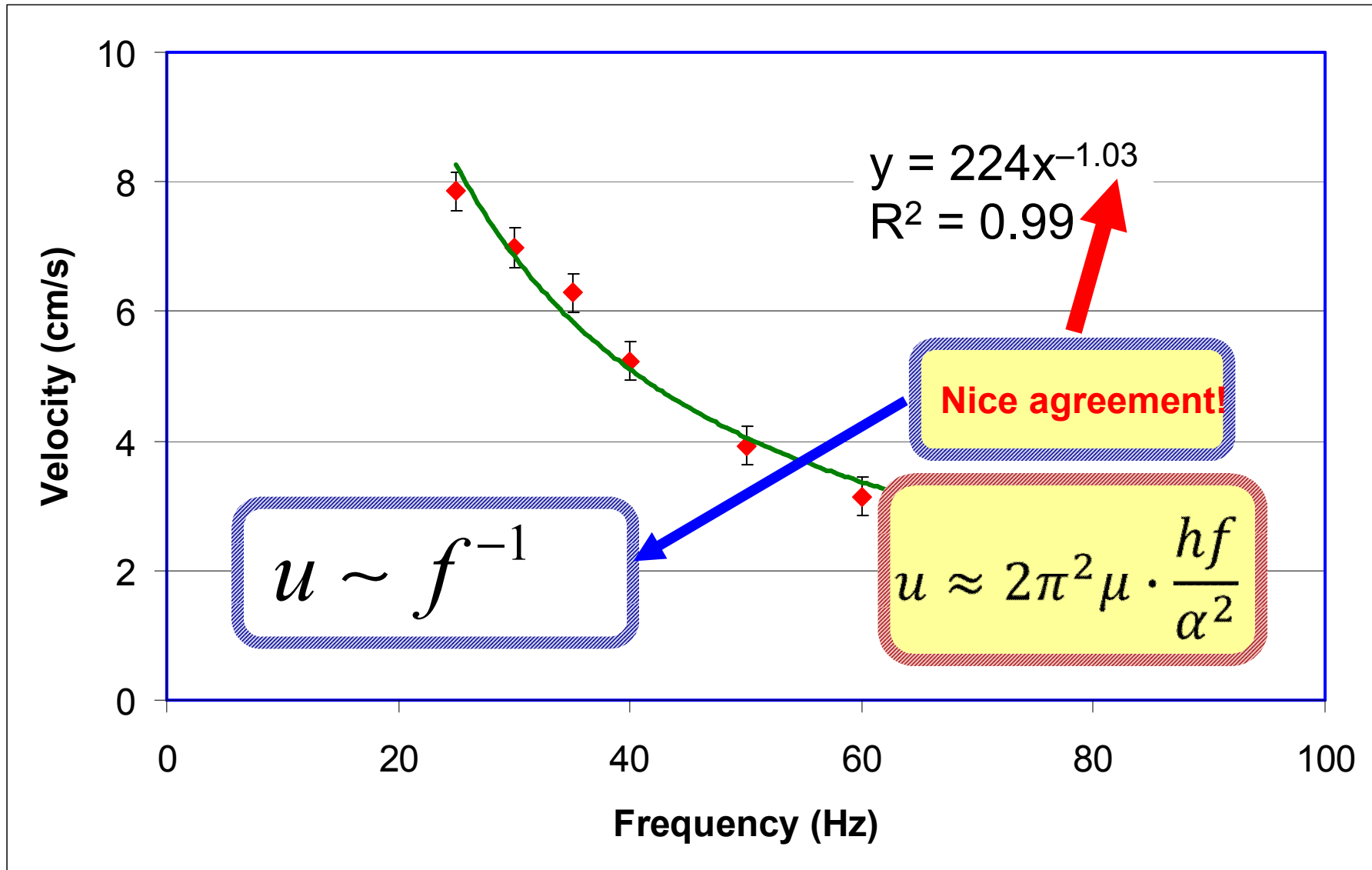


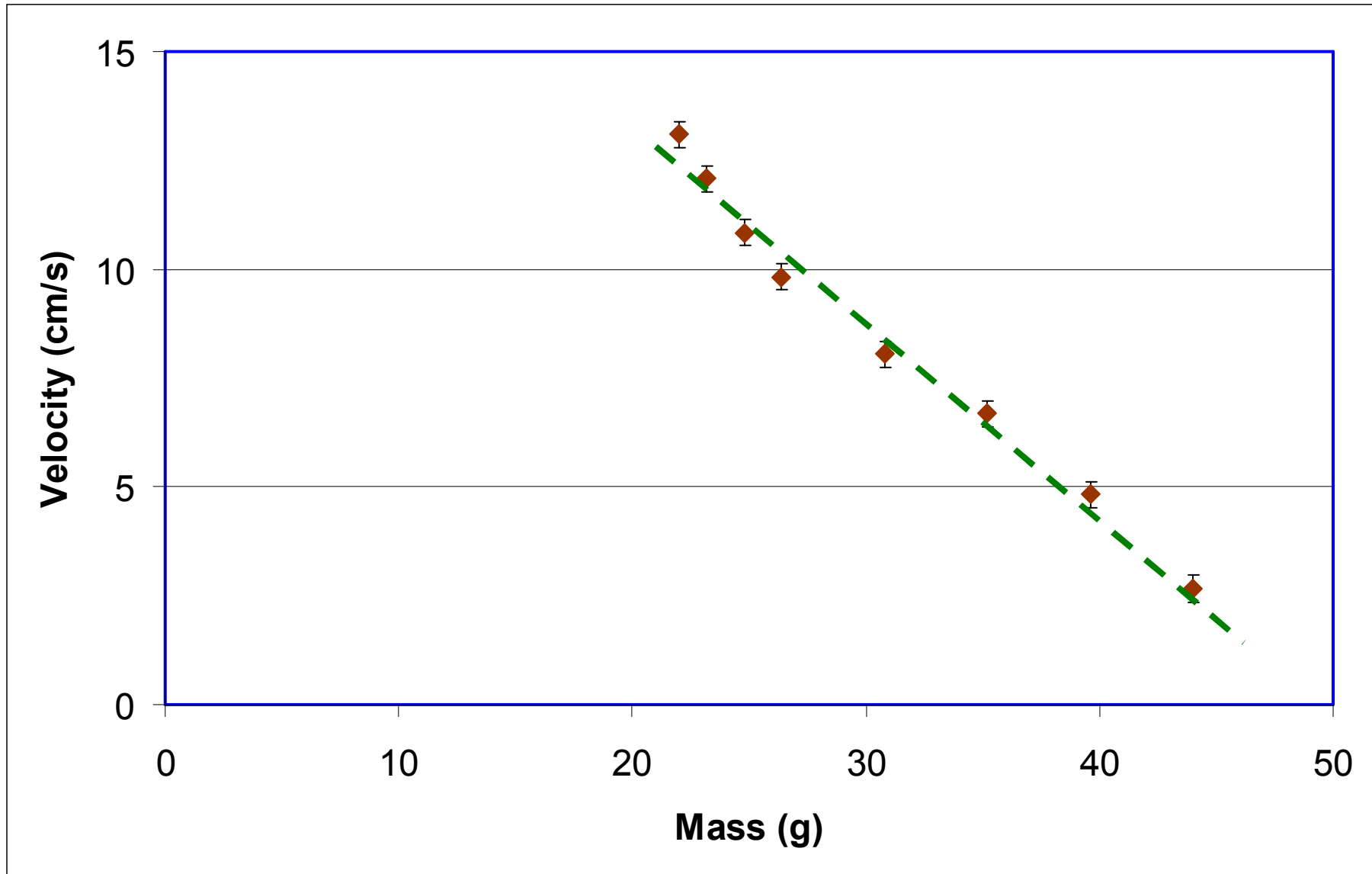
$$U = \text{const} \quad \Rightarrow \quad h \sim f^{-2}$$

$$u \sim hf \sim f^{-1}$$

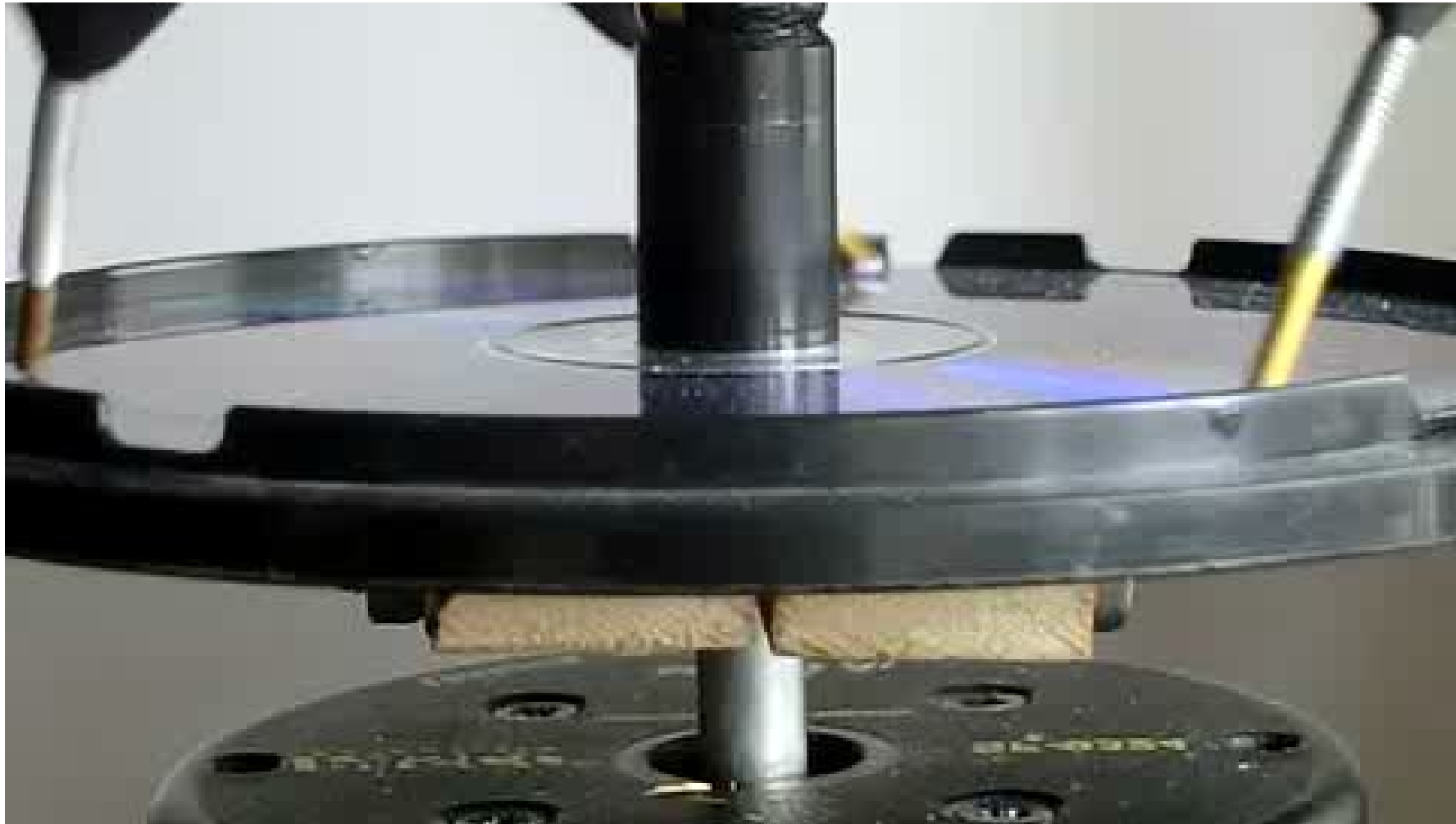
Velocity vs. frequency

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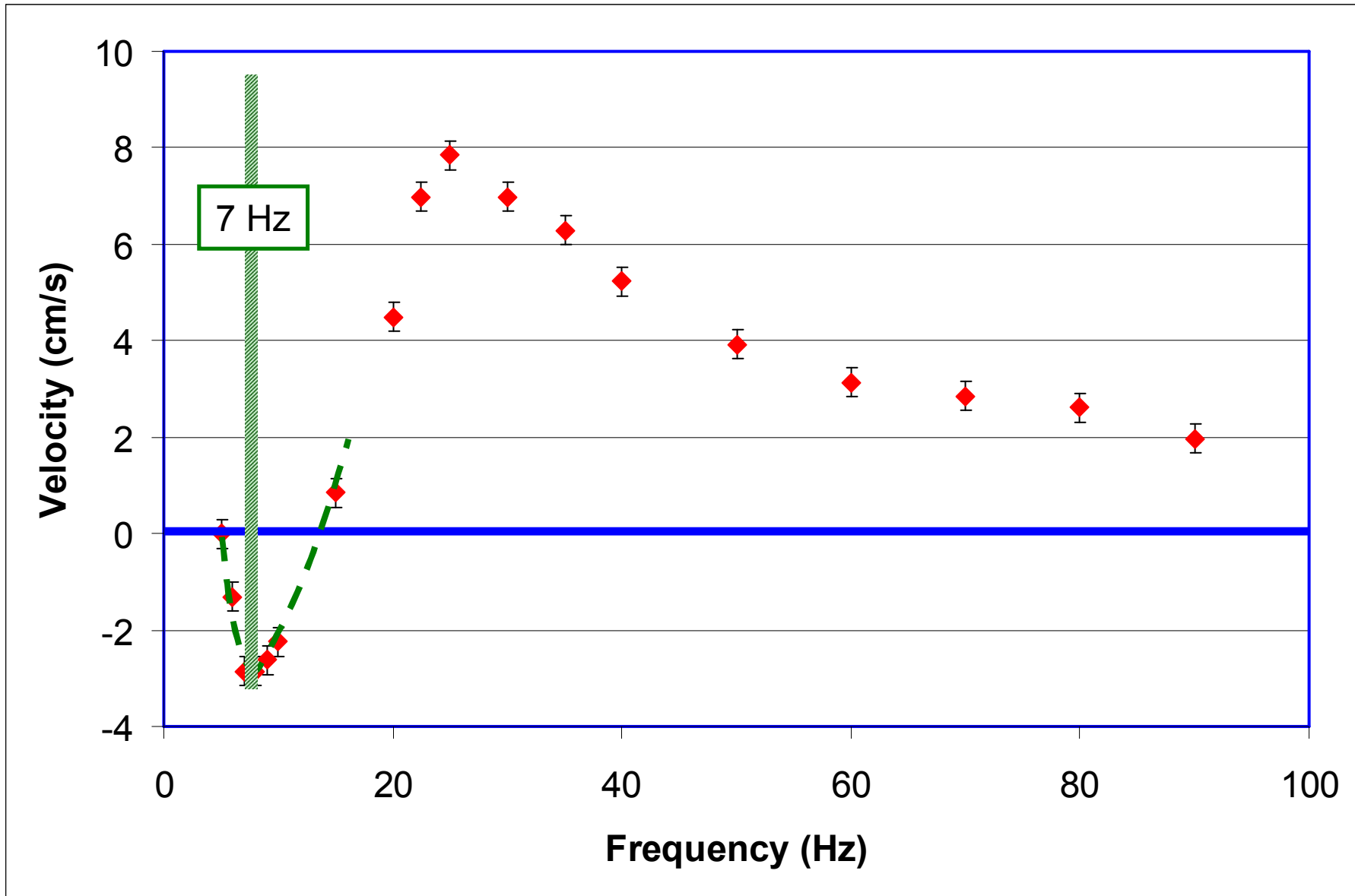


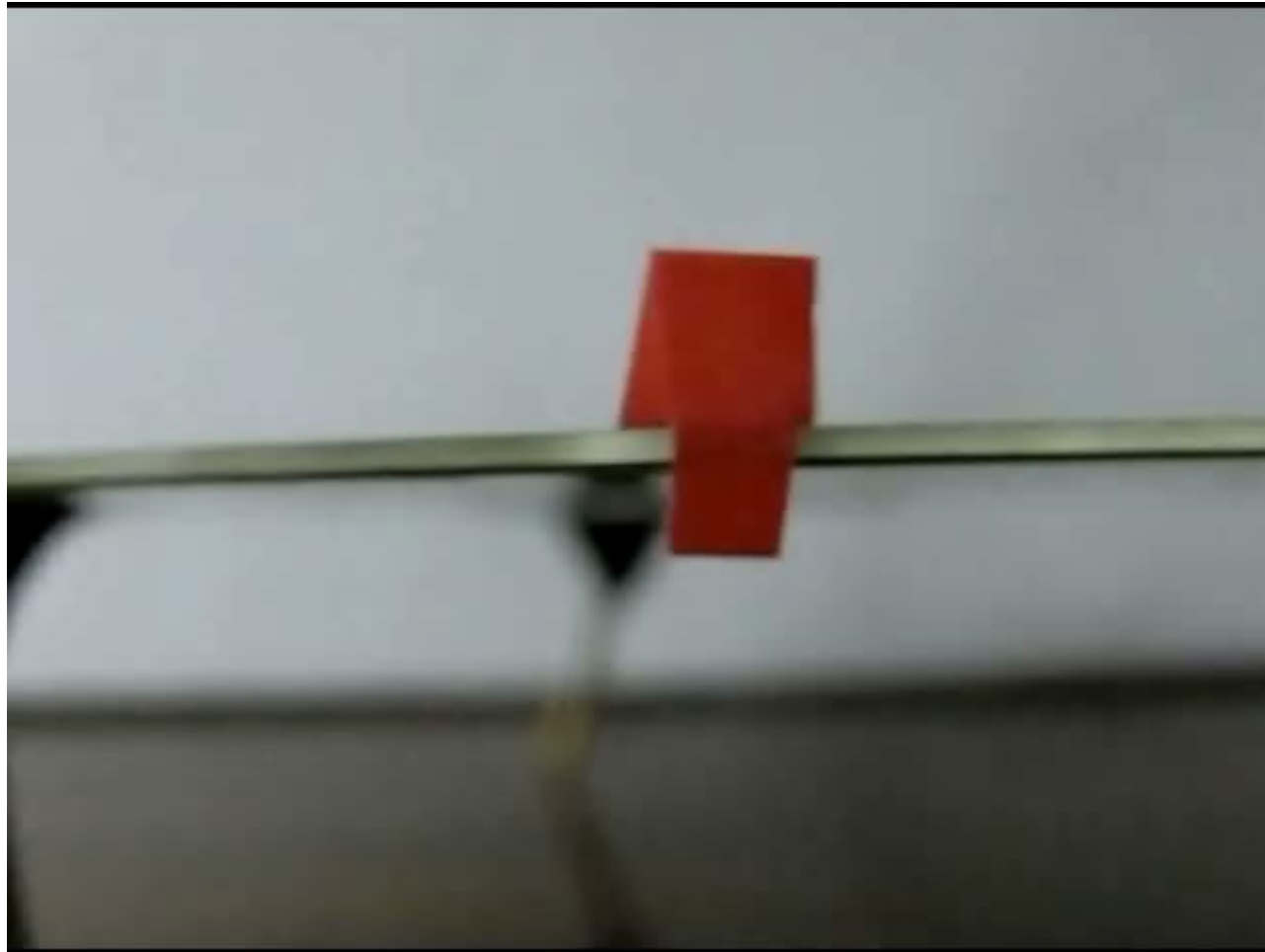


Backward motion



Frequency 7 Hz



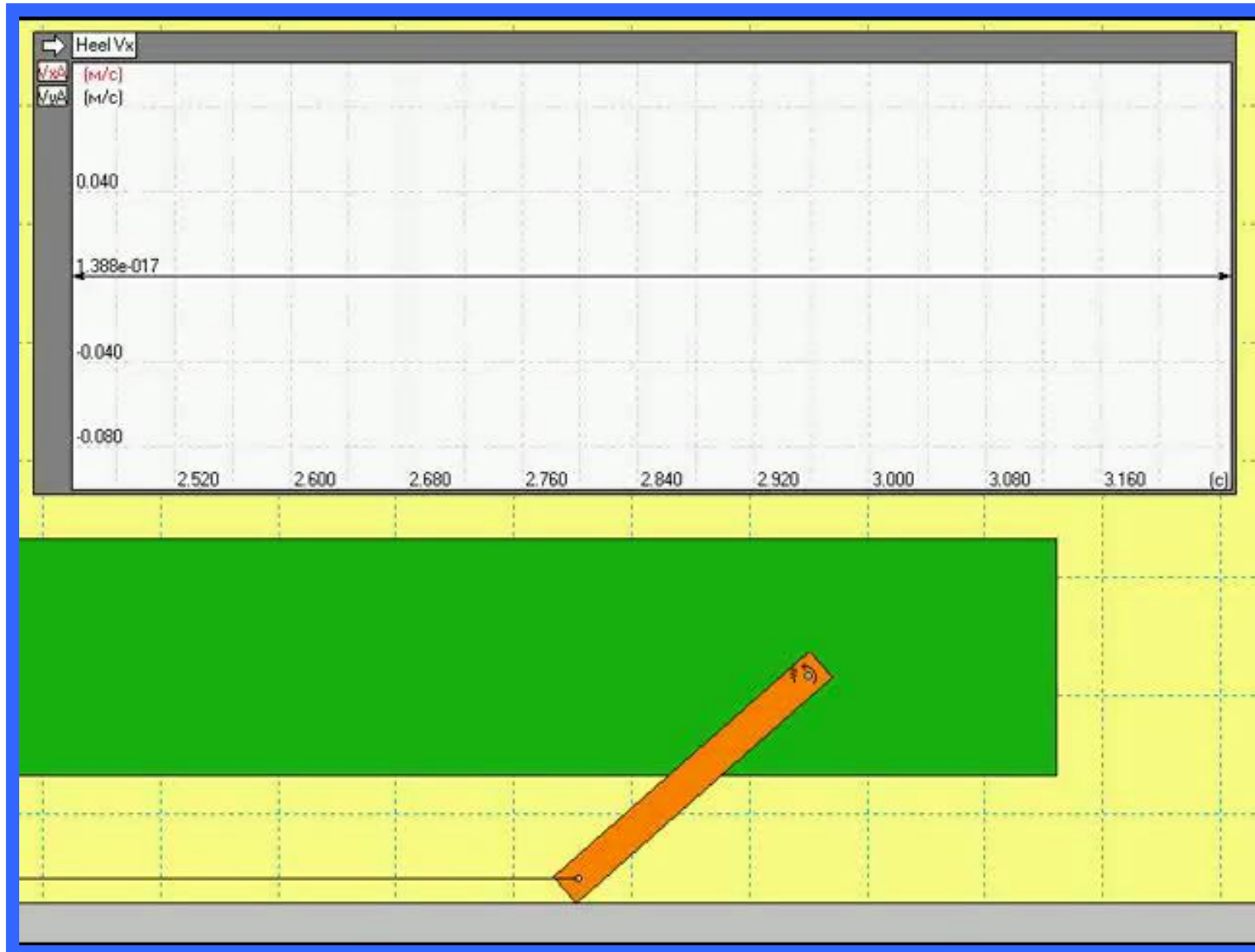


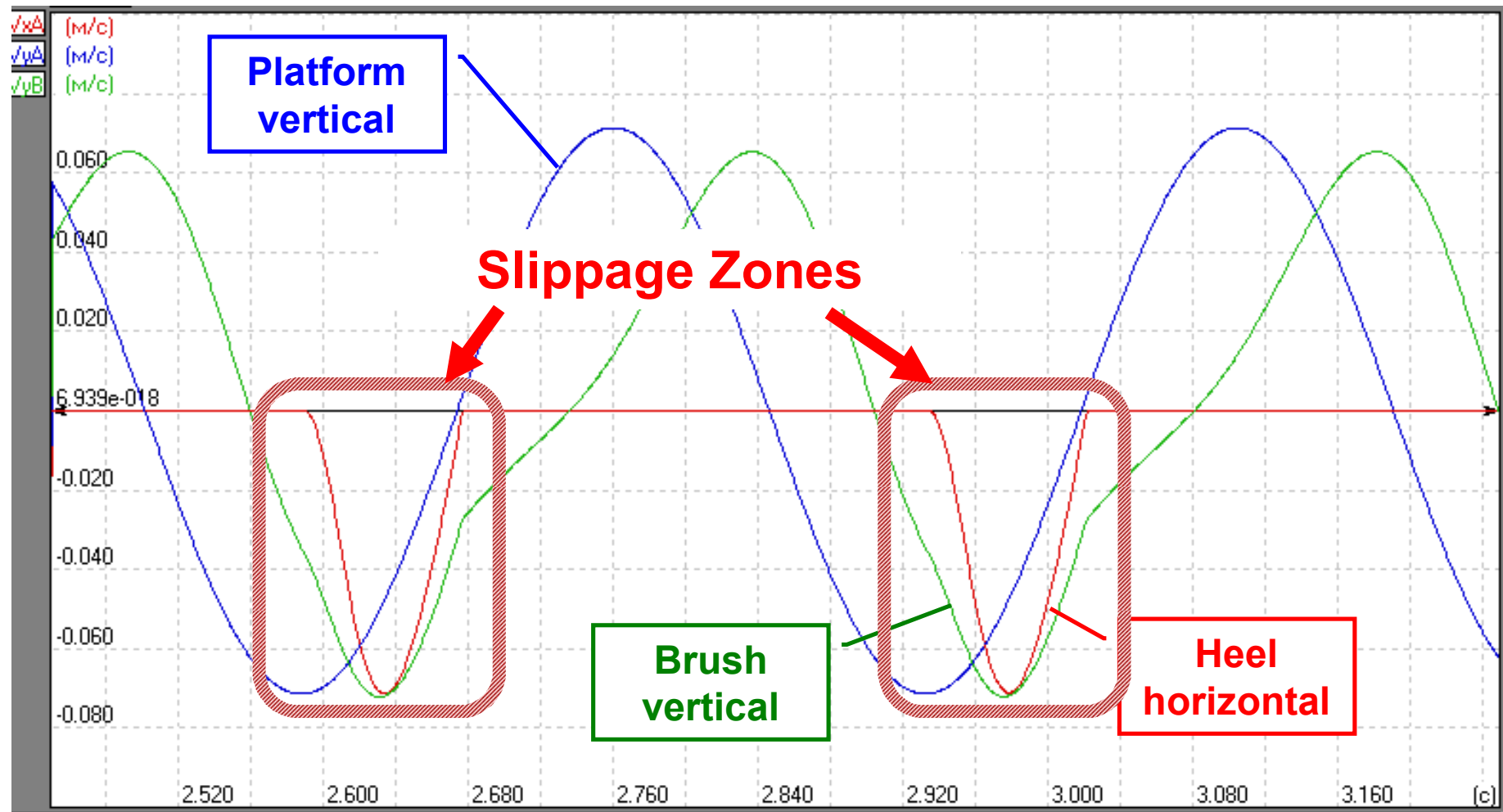
Frequency 7 Hz

Bristles' Behavior

Periodic heel slippage

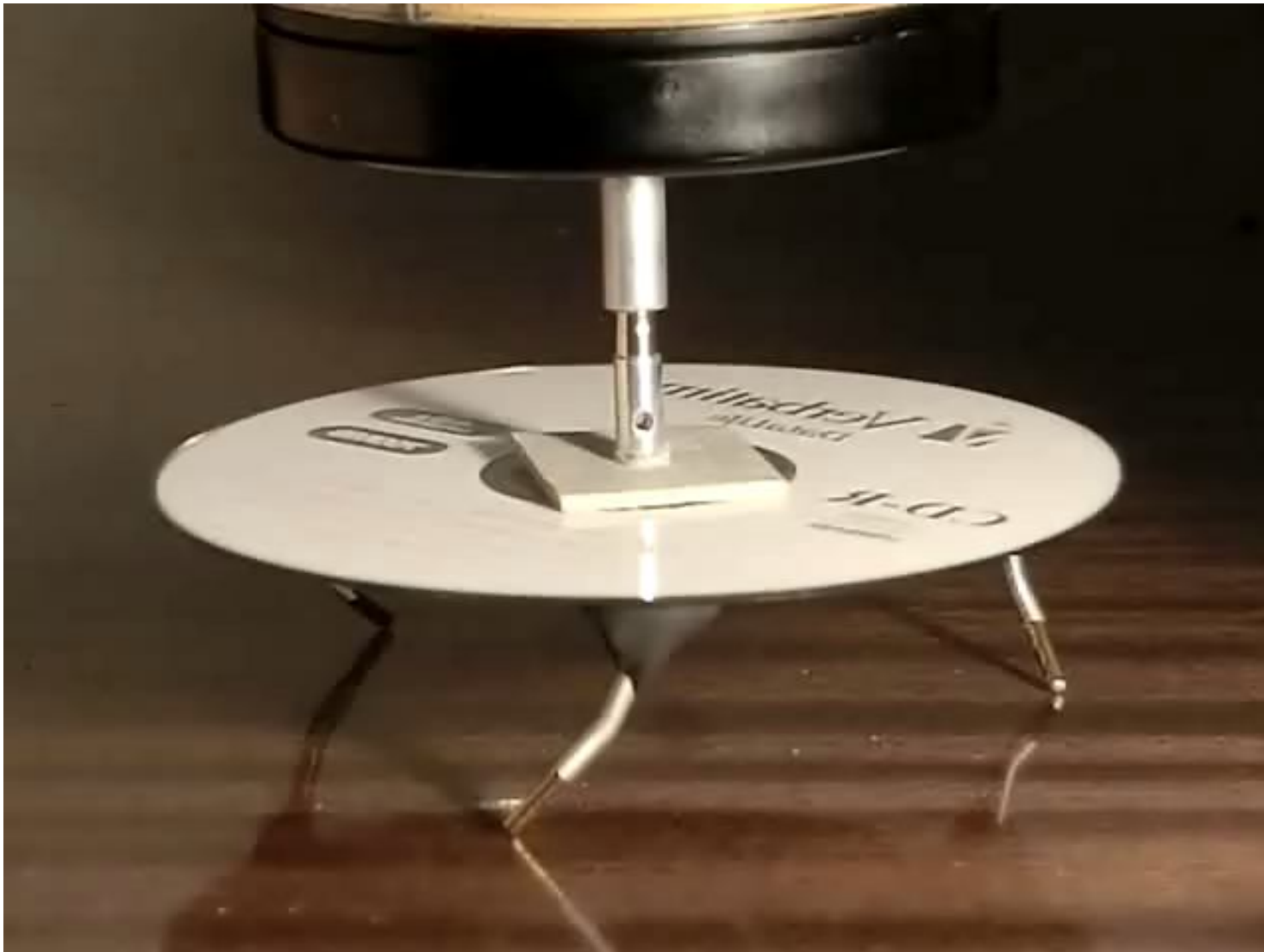
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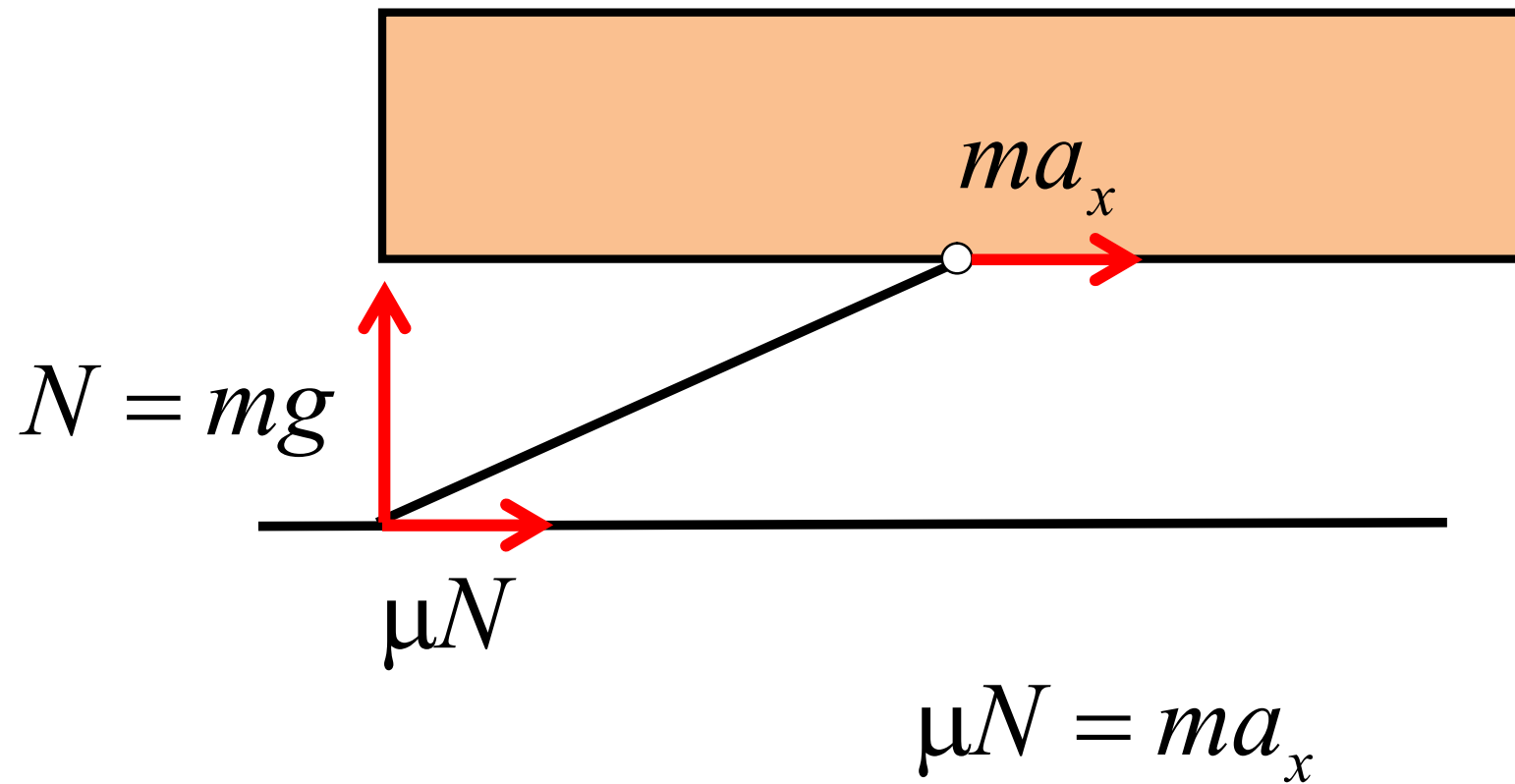


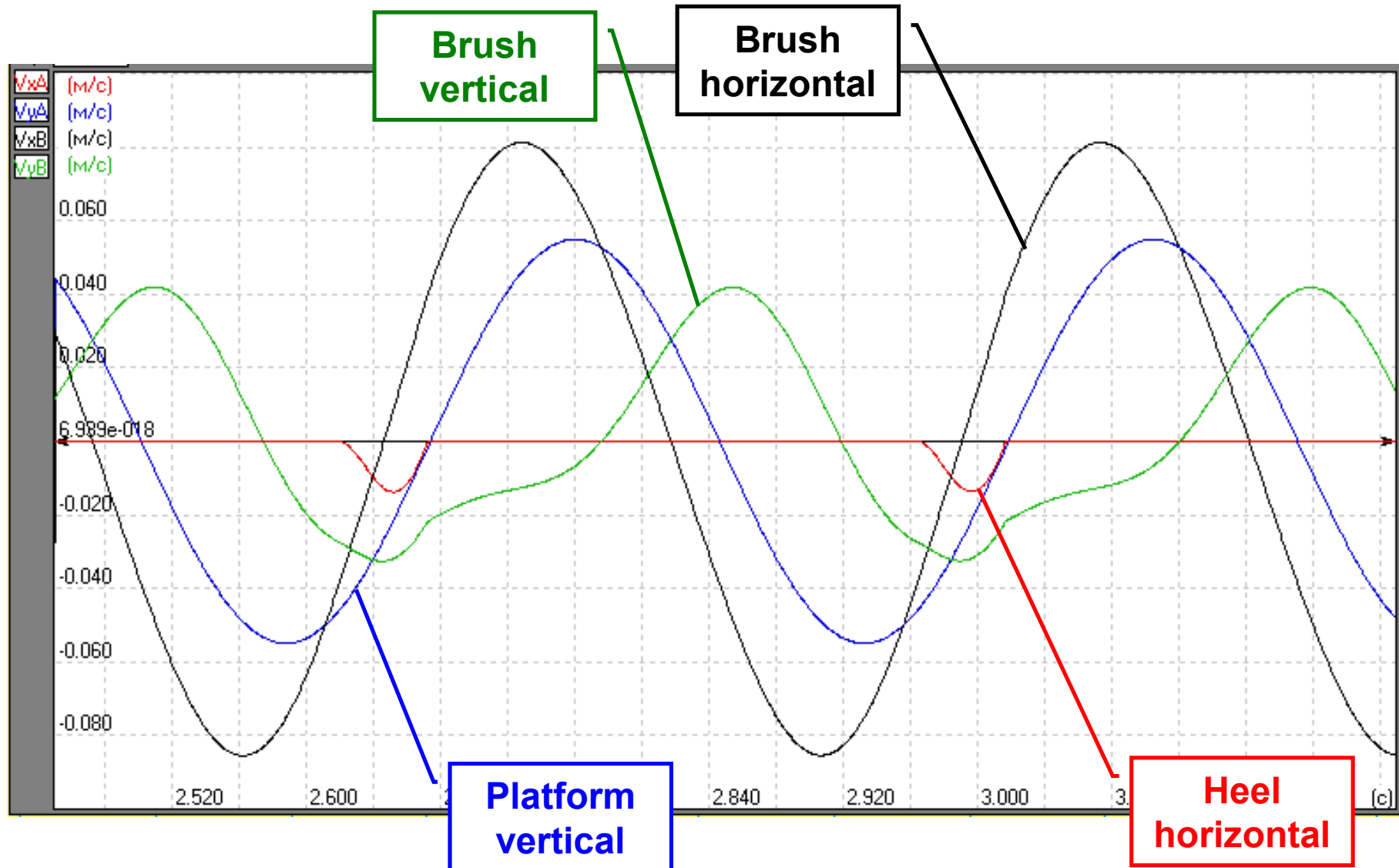


Surface's role

“...may start moving when placed on
a vibrating horizontal surface...”







Summary

Main results

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Experimental setup

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Brush

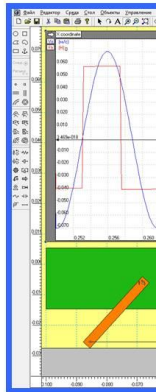
IP simulation

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Theoretical prediction

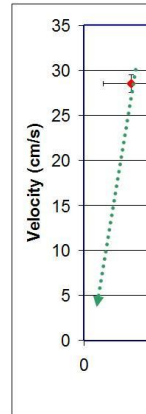
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Mechanical vibrator



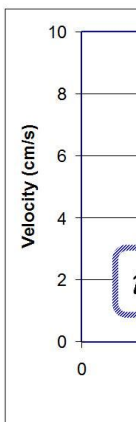
Velocity vs. angle of bristles

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Velocity vs. frequency

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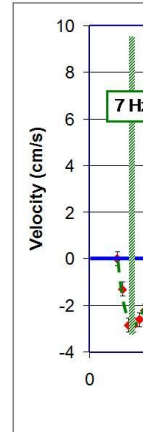
Backward motion (240 fps)

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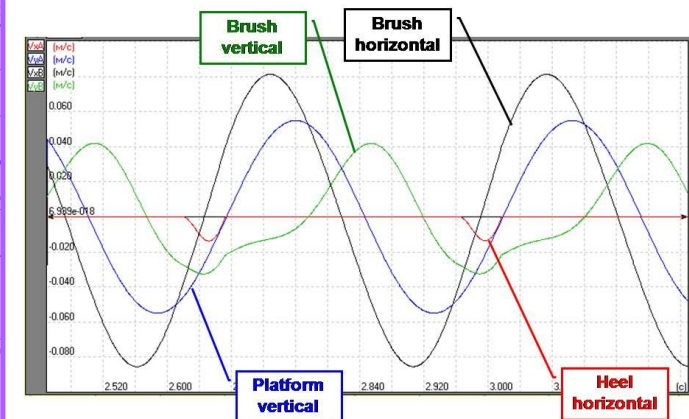
Velocity vs. frequency

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Brush and heel velocities

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**Thank you for
your attention!**